

# The Overall Picture

Application System + Problem
System Algorithm + Implementation
Algorithm Calculus + Strategy
Calculus Logic + States + Rules
Logic Syntax + Semantics

## 1 Algorithm: 5 CDCL( $S$ )

**Input** : An initial state  $(\epsilon; N; \emptyset; 0; \top)$ .

**Output**: A final state  $S = (M; N; U; k; \top)$  or  $S = (M; N; U; k; \perp)$

### 2 while (any rule applicable) do

#### 3 ifrule (**Conflict**( $S$ )) then

#### 4 | while (**Skip**( $S$ ) || **Resolve**( $S$ )) do

#### 5 | | update VSIDS on resolved literals;

#### 6 | | update VSIDS on learned clause, **Backtrack**( $S$ );

#### 7 | | if (*forget heuristic*) then

#### 8 | | | **Forget**( $S$ ), **Restart**( $S$ );

#### 9 | | else

#### 10 | | | if (*restart heuristic*) then

#### 11 | | | | **Restart**( $S$ );

#### 12 | else

#### 13 | ifrule (! **Propagate**( $S$ )) then

#### 14 | | **Decide**( $S$ ) literal with max. VSIDS score;

#### 15 | | return ( $S$ );



# Implementation: Data Structures

**Propagate**  $(M; N; U; k; \top) \Rightarrow_{\text{CDCL}} (ML^{C \vee L}; N; U; k; \top)$   
 provided  $C \vee L \in (N \cup U)$ ,  $M \models \neg C$ , and  $L$  is undefined in  $M$

**Conflict**  $(M; N; U; k; \top) \Rightarrow_{\text{CDCL}} (M; N; U; k; D)$   
 provided  $D \in (N \cup U)$  and  $M \models \neg D$

# Implementation

- data structures: clauses, trail, and the rules
- heuristics: decision literal, forget, restart
- space efficiency: forget
- quality: restarts
- special cases

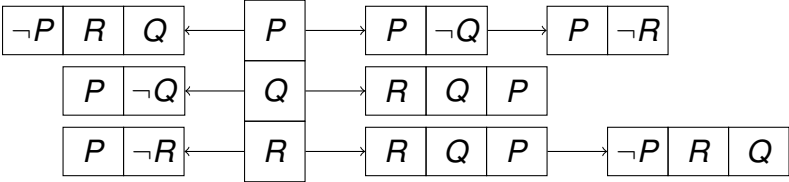
# Data Structures

Idea: Select two literals from each clause for indexing.

## 2.10.1 Invariant (2-Watched Literal Indexing)

If one of the watched literals is false and the other watched literal is not true, then all other literals of the clause are false.

$$N = \{P \vee \neg R, P \vee \neg Q, R \vee Q \vee P, \neg P \vee R \vee Q\}$$



# VSIDS: Variable State Independent Decaying Sum

- each propositional variable has a positive *score*, initially 0
- decide the variable with maximal score, remember sign (*phase saving*)
- increment the score of variables involved in resolution by  $b$
- increment the score of variables in learned clauses by  $b$
- initially  $b > 0$
- at Backtrack set  $b := c * b$  where  $2 \gg c > 1$ , i.e.,  $b_n = c^n * b$
- take care of overflows, i.e., rescale from time to time
- sometimes pick a variable randomly



# Forget

- fix a limit  $d$  on the number of learned clauses
- if more than  $|U| > d$  start forgetting
- remove redundant clauses
- sort the learned clauses according to a score
- typical elements of the score are clause length, the VSIDS score, dependency on decisions
- remove the  $k\%$  clauses with minimal score from  $U$
- $d := d + e$  for some  $e$ ,  $e \gg 1$
- do a Restart





# Restart

- after forgetting do a restart
- if a unit is learned do a restart
- restart often at the beginning of a run
- classics: Luby sequence 1, 1, 2, 1, 1, 2, 4, ...

$$(u_1, v_1) := (1, 1),$$

$$(u_{n+1}, v_{n+1}) := ((u_n \& - u_n) = v_n ? (u_n + 1, 1) : (u_n, 2 * v_n))$$

# Memory Matters: SPASS-SATT

Forget-Start	800	108800
Restarts	412	369
Conflicts	153640	133403
Decisions	184034	159005
Propagations	17770298	15544812
Time	11	23
Memory	16	41