

Software Model Checking with Ultimate

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July 3rd & 5th, 2019

- 1980: Emerson & Clarke: Explicit state model-checking.

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- 2001: Ball, Majumdar, Millstein & Rajamani: Predicate Abstraction
- 2009: Heizmann, H. & Podelski: Trace Abstraction.



Ultimate – a software model-checker

<https://ultimate.informatik.uni-freiburg.de/>

- Push button verification
- Input: C program
- Output: Correct (plus invariants) or Incorrect (plus counter-example)



Jürgen Christ



Daniel Dietsch



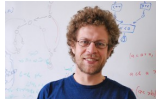
Marius Greitschus



Mathias Heizmann



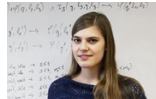
Jochen Hoenicke



Alexander Nutz



Martin Schäf



Tanja Schindler

... and 36 more contributors.

You can contribute too:

<https://github.com/ultimate-pa/ultimate>



- **ULTIMATE AUTOMIZER:** Trace Abstraction for Safety
- **ULTIMATE BÜCHI AUTOMIZER:** Trace Abstraction for Termination
- **ULTIMATE KOJAK:** Predicate Abstraction
- **ULTIMATE TAIPAN:** Abstract Interpretation + Trace Abstraction



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- **ULTIMATE TAIPAN:** Abstract Interpretation + Trace Abstraction
- **ULTIMATE LTL AUTOMIZER:** Checking LTL properties
- **ULTIMATE PETRI AUTOMIZER:** Concurrent Programs

Demo

```
int f(int i) {
  int j = 0;
  if (i > 0) {
    int *p = malloc(sizeof(int)); // allocate pointer
    *p = 0;
    while (i > 0) {
      *p += i; // use pointer
      if (i == 1) { // if in the last iteration:
        j = *p;
        free(p); // free the pointer
      }
      i--; // decrement i
    }
  }
  return j;
}
```

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    }
  }
  return j;
}
```

- Is every allocated memory eventually freed?
- Is every pointer dereference valid?

```
int f(int i) {
  int j = 0;
  if (i > 0) {
    int *p = malloc(sizeof(int));    // allocate pointer

    *p = 0;
    while (i > 0) {
      *p += i;                       // use pointer

      if (i == 1) {                 // if in the last iteration:
        j = *p;
        free(p);                   // free the pointer
      }

      i--;                           // decrement i
    }
  }

  return j;
}
```

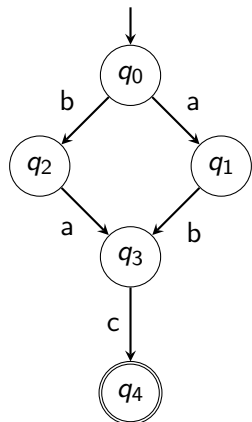
```
int f(int i) {
  int j = 0;
  if (i > 0) {
    int *p = malloc(sizeof(int)); // allocate pointer
    palloc = 1;
    *p = 0;
    while (i > 0) {
      *p += i; // use pointer
      assert(palloc == 1);
      if (i == 1) { // if in the last iteration:
        j = *p;
        free(p); // free the pointer
        palloc = 0;
      }
      i--; // decrement i
    }
  }
  assert(palloc == 0);
  return j;
}
```

```
int f(int i) {  
    ...  
    if (i > 0) {  
        ... // allocate pointer  
        palloc = 1;  
        ...  
        while (i > 0) {  
            ... // use pointer  
            assert(palloc == 1);  
            if (i == 1) {  
                ... // if in the last iteration:  
                ... // free the pointer  
                palloc = 0;  
            }  
            i--; // decrement i  
        }  
    }  
    assert(palloc == 0);  
}
```

Trace Abstraction

A finite automaton $\mathcal{A} = (\Sigma, Q, \rightarrow, q_0, F)$ consists of

- Σ : a finite alphabet
- Q : a finite set of locations
- $\rightarrow \subseteq Q \times \Sigma \times Q$: a transition relation
- $q_0 \in Q$: the initial location
- $F \subseteq Q$: the accepting locations



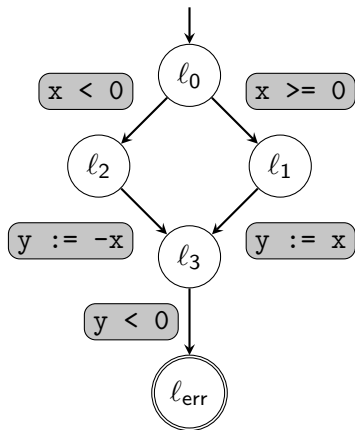
Finite Automaton and Program Automaton

A **finite automaton** $\mathcal{A} = (\Sigma, Q, \rightarrow, q_0, F)$ consists of

- Σ : a finite alphabet
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- $\rightarrow \subseteq Q \times \Sigma \times Q$: a transition relation
- $q_0 \in Q$: the initial location
- $F \subseteq Q$: the accepting locations

A **program automaton** is a finite automaton:

- Σ is the set of statements occurring in the program
- Q are the program locations
- \rightarrow defines the control flow graph
- $l_0 \in Q$: the initial location
- F is the set containing the error location l_{err}



A word over Σ is called a **trace**.

The language of the program automaton is the set of **error traces**.

- Σ is the set of statements occurring in the program.

Only two kinds of statements:

- `x := expr` assigns the value of `expr` to variable `x`
- `cond` checks if the condition `cond` is true, blocks otherwise.

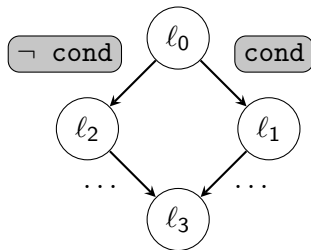
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Only two kinds of statements:

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Translation of if statement

```
l0: if (cond)
l1:   ...
      else
l2:   ...
l3:
```



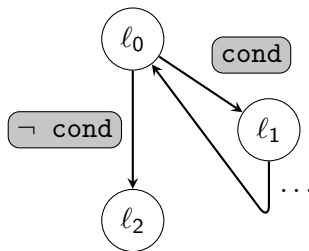
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Only two kinds of statements:

- `x := expr` assigns the value of `expr` to variable `x`
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Translation of while statement

```
l0: while (cond)
l1:   ...
l2:
```



- Σ is the set of statements occurring in the program.

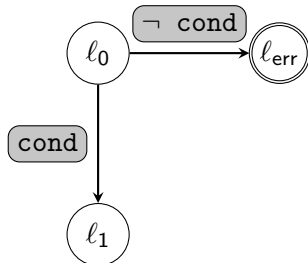
Only two kinds of statements:

- `x := expr` assigns the value of `expr` to variable `x`
- `cond` checks if the condition `cond` is true, blocks otherwise.

Translation of assert statement

l_0 : `assert(cond)`

l_1 :



- Σ is the set of statements occurring in the program.

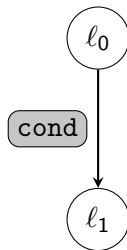
Only two kinds of statements:

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- `cond` checks if the condition `cond` is true, blocks otherwise.

Translation of assume statement

l_0 : `assume(cond)`

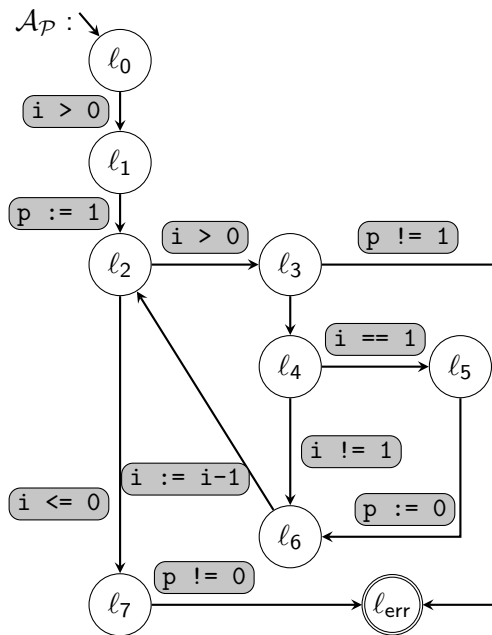
l_1 :



```
l0:  assume i > 0
l1:  p := 1
l2:  while (i > 0) {
l3:    assert p == 1
l4:    if (i == 1)
l5:      p := 0
l6:    i := i - 1
      }
l7:  assert p == 0
```

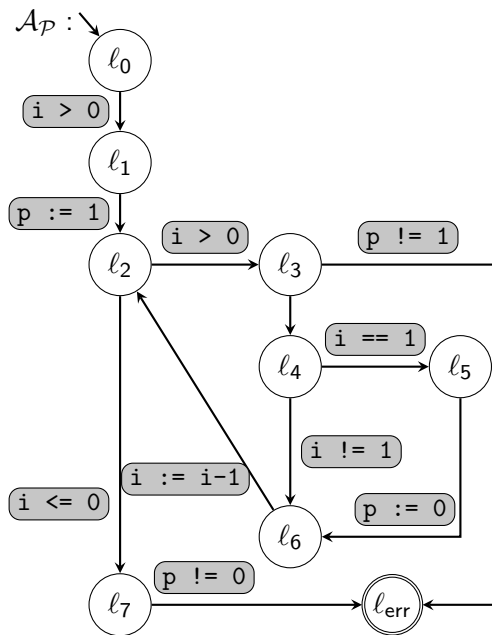

Example – Program and Program Automaton

