

Practical Animation Reconstruction

Hao Li



Correspondence Problem Classification

How many meshes?

More than two: multi-view registration

Initial registration available?

Yes: Local optimization methods

Class of transformations?

Non-rigid deformations



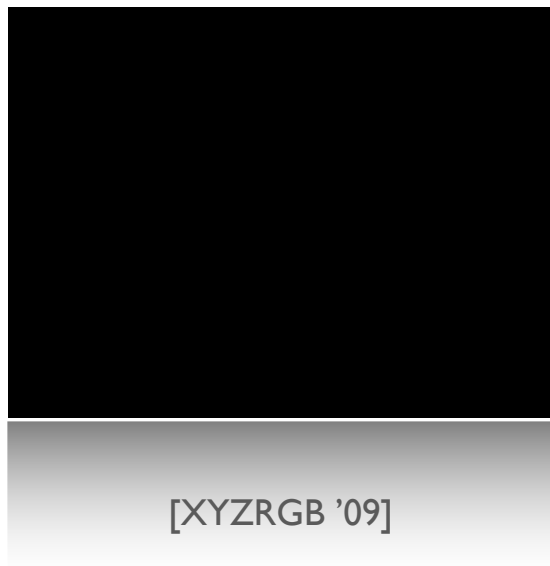
Performance Capture



Performance Capture



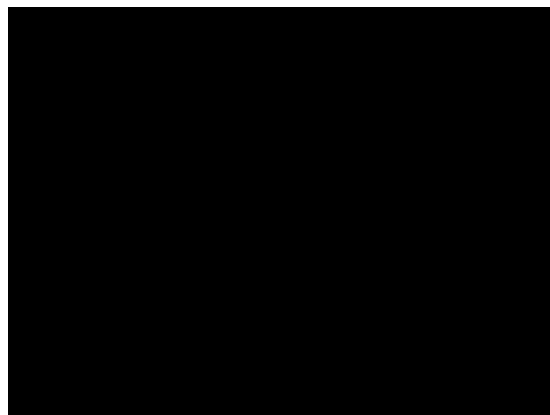
Performance Capture



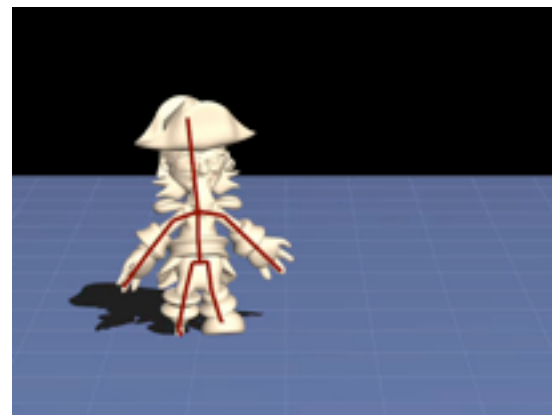
Performance Capture



Performance Capture

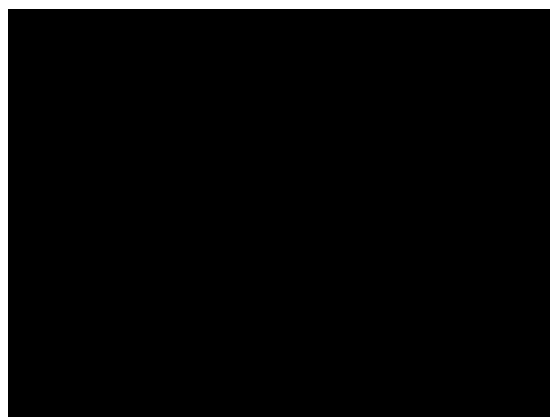


[XYZRGB '09]

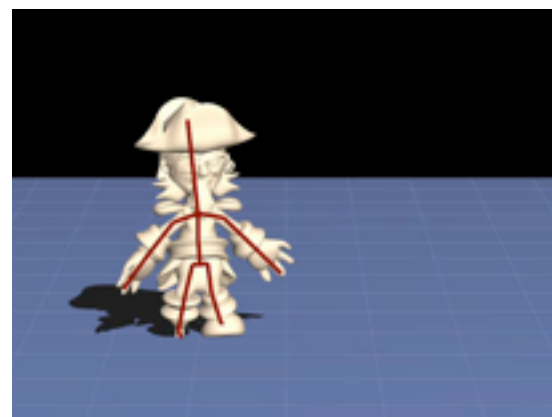


[Baran & Popović '07]

Performance Capture

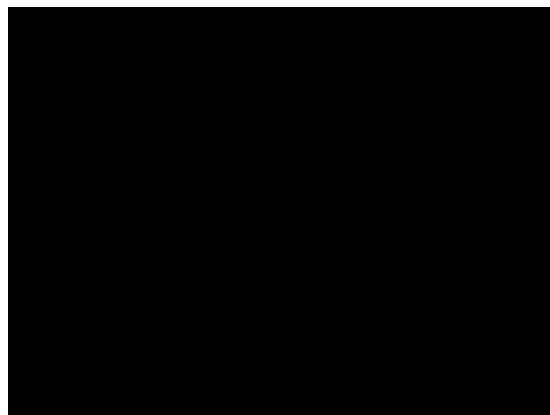


[XYZRGB '09]

