

Semantic guidance for unbounded symbolic reachability

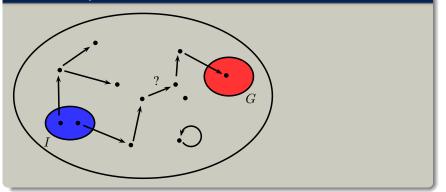
Martin Suda

Max Planck Institute für Informatik

VTSA 2012

The algorithm

Transition system



Reachability

Does there exist a finite path from an *I*-state to a *G*-state?

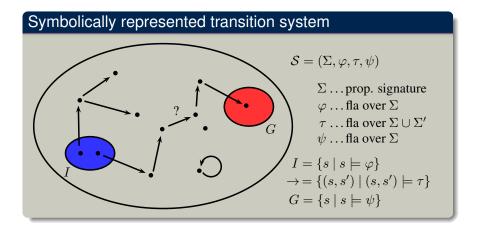
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Research

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The algorithm



Reachability

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Research

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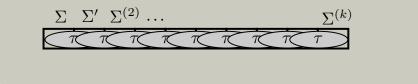


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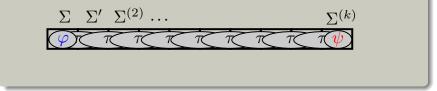


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Bounded model checking

Iterate the above for increasing values of k = 0, 1, 2, ...

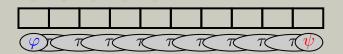
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- If one of them is SAT, we have an answer!
- But how do we know when to terminate in the other case?



We need more control over what's happening inside the solver

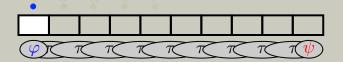
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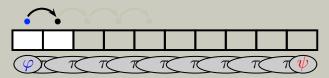
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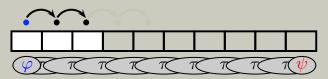


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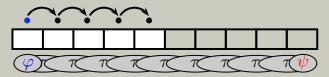
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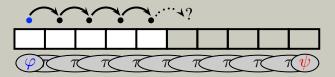
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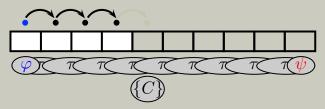
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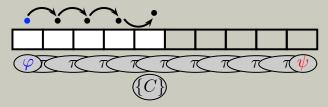
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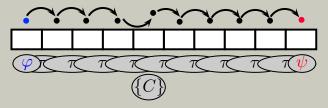
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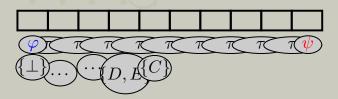
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• or discover inconsistency in a form of the empty clause \perp .

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- Empty clause depending only on φ: there is no path of length k starting in a φ-state.
- Empty clause depending only on ψ: there is no path of length k ending in a ψ-state.

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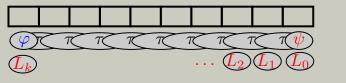
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Empty clause depending on neither: there is no path of lenght k.



Defining layers

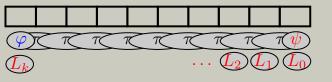
Let L_i be the set of clauses that *depend* on ψ and were inserted *j* steps before the goal formula ψ .





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Properties of layers

• $(L_i)' \wedge \tau \models L_{i+1}$ (The way they get derived.)

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• $L_i \land \varphi \models \bot$ (That's how it ended when k = i.)

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• Once $L_i = L_i$ for $i \neq j$, the whole instance is UNSAT. (Cut and paste argmument over the proof.)



Summary of the method

- SAT-solver builds a model path for left to right
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Related work

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Thank you for attention

Comments? Questions? Suggestions?