```
l0: assume i > 0
l1: p := 1
l2: while (i > 0) {
l3:   assert p == 1
l4:   if (i == 1)
l5:     p := 0
l6:     i := i - 1
      }
l7: assert p == 0
```



Example – Program and Program Automaton

$$\Sigma = \left\{ \begin{array}{l} i > 0, i \leq 0, i := i-1, \\ i == 1, i \neq 1, p := 1, \\ p \neq 0, p \neq 1, p := 0 \end{array} \right\}$$



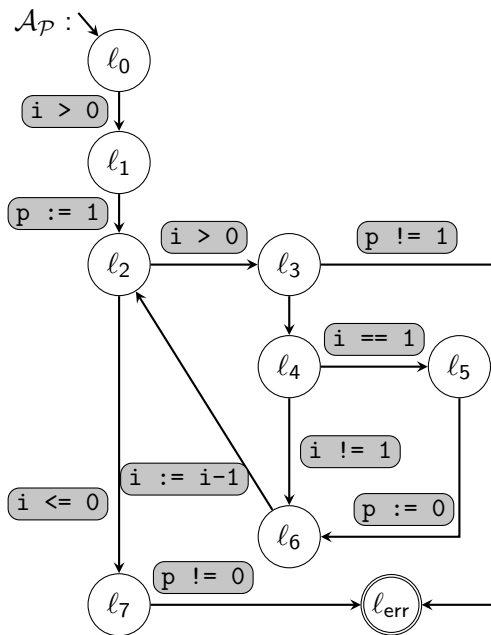
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Trace

Word over the alphabet of statements.

Example:

$$\pi = i == 1 \ i := i-1 \ i == 1$$



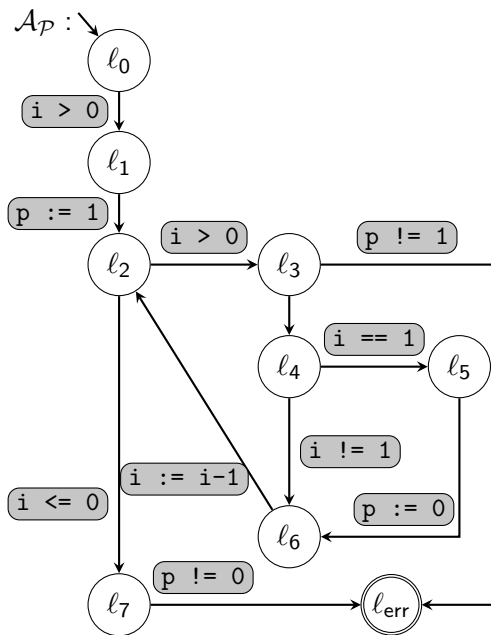
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Error Trace

Word accepted by the program automaton.

Example:

$$\pi = i > 0 \ p := 1 \ i > 0 \ p \neq 1$$



$$\Sigma = \left\{ \begin{array}{l} i > 0, i \leq 0, i := i-1, \\ i == 1, i != 1, p := 1, \\ p != 0, p != 1, p := 0 \end{array} \right\}$$

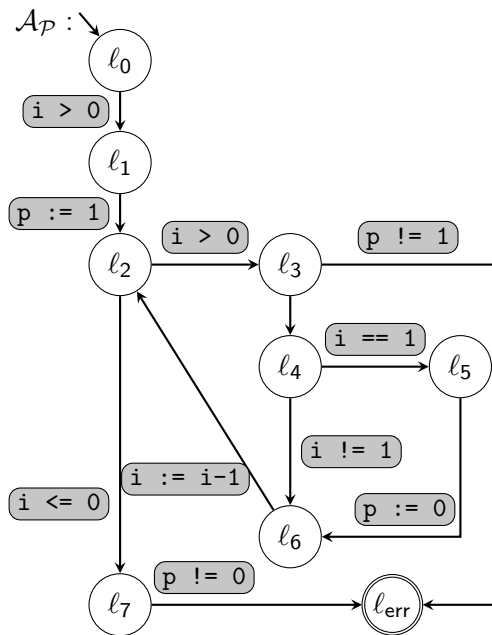
Error Trace

Word accepted by the program automaton.

Example:

$$\pi = i > 0 \ p := 1 \ i > 0 \ p != 1$$

Does π refute correctness of \mathcal{P} ?



A **valuation** $\nu : \text{Var} \rightarrow \text{Value}$ maps variables to some value domain.

$$\nu_0 = \left\{ \begin{array}{l} i \mapsto 1 \\ p \mapsto 0 \end{array} \right\}$$

Valuation are extended to expressions in a natural way.

$$\nu_0(i - 1) = \nu_0(i) - 1 = 0$$

The **update of a valuation** $\nu[x := c]$ is a copy of valuation ν that maps x to c .

$$\nu_0[i := 0] = \left\{ \begin{array}{l} i \mapsto 0 \\ p \mapsto 0 \end{array} \right\}$$

The meaning of the statements is given by a transition system.

- Valuations are the states of the transition system.
- Transitions are labelled with statements.

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$$\nu \xrightarrow{x := \text{expr}} \nu[x := \nu(\text{expr})]$$

$$\nu \xrightarrow{\text{cond}} \nu \quad \text{iff} \quad \nu(\text{cond}) = \mathbf{true}.$$

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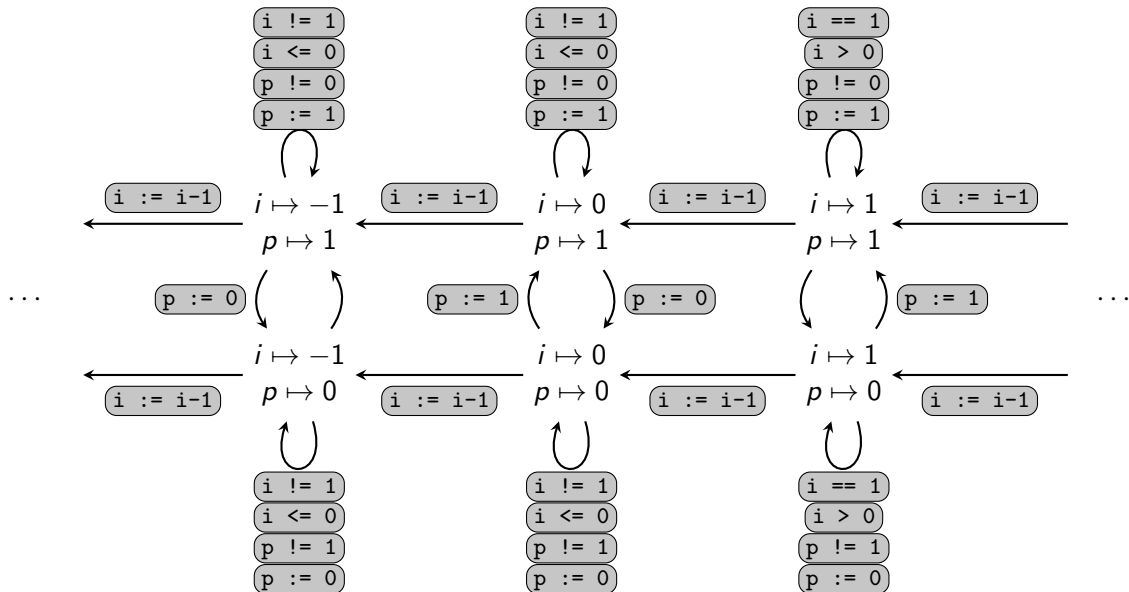
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Example: $\pi = \boxed{i > 0} \boxed{p := 1} \boxed{i > 0} \boxed{p \neq 1}$

$$\begin{array}{c}
 i \mapsto 1 \\
 p \mapsto 0
 \end{array}
 \xrightarrow{\boxed{i > 0}}
 \begin{array}{c}
 i \mapsto 1 \\
 p \mapsto 0
 \end{array}
 \xrightarrow{\boxed{p := 1}}
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 \end{array}
 \xrightarrow{\boxed{i > 0}}
 \begin{array}{c}
 i \mapsto 1 \\
 p \mapsto 1
 \end{array}
 \xrightarrow{\boxed{p \neq 1}}$$

The transition system is **infinite** and has infinitely many initial states.



Intuitively, there is no sequence of valuations for the trace:

$\pi = \boxed{i > 0} \boxed{p := 1} \boxed{i > 0} \boxed{p \neq 1}.$

How can we show this?

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SMT Solver!

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SMT Solver!

- SSA (Single Static Assignment): copy the variable each time it is assigned.

$\boxed{i_0 > 0} \boxed{p_1 := 1} \boxed{i_0 > 0} \boxed{p_1 \neq 1}$

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- SSA (Single Static Assignment): copy the variable each time it is assigned.

$$\boxed{i_0 > 0} \boxed{p_1 := 1} \boxed{i_0 > 0} \boxed{p_1 \neq 1}$$

- Replace `:=` by logical equality and conjunct all statements.

$$SSA(\pi) : i_0 > 0 \wedge p_1 = 1 \wedge i_0 > 0 \wedge p_1 \neq 1$$

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- Replace := by logical equality and conjunct all statements.

$$SSA(\pi) : i_0 > 0 \wedge p_1 = 1 \wedge i_0 > 0 \wedge p_1 \neq 1$$

- Ask SMT solver, if there is a solution for the formula:

unsat

SMT solvers are programs that decide satisfiability.

Ultimate uses z3, CVC4, mathsat and our own SMT solver SMTInterpol.

- Input a formula, for example:

$$i_0 > 0 \wedge p_1 = 1 \wedge i_1 = i_0 - 1 \wedge i_1 \leq 0$$

- Either sat (satisfiable) and optionally a model:

$$i_0 = 1, p_1 = 1, i_1 = 0$$

or unsat.

<https://ultimate.informatik.uni-freiburg.de/smtinterpol/>

```
(set-option :produce-models true)
(set-logic QF_LIA)
(declare-const i0 Int)
(declare-const p0 Int)
(declare-const i1 Int)
(declare-const p1 Int)

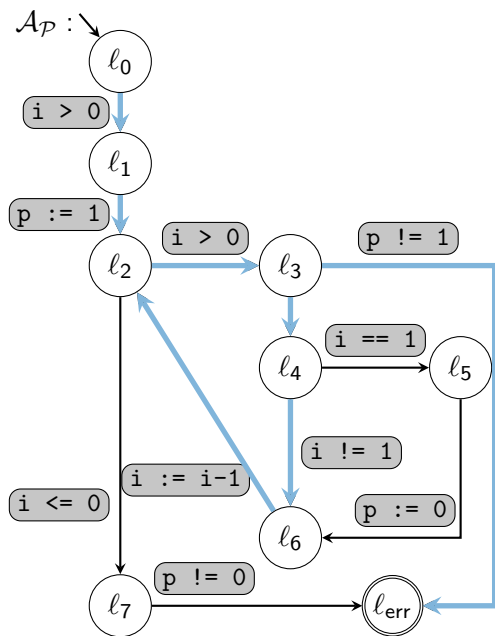
(assert (and (> i0 0)
            (= p1 1)
            (= i1 (- i0 1))
            (<= i1 0)))

(check-sat)
(get-model)
```

- Build program automaton.
- Collect error traces.
- For each error trace ask SMT solver.

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Problem: There are infinitely many error traces.



Some error traces:

`i > 0` `p := 1` `i > 0` `p != 1`

`i > 0` `p := 1`

`i > 0` `i != 1` `i := i-1`

`i > 0` `p != 1`

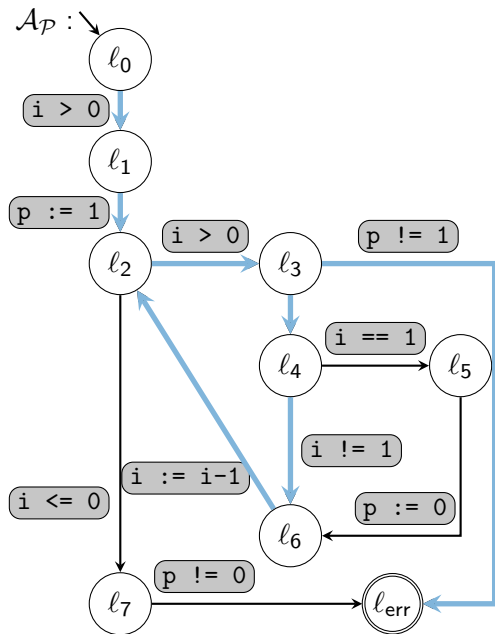
`i > 0` `p := 1`

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`i > 0` `p != 1`

⋮



Some error traces:

`i > 0` `p := 1` `i > 0` `p != 1`

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`i > 0` `p != 1`

`i > 0` `p := 1`

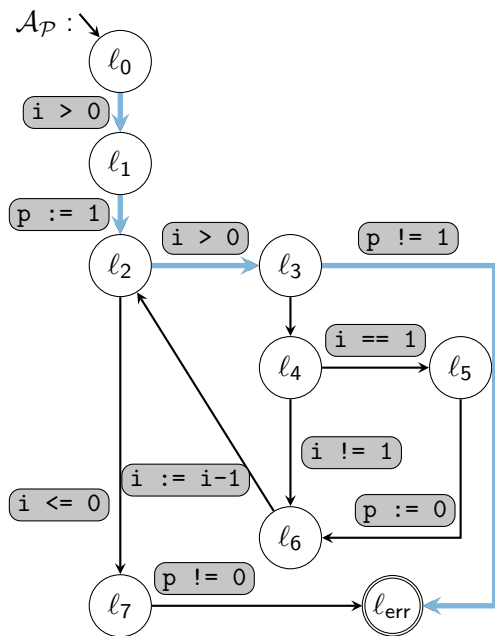
`i > 0` `i != 1` `i := i-1`

`i > 0` `i != 1` `i := i-1`

`i > 0` `p != 1`

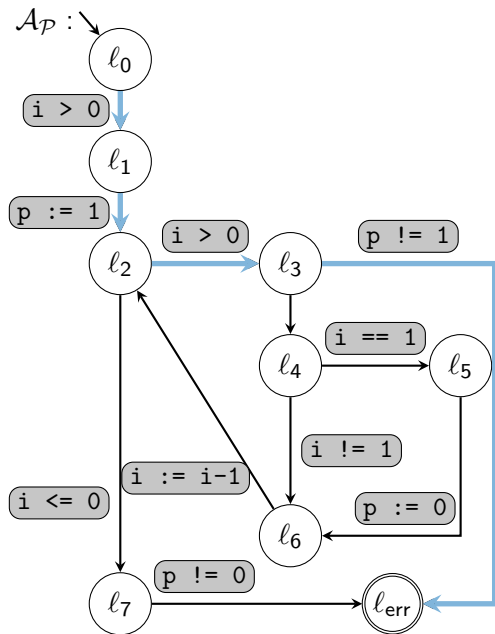
⋮

All infeasible for the same reason.



Observation

Every trace ... $p := 1$... $p != 1$... is infeasible, as long as there is no statement $p := 0$ in the middle

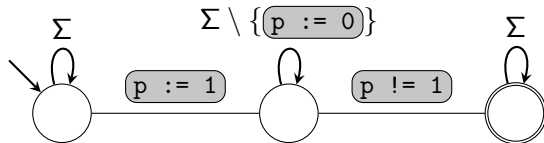


Observation

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Traces can be described by a finite automaton:

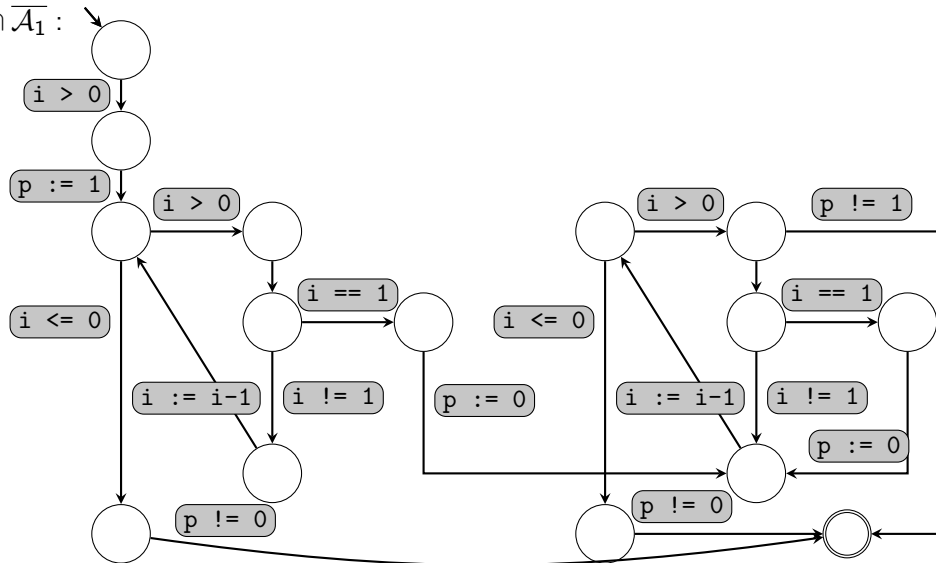
$\mathcal{A}_1 :$



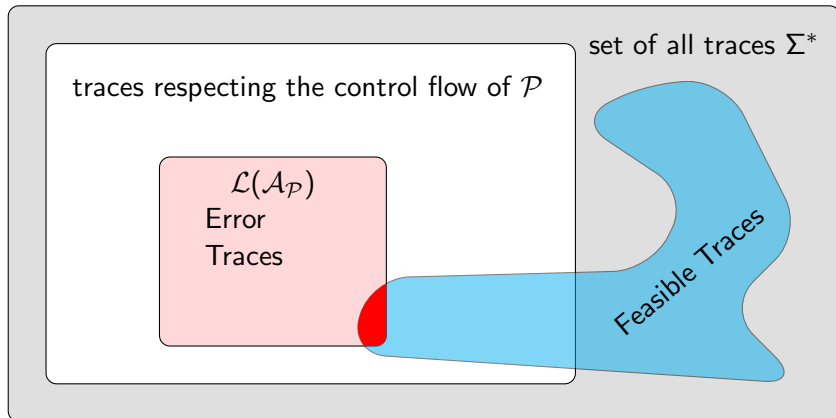
Subtracting Finite Automata from Each Other

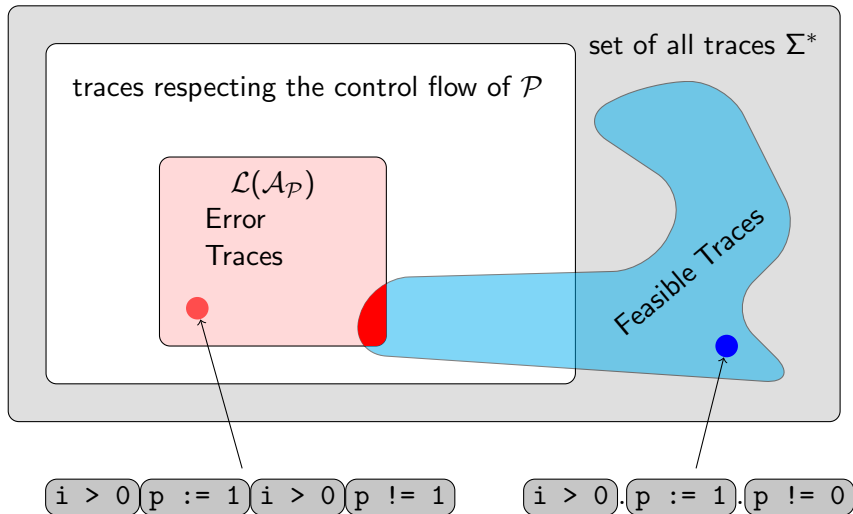
There are algorithms to complement and intersect finite automata.

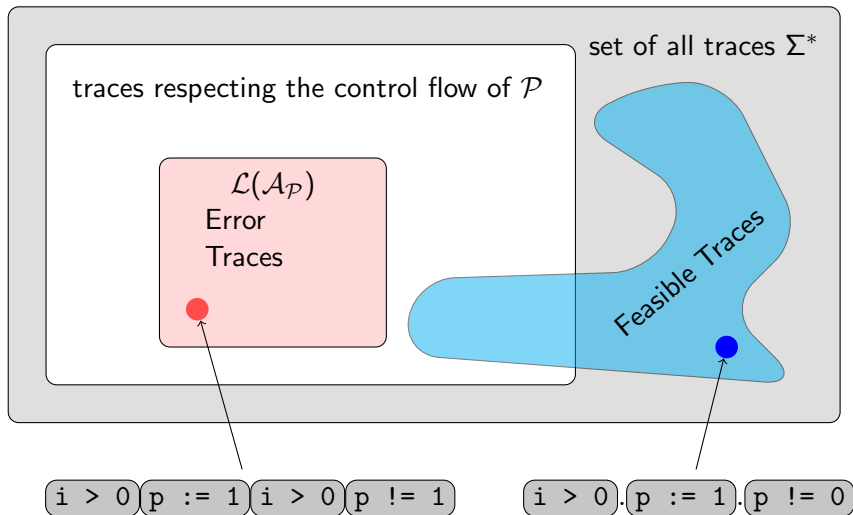
$\mathcal{A}_p \cap \overline{\mathcal{A}_1}$:

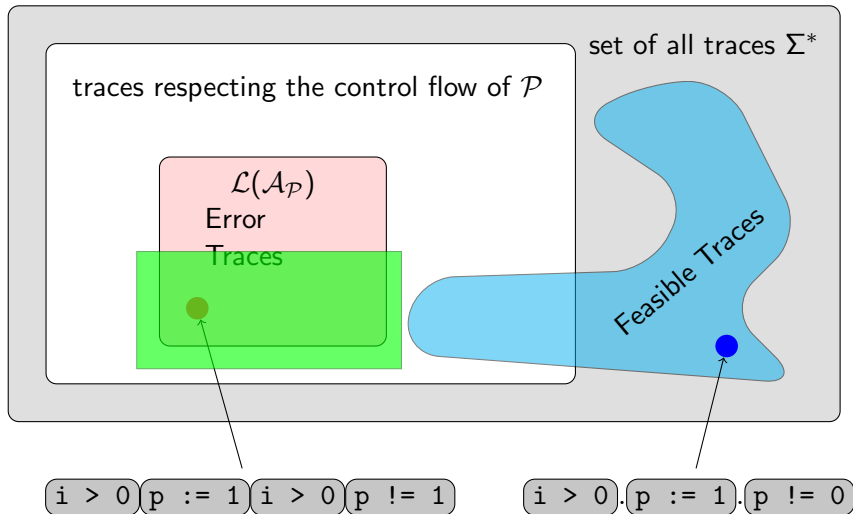


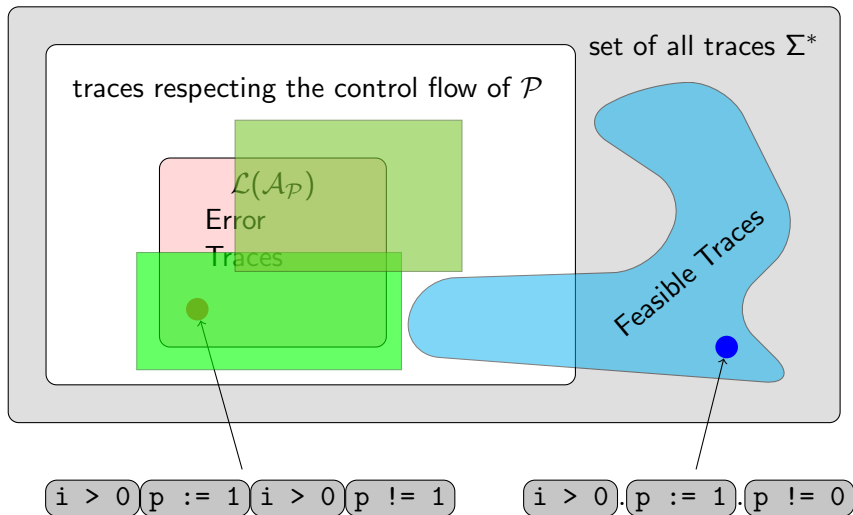
- 1 Build program automaton.
- 2 Pick an error traces. If none, program is safe.
- 3 Ask SMT solver. If sat, program is unsafe.
- 4 Generalize error trace to an automaton.
- 5 Subtract from program automaton.
- 6 Go to step 2.

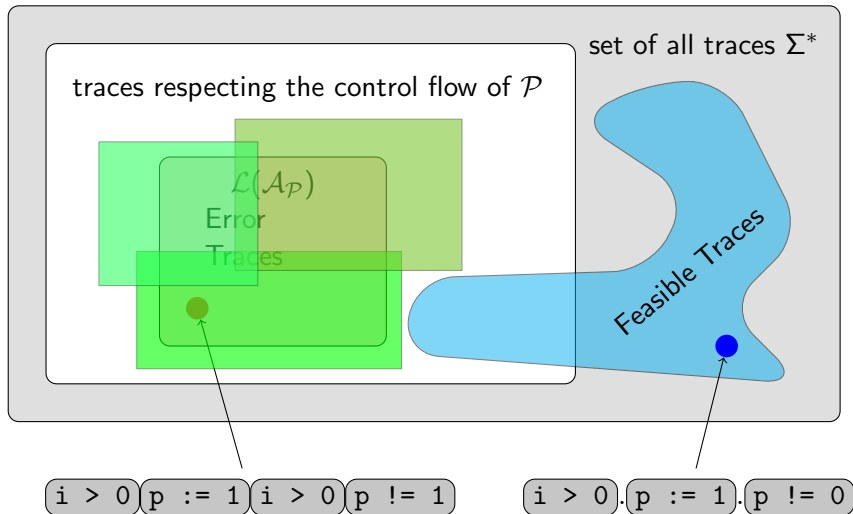












Definition (Trace Abstraction)

A **trace abstraction** is given by a tuple of automata $(\mathcal{A}_1, \dots, \mathcal{A}_n)$ such that each \mathcal{A}_i recognizes a subset of infeasible traces, for $i = 1, \dots, n$.

We say that the **trace abstraction** $(\mathcal{A}_1, \dots, \mathcal{A}_n)$ does not admit an error trace if $\mathcal{A}_{\mathcal{P}} \cap \overline{\mathcal{A}_1} \cap \dots \cap \overline{\mathcal{A}_n}$ is empty.

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Theorem (Soundness)

$$\mathcal{L}(\mathcal{A}_{\mathcal{P}} \cap \overline{\mathcal{A}_1} \cap \dots \cap \overline{\mathcal{A}_n}) = \emptyset \quad \Rightarrow \quad \mathcal{P} \text{ is correct}$$

Theorem (Completeness)

If \mathcal{P} is correct, there is a trace abstraction $(\mathcal{A}_1, \dots, \mathcal{A}_n)$ such that

$$\mathcal{L}(\mathcal{A}_{\mathcal{P}} \cap \overline{\mathcal{A}_1} \cap \dots \cap \overline{\mathcal{A}_n}) = \emptyset$$

Naïve Approach:

Exclude infeasible error traces.

... but there are infinitely many.

Interpolant Based Approach:

Generalize infeasible error traces.

Exclude classes of infeasible traces.

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Interpolants for Infeasible Traces

Let $st_1 \wedge \dots \wedge st_n$ be an infeasible trace. There exists a sequence of predicates l_0, \dots, l_n such that

$$l_0 = \mathbf{true} \quad l_i \wedge st_{i+1} \Rightarrow l_{i+1} \quad l_n = \mathbf{false}$$

In particular:

$$st_1 \wedge \dots \wedge st_i \Rightarrow l_i \Rightarrow \neg(st_{i+1} \wedge \dots \wedge st_n)$$

Example:

$$\mathbf{true} \quad i_0 > 0 \quad \mathbf{true} \quad p_1 = 1 \quad p_1 = 1 \quad i_0 > 0 \quad p_1 = 1 \quad p_1 \neq 1 \quad \mathbf{false}$$

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Interpolants are intermediate assertions in a Hoare proof.

true $i_0 > 0$ **true** $p_1 = 1$ **$p_1 = 1$** $i_0 > 0$ **$p_1 = 1$** $p_1 \neq 1$ **false**

true $i_0 > 0$ **true** $p_1 = 1$ $p_1 = 1$ $i_0 > 0$ $p_1 = 1$ $p_1 \neq 1$ **false**

{true}	i > 0	{true}
{true}	p := 1	{p = 1}
{p = 1}	i > 0	{p = 1}
{p = 1}	p != 1	{false}

This proves that the trace is infeasible:

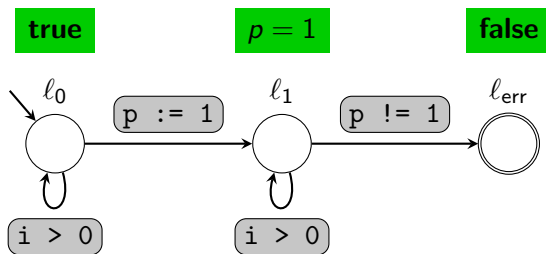
{true} i > 0 p := 1 i > 0 p != 1 {false}

```
(set-option :produce-interpolants true)
(set-logic QF_LIA)
(declare-const i0 Int)
(declare-const p0 Int)
(declare-const i1 Int)
(declare-const p1 Int)

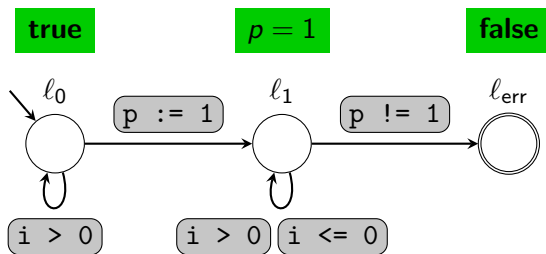
(assert (! (> i0 0) :name st1))
(assert (! (= p1 1) :name st2))
(assert (! (> i0 0) :name st3))
(assert (! (not (= p1 1)) :name st4))

(check-sat)
(get-interpolants st1 st2 st3 st4)
```

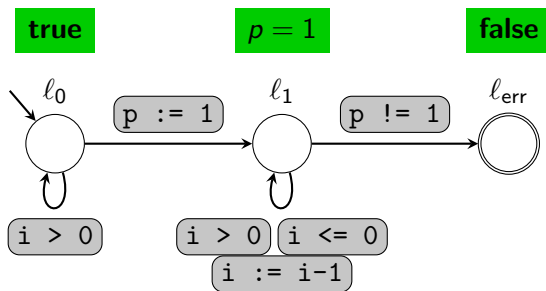

Example – Use Interpolants to Generalize Infeasible Traces



Example – Use Interpolants to Generalize Infeasible Traces



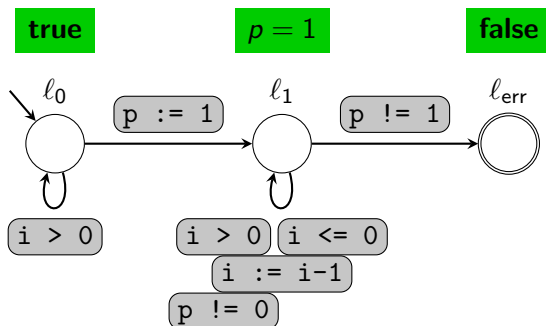
$\{p = 1\}$ $i \leq 0$ $\{p = 1\}$



$\{p = 1\}$ $i \leq 0$ $\{p = 1\}$

$\{p = 1\}$ $i := i - 1$ $\{p = 1\}$

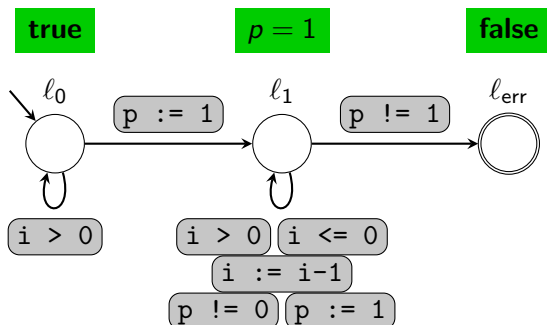
Example – Use Interpolants to Generalize Infeasible Traces



$\{p = 1\}$ $i \leq 0$ $\{p = 1\}$
 $\{p = 1\}$ $p \neq 0$ $\{p = 1\}$

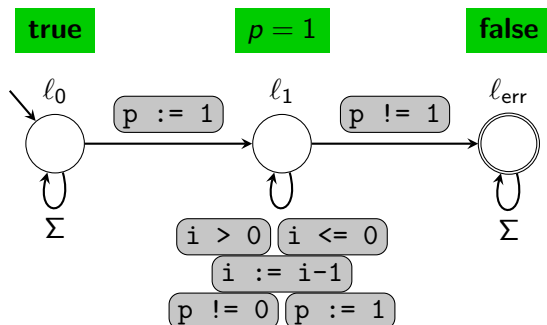
$\{p = 1\}$ $i := i - 1$ $\{p = 1\}$

Example – Use Interpolants to Generalize Infeasible Traces



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Given: Sequence of interpolants $\mathcal{I} = I_0, I_1, \dots, I_n$

Definition (Interpolant Automaton $\mathcal{A}_{\mathcal{I}}$)

$$\mathcal{A}_{\mathcal{I}} = \langle Q_{\mathcal{I}}, \delta_{\mathcal{I}}, Q_{\mathcal{I}}^{\text{init}}, Q_{\mathcal{I}}^{\text{fin}} \rangle \quad Q_{\mathcal{I}} = \mathcal{I}$$

$$(I_i, st, I_j) \in \delta_{\mathcal{I}} \quad \text{iff} \quad \{I_i\} \text{ st } \{I_j\} \text{ holds}$$

$$q_0 := \mathbf{true} \in Q_{\mathcal{I}}$$

$$Q^{\text{fin}} := \{\mathbf{false}\} \subseteq Q_{\mathcal{I}}$$

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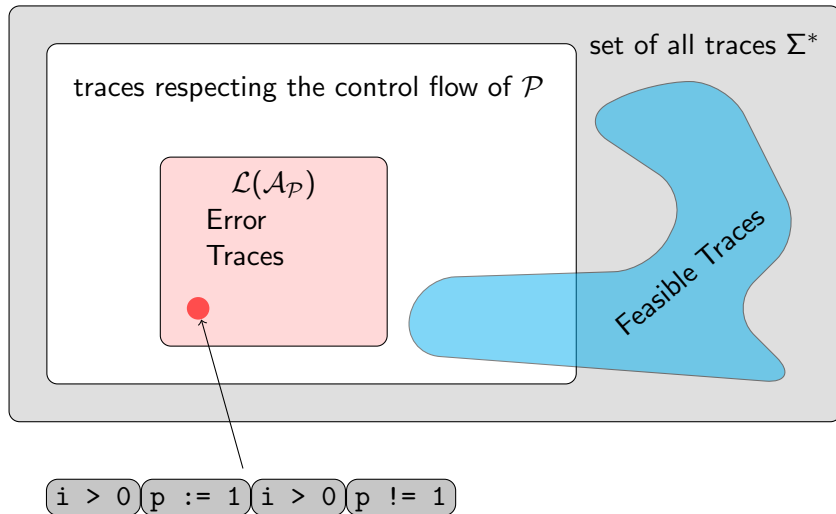
$$Q_{\mathcal{I}}^{\text{fin}} := \{\mathbf{false}\} \subseteq Q_{\mathcal{I}}$$

Theorem

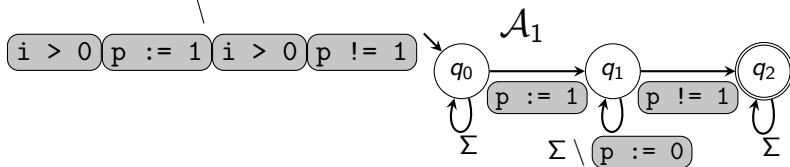
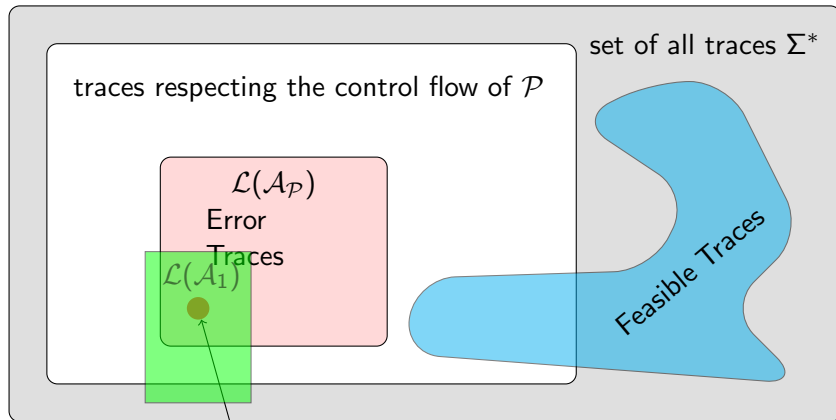
An interpolant automaton $\mathcal{A}_{\mathcal{I}}$ recognizes a subset of infeasible traces.

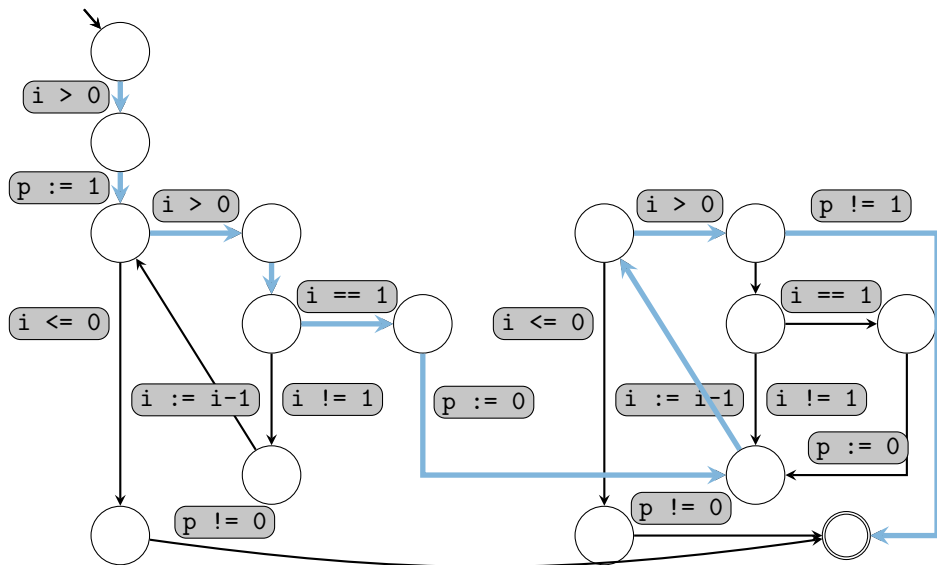
$$\mathcal{L}(\mathcal{A}_{\mathcal{I}}) \subseteq \text{Infeasible}$$

Example – Refinement Using Interpolant Automata



Example – Refinement Using Interpolant Automata



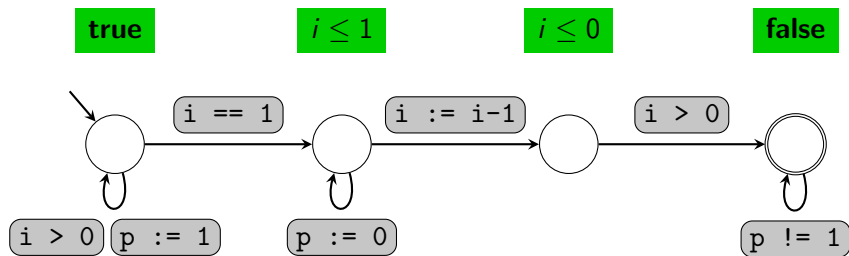


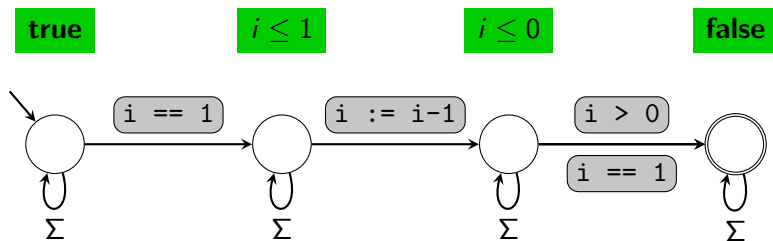
`i > 0` `p := 1` `i > 0` `i == 1` `p := 0` `i := i-1` `i > 0` `p != 1`

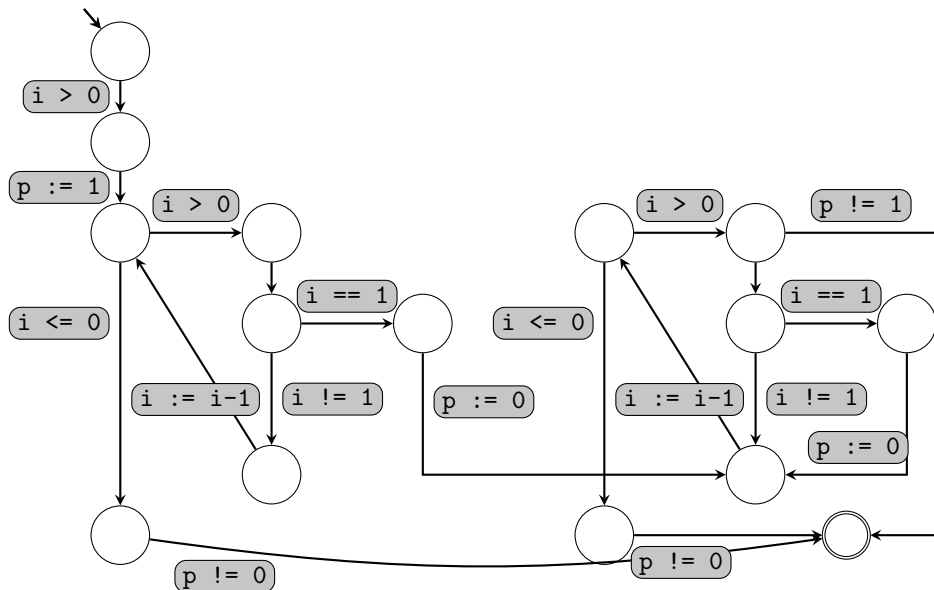
```
(set-option :produce-interpolants true)
(set-logic QF_LIA)
(declare-const i0 Int)
(declare-const i1 Int)
(declare-const p0 Int)
(declare-const p1 Int)
(declare-const p2 Int)

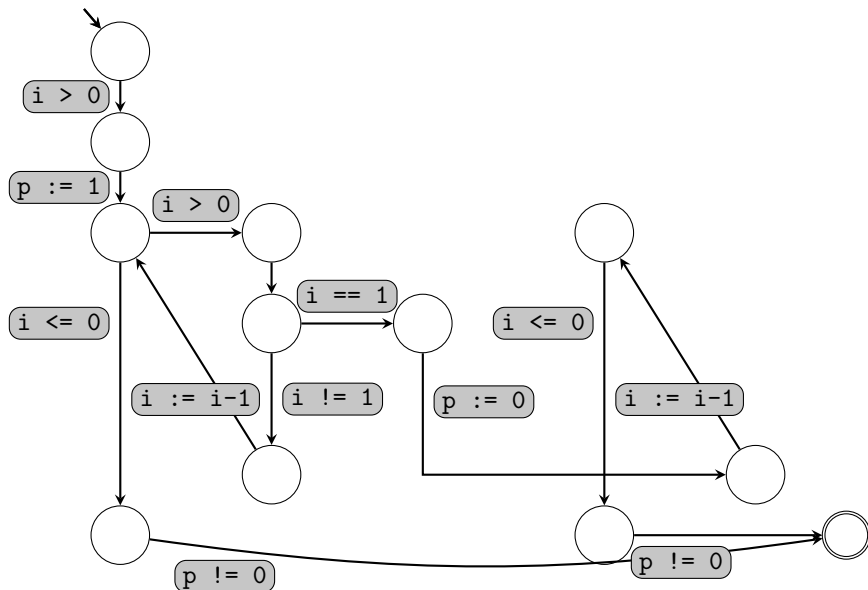
(assert (! (...) :named st1))
...

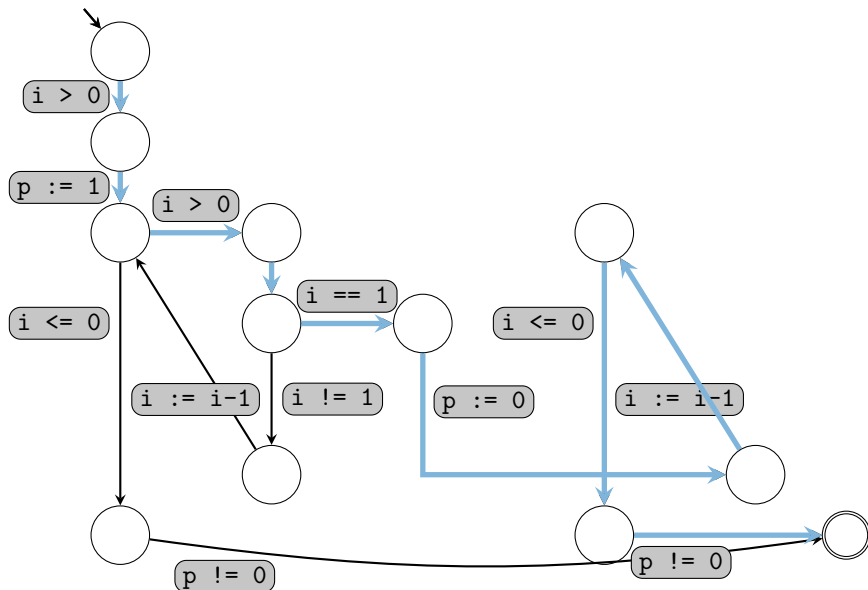
(check-sat)
(get-interpolants st1 st2 st3 ...)
```











`i > 0` `p := 1` `i > 0` `i == 1` `p := 0` `i := i-1` `i <= 0` `p != 0`

```
(set-option :produce-interpolants true)
(set-logic QF_LIA)
(declare-const i0 Int)
(declare-const i1 Int)
(declare-const p0 Int)
(declare-const p1 Int)
(declare-const p2 Int)

(assert (! (...) :named st1))
...

(check-sat)
(get-interpolants st1 st2 st3 ...)
```

`i > 0` `p := 1` `i > 0` `i == 1` `p := 0` `i := i-1` `i <= 0` `p != 0`

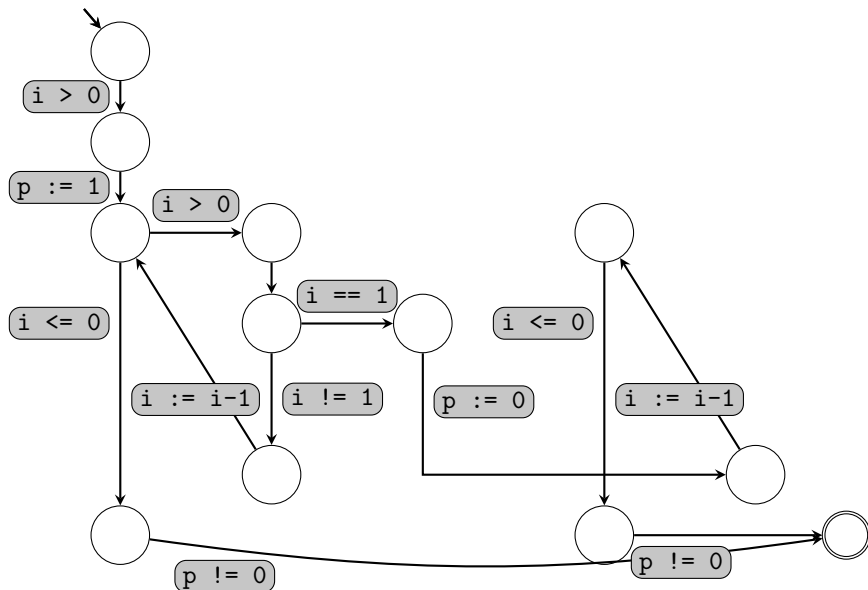
```
(set-option :produce-interpolants true)
(set-logic QF_LIA)
(declare-const i0 Int)
(declare-const i1 Int)
(declare-const p0 Int)
(declare-const p1 Int)
(declare-const p2 Int)

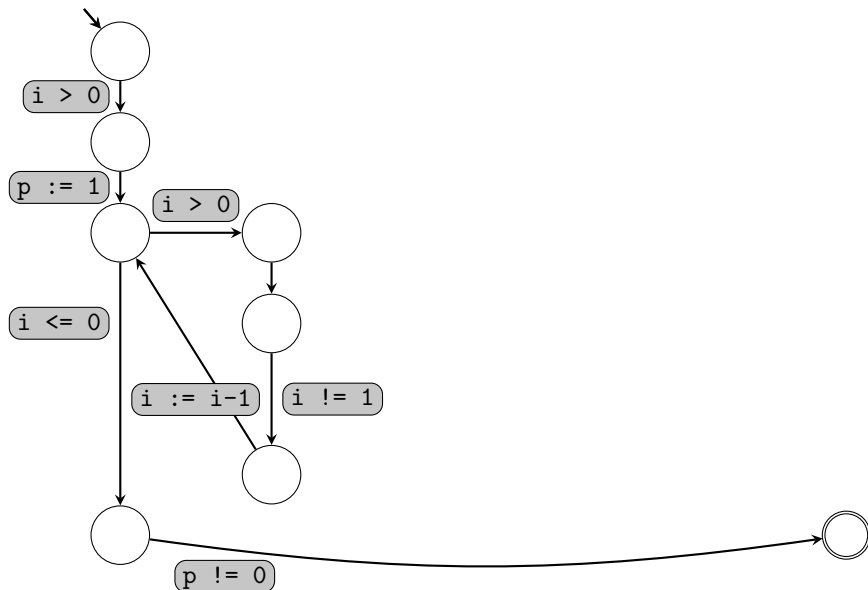
(assert (! (...) :named st1))
...

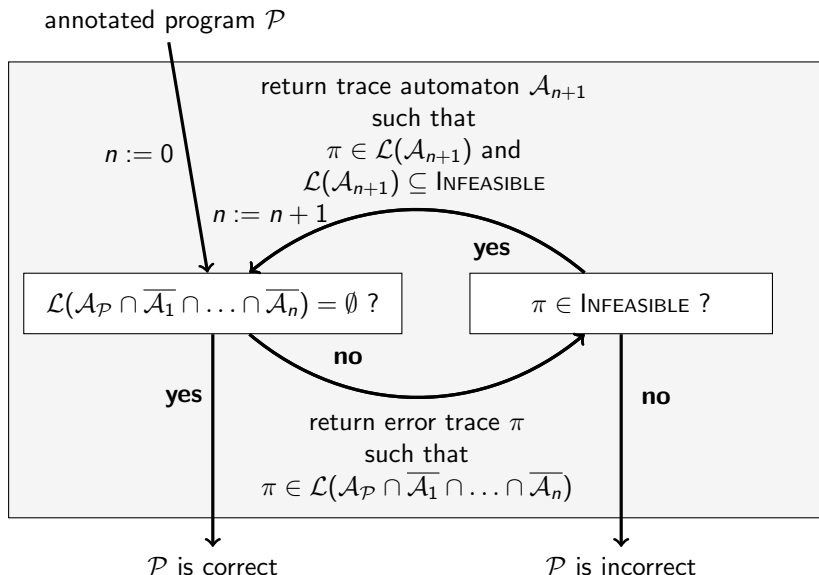
(check-sat)
(get-interpolants st1 st2 st3 ...)
```



```
;;(true true true true (= p2 0) (= p2 0) (= p2 0))
```







Recursive Function

Example: McCarthy 91 Function

```
int f91(int x) {  
    if (x > 100)  
        return x - 10;  
    else  
        return f91(f91(x + 11));  
}
```


Example: McCarthy 91 Function

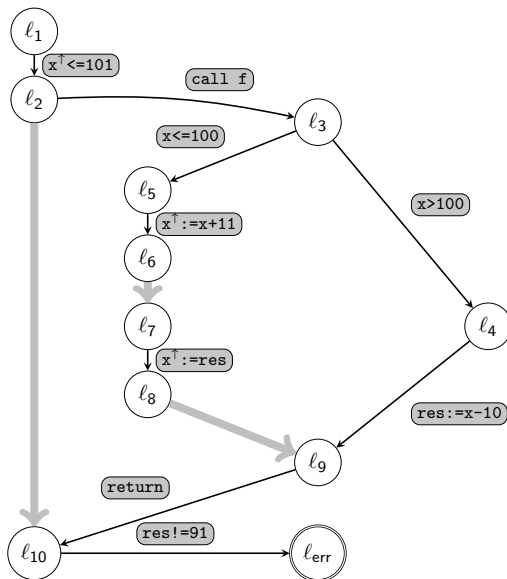
```
int f91(int x) {
    if (x > 100)
        return x - 10;
    else
        return f91(f91(x + 11));
}
```

```
int main(int x) {
    int res;
    if (x <= 101) {
        res = f91(x);
        //@assert(res == 91);
    }
}
```

```

f(x) {
l3:   if (x > 100) {
l4:     res := x - 11
      } else {
l5:     x↑ := x + 10
l6:     call f
l7:     x↑ := res
l8:     call f
      }
l9:   return res
}

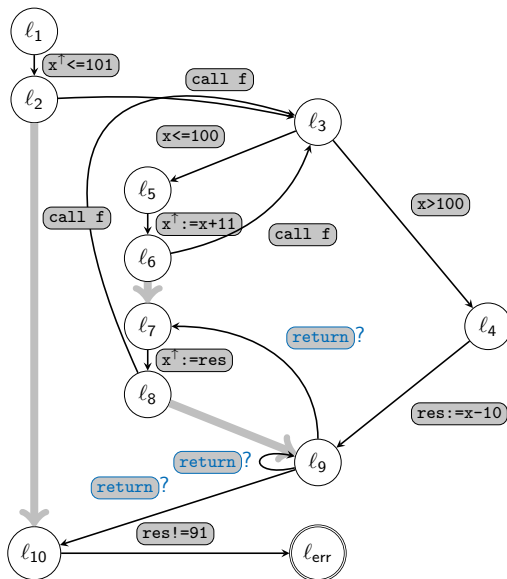
main() {
l1:   if (x↑ ≤ 101) {
l2:     call f
l10:  assert(res == 91)
      }
}
    
```



```

f(x) {
l3:   if (x > 100) {
l4:     res := x - 11
      } else {
l5:     x↑ := x + 10
l6:     call f
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main() {
l1:   if (x↑ <= 101) {
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```

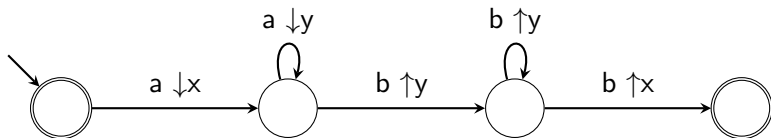


Reminder Push-down Automaton

A **push-down automaton** $\mathcal{A} = (\Sigma, \Gamma, Q, \rightarrow, q_0, F)$ consists of

- Σ : a finite alphabet
- Γ : a **stack alphabet**
- Q : a finite set of locations
- $\rightarrow \subseteq Q \times \Sigma \times Op \times Q$: a transition relation, where Op is a stack operation: $\downarrow\gamma$ (push), $\uparrow\gamma$ (pop), or none.
- $q_0 \in Q$: the initial location
- $F \subseteq Q$: the accepting locations

Example:

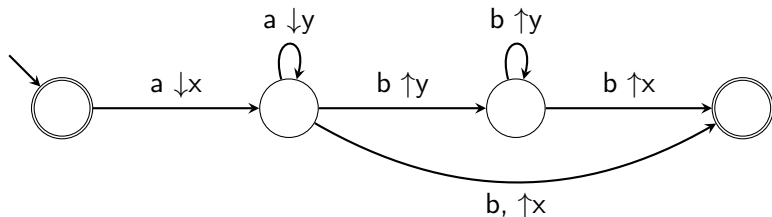


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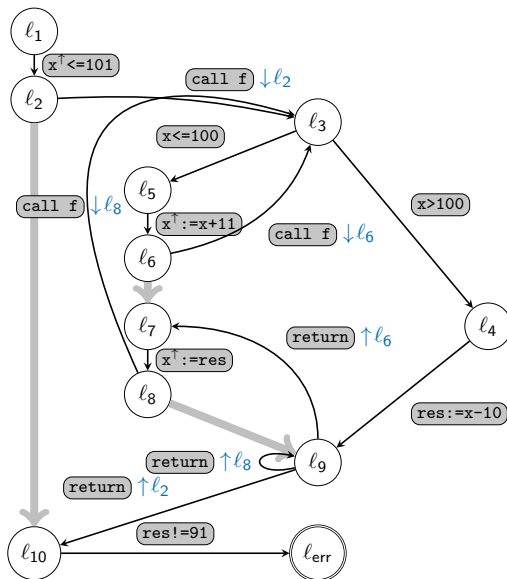
Example:



```

f(x) {
l3:   if (x > 100) {
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      } else {
l5:     x↑ := x + 10
l6:     call f
l7:     x↑ := res
l8:     call f
      }
l9:   return res
}

main() {
l1:   if (x↑ <= 101) {
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l10:  assert(res == 91)
      }
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```



Problem

Push-down Automata can't be subtracted/complemented/intersected.

Problem

Push-down Automata can't be subtracted/complemented/intersected.

Solution: Alur & Madhusudan: Visibly Push-down Languages, 2004

- Closed under complementation, intersection
- The symbol decides whether to push, pop, or do nothing
- Suitable for call/return statements.

A **visibly push-down automaton** $\mathcal{A} = (\Sigma_i, \Sigma_c, \Sigma_r, \Gamma, Q, \rightarrow, q_0, F)$ consists of

- $\Sigma_i, \Sigma_c, \Sigma_r$: three distinct finite alphabet for internal, call, and return statements.
- Γ : a stack alphabet
- Q : a finite set of locations

- $\rightarrow \subseteq \left(\begin{array}{c} Q \times \Sigma_i \times Q \\ \cup \quad Q \times \Sigma_c \times \downarrow \Gamma \times Q \\ \cup \quad Q \times \Sigma_r \times \uparrow \Gamma \times Q \end{array} \right)$.

Call statements always push a value, return statements always pop a value, and internal statements do not change stack.

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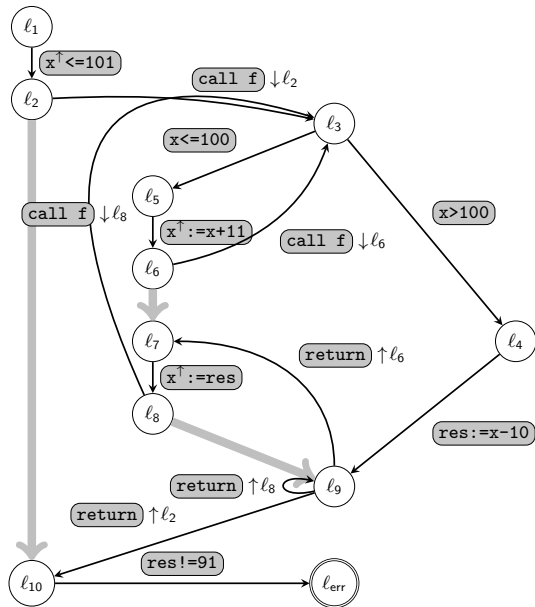
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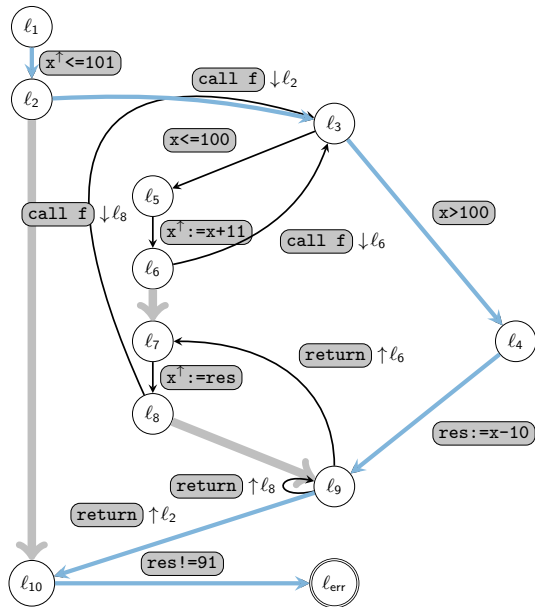
Call statements always push a value, return statements always pop a value, and internal statements do not change stack.

- $q_0 \in Q$: the initial location
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Remark

Nested word automata have equivalent power, differ only in details.





Error Trace:

```

x^<=101 call f x>100 res:=x-10
return res!=91
  
```

- Call statements copy parameters, e.g.

$$\text{call } f \longrightarrow x_1 = x_0^\uparrow$$

- Return statements do nothing.

$$\text{return} \longrightarrow \mathbf{true}$$

- SSA numbering must obey scoping rules, e.g.,

$$\begin{array}{c}
 \boxed{x^\uparrow := x} \quad \boxed{\text{call } f(x)} \quad \boxed{x := x+1} \quad \boxed{\text{res} := x} \quad \boxed{\text{return}} \quad \boxed{z := x + \text{res}} \\
 \downarrow \\
 x_1^\uparrow = x_0 \wedge x_1 = x_1^\uparrow \wedge x_2 = x_1 + 1 \wedge \text{res}_1 = x_2 \wedge z_1 = x_? + \text{res}_?
 \end{array}$$

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 \downarrow \\
 x_1^\uparrow = x_0 \wedge x_1 = x_1^\uparrow \wedge x_2 = x_1 + 1 \wedge \text{res}_1 = x_2 \wedge z_1 = x_0 + \text{res}_1
 \end{array}$$

Error Trace:

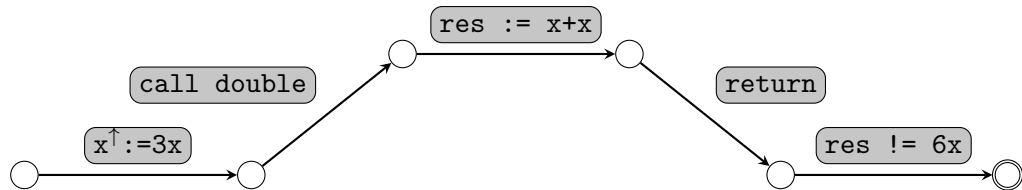
$\pi =$ `x↑<=101` `call f` `x>100` `res:=x-10` `return` `res!=91`

SSA:

$SSA(\pi) = x_0^{\uparrow} \leq 101 \wedge x_1 = x_0^{\uparrow} \wedge x_1 > 100 \wedge res_1 = x_1 - 10 \wedge res_1 \neq 91$

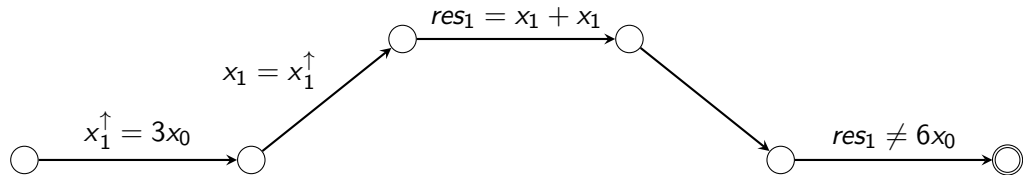
Interpolation for Recursive Traces

```
int main(x) { assert double(3*x) == 6*x; }  
int double(x) { return x+x; }
```



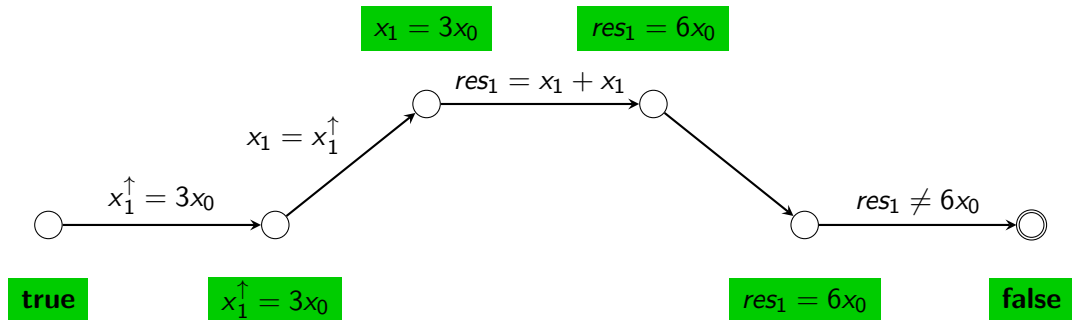
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Interpolation for Recursive Traces

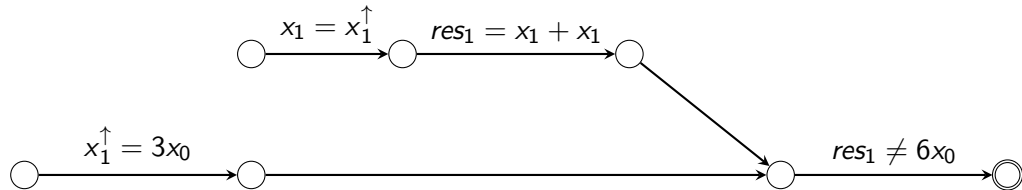
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Problem: Interpolants use differently scoped variables

Interpolation for Recursive Traces

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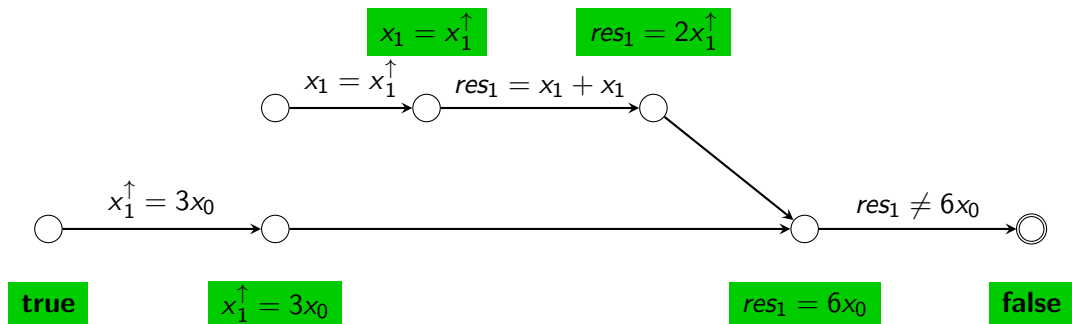


Problem: Interpolants use differently scoped variables

Solution: Tree Interpolants

Interpolation for Recursive Traces

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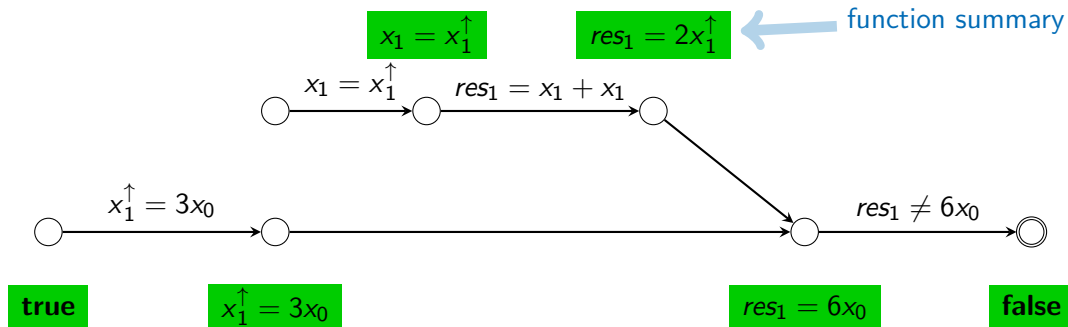


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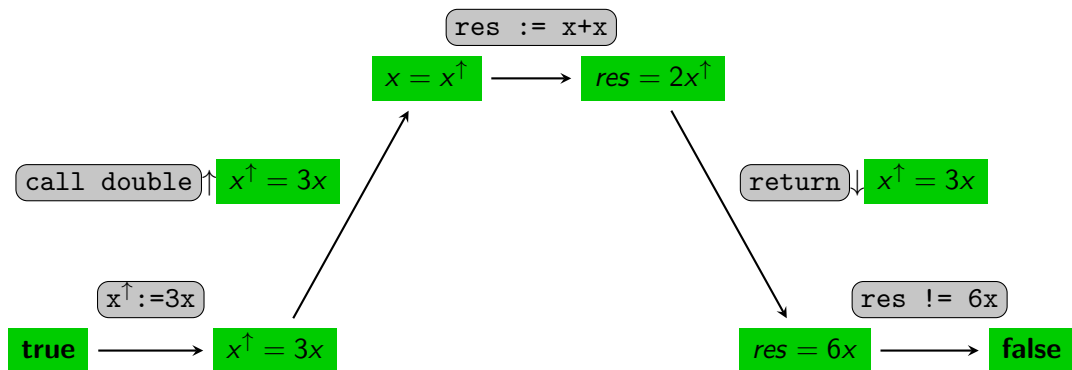


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$$(I_i, \text{call } f \uparrow I_i, I_j) \quad \text{iff} \quad x^\uparrow = x \Rightarrow I_j$$

$$(I_i, \text{return} \downarrow I_k, I_j) \quad \text{iff} \quad I_i \wedge I_k \Rightarrow I_j$$

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$$Q_{\mathcal{I}}^{\text{fin}} := \{\text{false}\} \subseteq Q_{\mathcal{I}}$$

Theorem

An interpolant automaton $\mathcal{A}_{\mathcal{I}}$ recognizes a subset of infeasible traces.

$$\mathcal{L}(\mathcal{A}_{\mathcal{I}}) \subseteq \text{Infeasible}$$


```
x↑ := 3x call double res := x+x return res != 6x
```

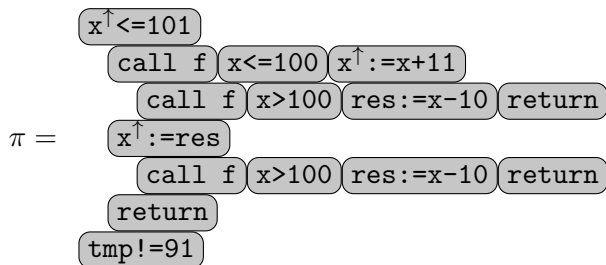
```
(set-option :produce-interpolants true)
(set-logic QF_LIA)
(declare-const x0 Int)
(declare-const x1 Int)
(declare-const x^1 Int)
(declare-const res1 Int)

(assert (! (= x^1 (* 3 x0)) :named st1))
(assert (! (= x1 x^1) :named st2))
(assert (! (= res1 (+ x1 x1)) :named st3))
(assert (! true :named st4))
(assert (! (not (= res1 (* 6 x0))) :named st5))

(check-sat)
(set-option :print-terms-cse false)
(get-interpolants st1 (st2 st3) st4 st5)
```

$\pi =$

```
x↑ ≤ 101
  call f x ≤ 100 x↑ := x + 11
    call f x > 100 res := x - 10 return
  x↑ := res
    call f x > 100 res := x - 10 return
  return
tmp != 91
```



$$\begin{aligned}
 \text{SSA}(\pi) = & x_0^\uparrow \leq 101 \wedge \\
 & x_1 = x_0^\uparrow \wedge x_1 \leq 100 \wedge x_1^\uparrow = x_1 + 11 \wedge \\
 & x_2 = x_1^\uparrow \wedge x_2 > 100 \wedge \text{res}_1 = x_2 - 10 \wedge \mathbf{true} \wedge \\
 & x_2^\uparrow = \text{res}_1 \wedge \\
 & x_3 = x_2^\uparrow \wedge x_3 > 100 \wedge \text{res}_2 = x_3 - 10 \wedge \mathbf{true} \wedge \\
 & \mathbf{true} \wedge \\
 & \text{res}_2 \neq 91
 \end{aligned}$$

```
(set-option :produce-interpolants true)
(set-logic QF_LIA)
(declare-const x0 Int)
(declare-const x1 Int)
(declare-const x2 Int)
(declare-const x3 Int)
(declare-const x^0 Int)
...

(assert (! (...) :named st1))
...

(check-sat)
(get-interpolants st1 (st2 ...) st12)
```

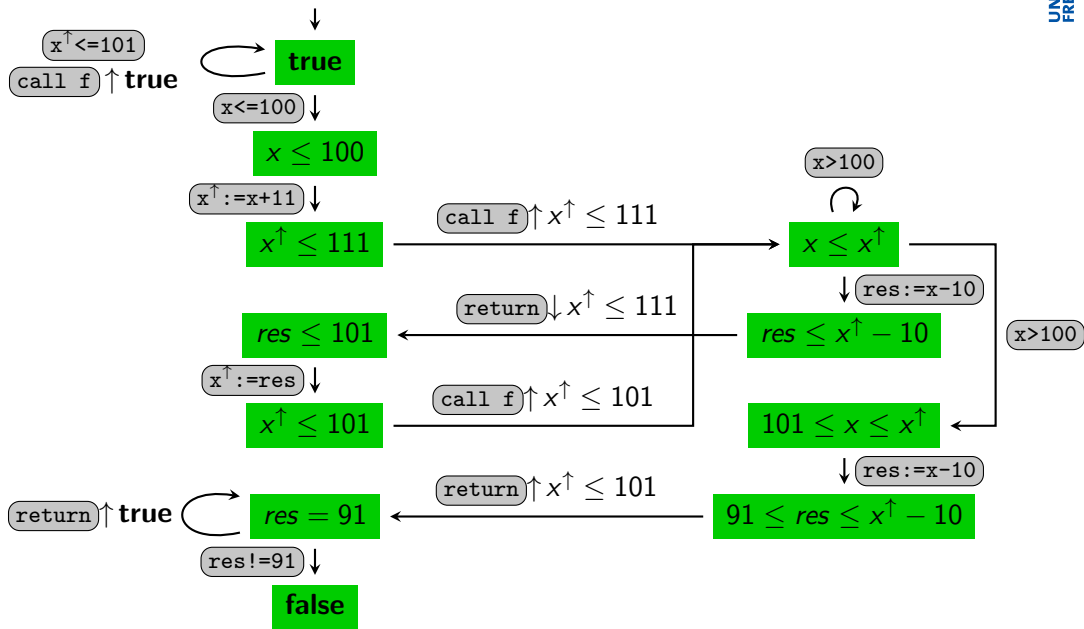
Computing Interpolants

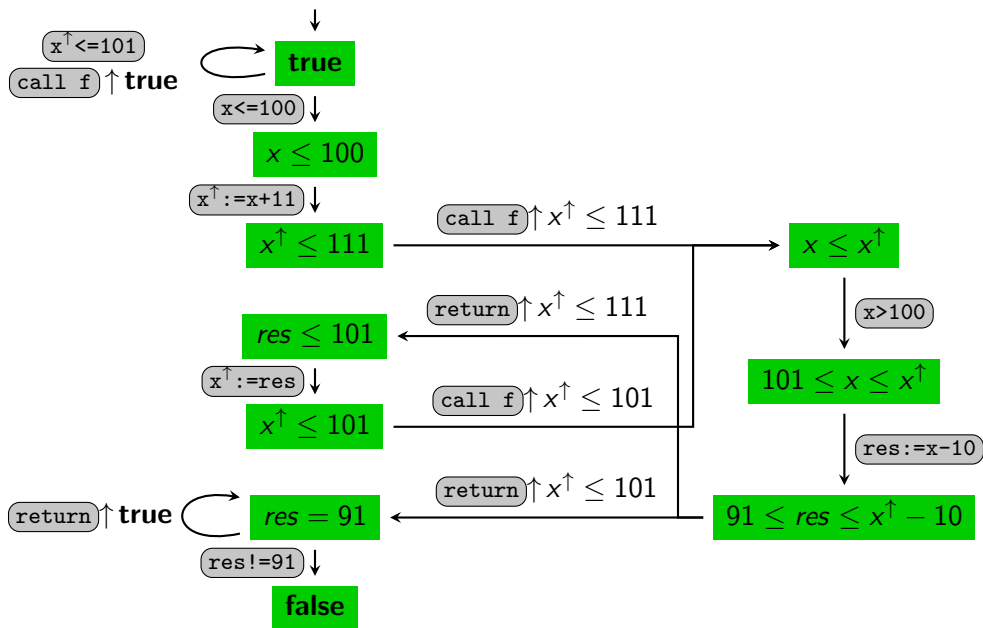
```
(set-option :produce-interpolants true)
(set-logic QF_LIA)
(declare-const x0 Int)
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(declare-const x3 Int)
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...

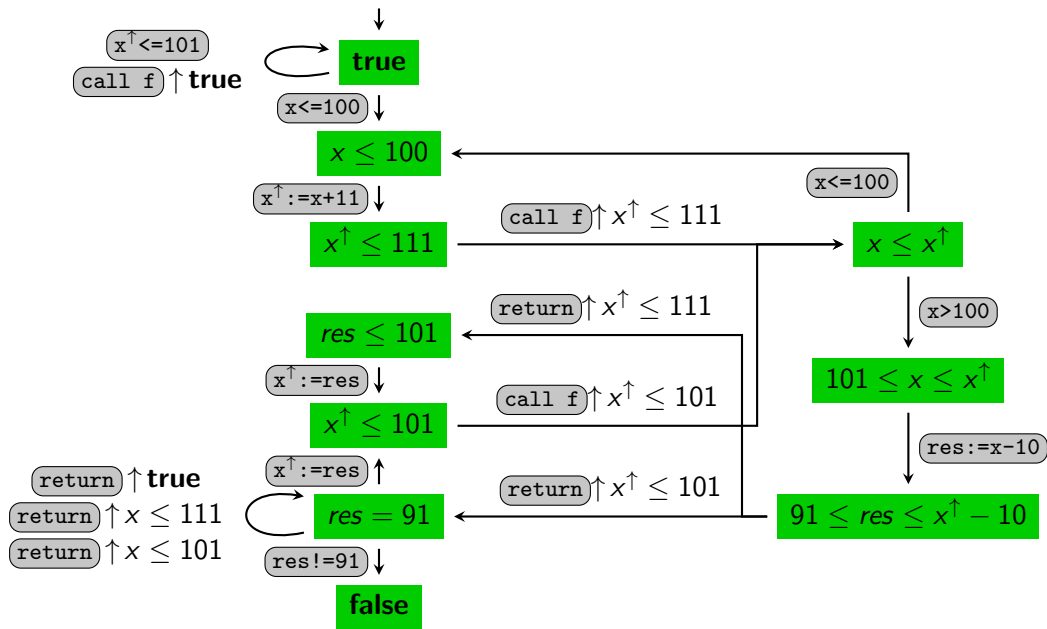
(assert (! (...) :named st1))
...

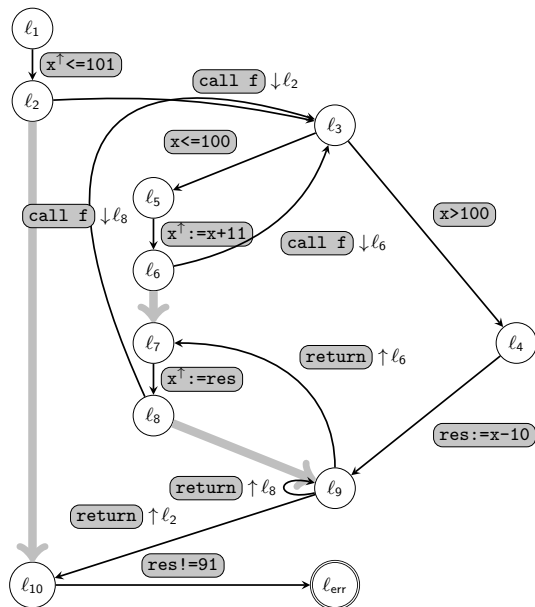
(check-sat)
(get-interpolants st1 (st2 ...) st12)

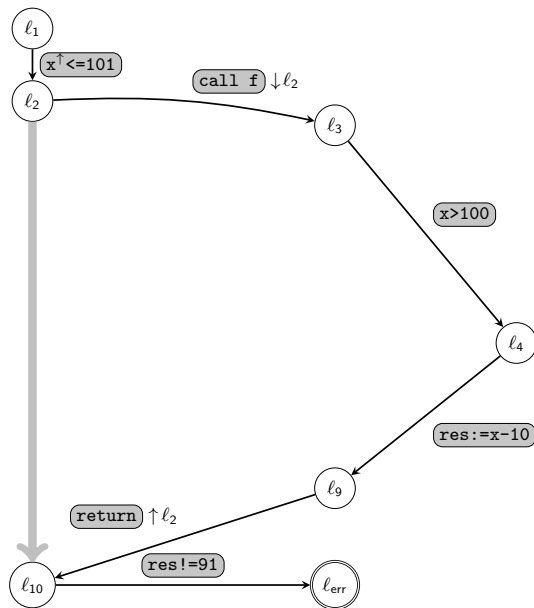
;;(true true (<= x1 100) (<= x^1 111) (<= x2 x^1) (<= x2 x^1)
;;(<= res1 (- x^1 10)) (<= x^2 101) (<= x3 x^2) (<= 101 x3 x^2))
;;(or (<= 91 res2 (- x^2 10)) (= res2 91)) (= res2 91))
```











Termination

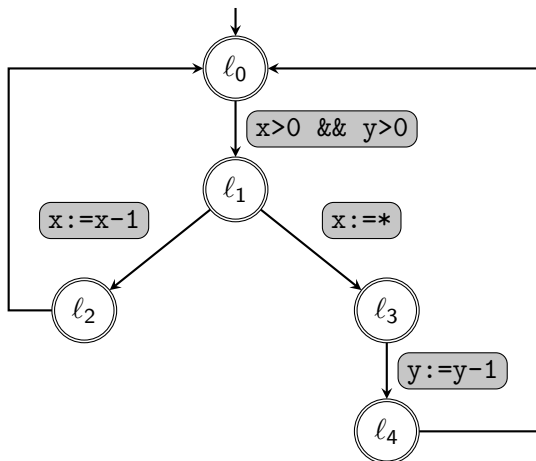
```
void main() {  
  while (x > 0 && y > 0) {  
    if (*) {  
      x := x - 1;  
    } else {  
      x := *;  
      y := y - 1;  
    }  
  }  
}
```

Does this program terminate?

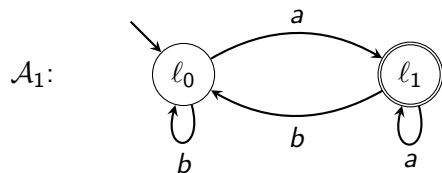
```
void main() {  
  while (x > 0 && y > 0) {  
    if (*) {  
      x := x - 1;  
    } else {  
      x := *;  
      y := y - 1;  
    }  
  }  
}
```

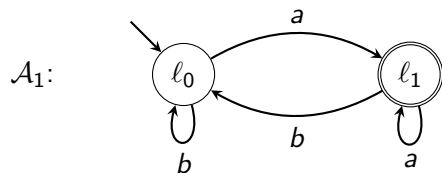
Does this program terminate?
How can we prove it?

```
void main() {  
  while (x > 0 && y > 0) {  
    if (*) {  
      x := x - 1;  
    } else {  
      x := *;  
      y := y - 1;  
    }  
  }  
}
```

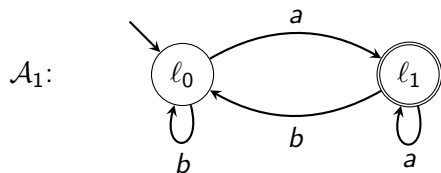


A Büchi automaton accepts infinite words that infinitely often visit accepting states.

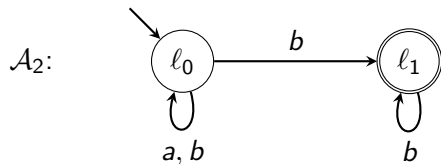




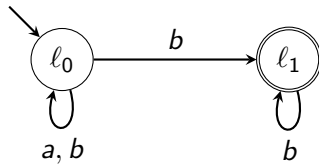
$$\mathcal{L}(\mathcal{A}_1) = \{(a + b)^\omega \mid \text{infinitely many } a\}$$



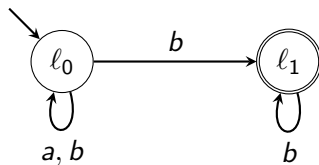
$$\mathcal{L}(\mathcal{A}_1) = \{(a + b)^\omega \mid \text{infinitely many } a\}$$



$$\mathcal{L}(\mathcal{A}_2) = \{(a + b)^\omega \mid \text{finitely many } a\}$$



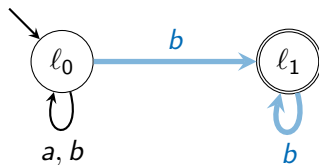
How to represent infinite words?



How to represent infinite words?

Fact

Every non-empty Büchi-Automaton accepts an ultimately periodic word.

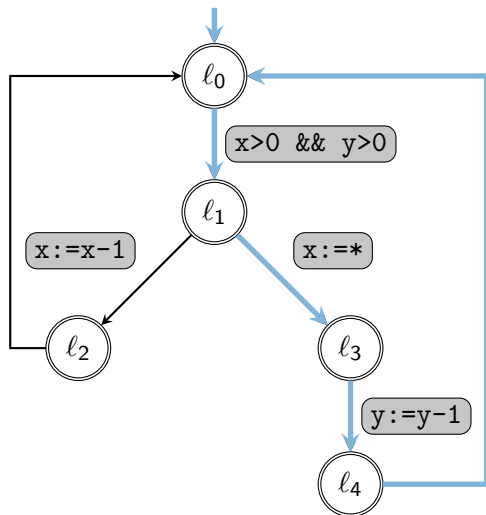


How to represent infinite words?

Fact

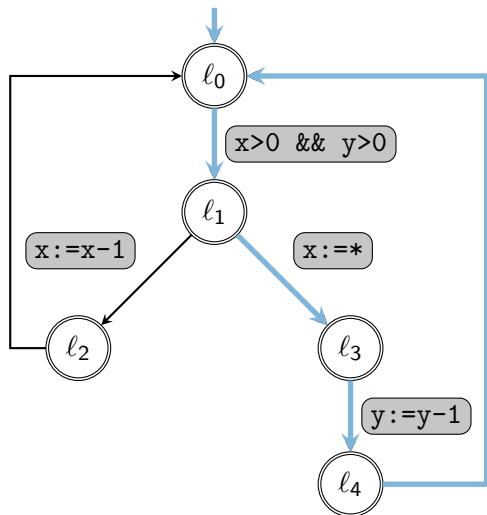
Every non-empty Büchi-Automaton accepts an ultimately periodic word.

$$b(b)^\omega \in \mathcal{L}(\mathcal{A}_2)$$



Error Trace:

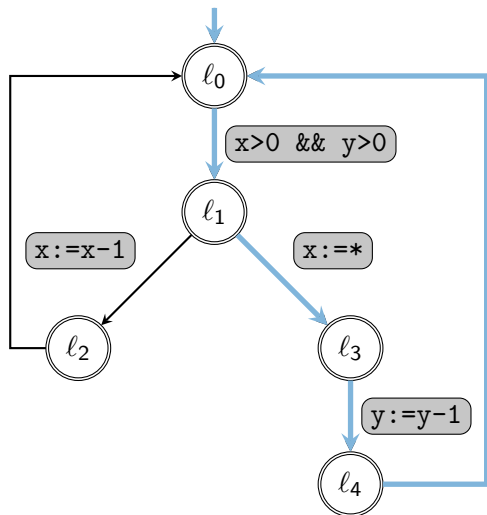
$x > 0 \ \&\& \ y > 0 \ (\ x := * \ y := y - 1 \ x > 0 \ \&\& \ y > 0)^\omega$



Error Trace:

$$x>0 \ \&\& \ y>0 \ (x:=* \ y:=y-1 \ x>0 \ \&\& \ y>0)^\omega$$

Infeasible: Ranking function y .

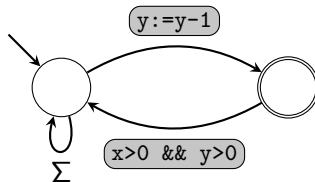


Error Trace:

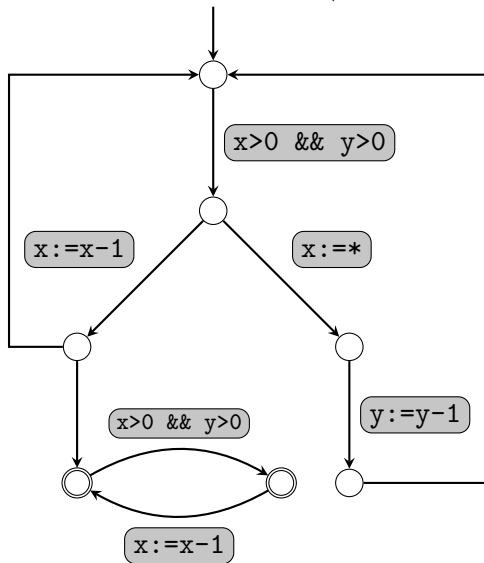
$$x>0 \ \&\& \ y>0 \ (x:=* \ y:=y-1 \ x>0 \ \&\& \ y>0)^\omega$$

Infeasible: Ranking function y .

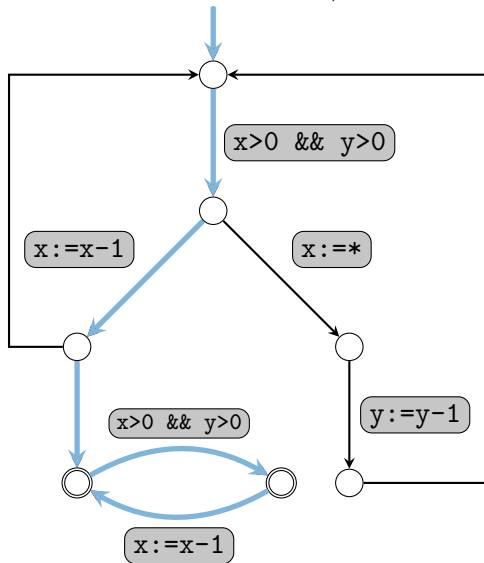
Generalization:



∃ algorithms for intersection/complementation of Büchi Automata!



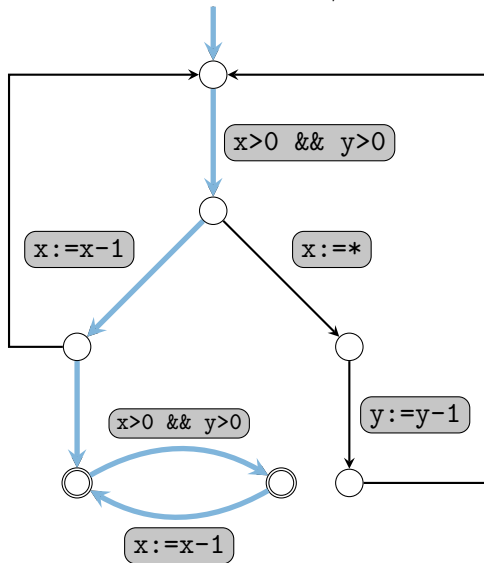
∃ algorithms for intersection/complementation of Büchi Automata!



Error Trace:

`x>0 && y>0` `x:=x-1` ((`x>0 && y>0` `x:=x-1`)^ω)

∃ algorithms for intersection/complementation of Büchi Automata!

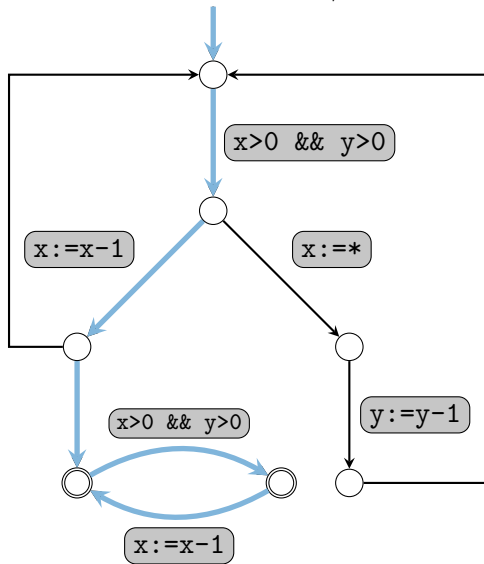


Error Trace:

$x > 0 \ \&\& \ y > 0 \ x := x - 1 \ ((x > 0 \ \&\& \ y > 0 \ x := x - 1)^\omega$

Infeasible: Ranking function x .

∃ algorithms for intersection/complementation of Büchi Automata!

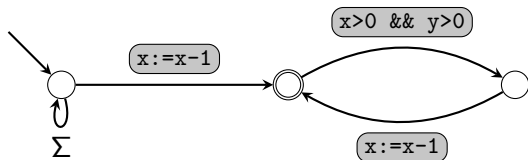


Error Trace:

$x>0 \ \&\& \ y>0 \ x:=x-1 \ ((x>0 \ \&\& \ y>0 \ x:=x-1)^\omega$

Infeasible: Ranking function x .

Generalization:



We have a tool `ULTIMATE RANKFINDER`.

- General pattern $rank := c_1x_1 + \dots + c_nx_n$
where x_1, \dots, x_n are the variables, $c_1 \dots c_n \in \mathbb{Z}$.
- For a lasso $stem(loop)^\omega$, encode an SMT problem:

$$\forall x_1 \dots x_n, x'_1, \dots, x'_n. loop \Rightarrow rank \geq 0 \wedge rank' \leq rank - 1$$

Quantifiers can be eliminated with Farkas' Lemma.

- Ask SMT solver for solution for c_1, \dots, c_n (non-linear arithmetic required).