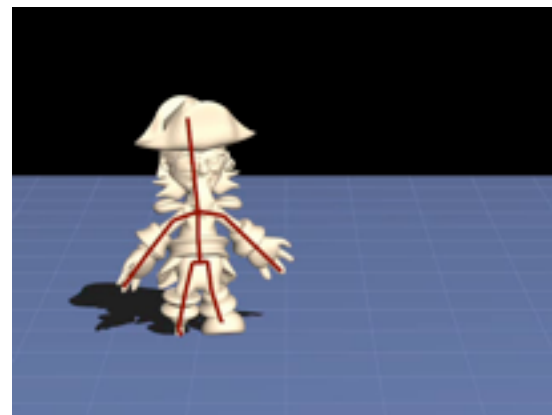


[Baran & Popović '07]

Performance Capture



[XYZRGB '09]

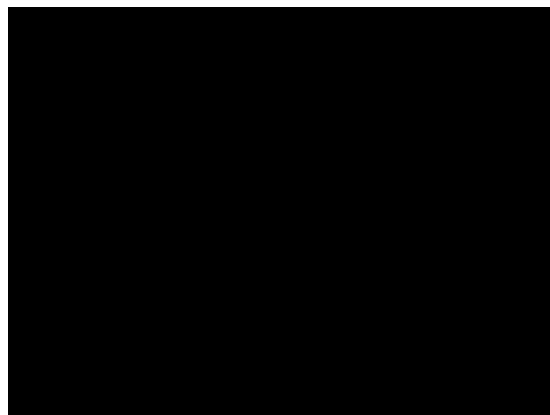


[Baran & Popović '07]

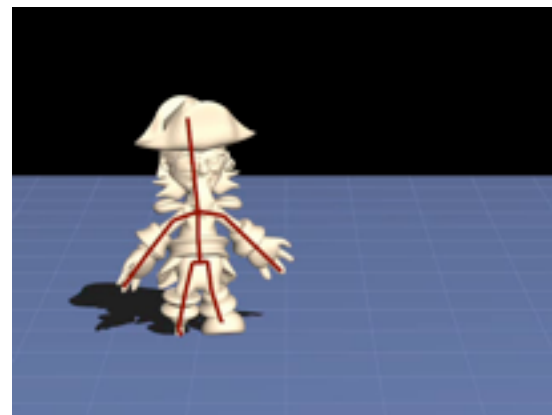


[Vicon '08]

Performance Capture



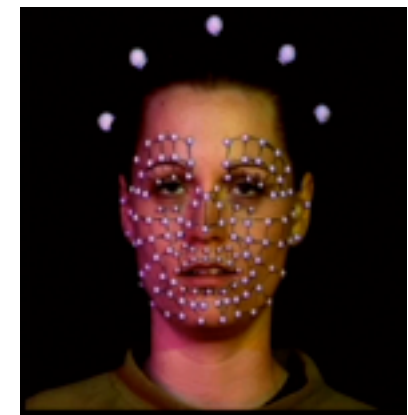
[XYZRGB '09]



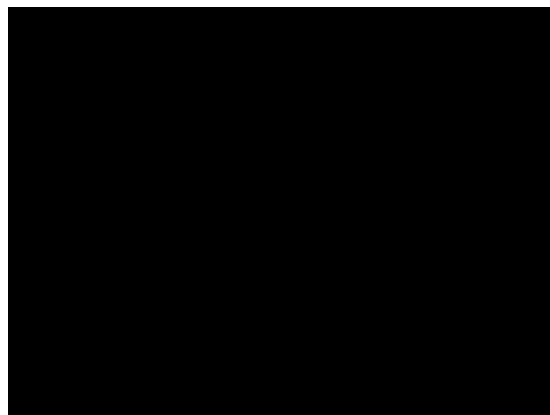
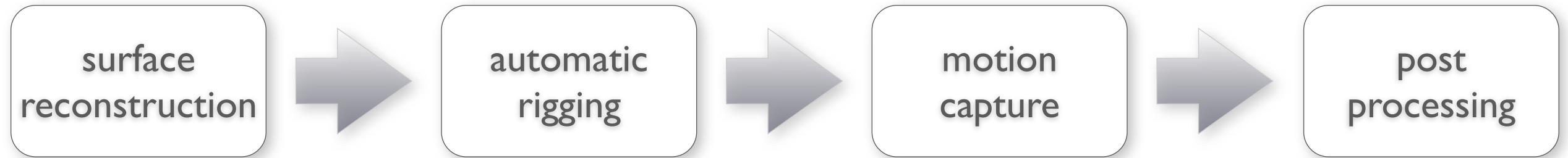
[Baran & Popović '07]



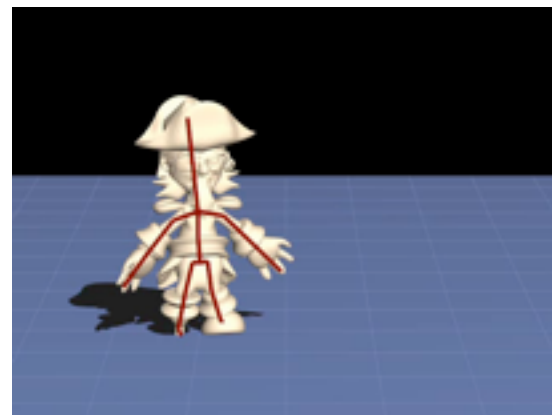
12:02:56-20
[Vicon '08]



Performance Capture



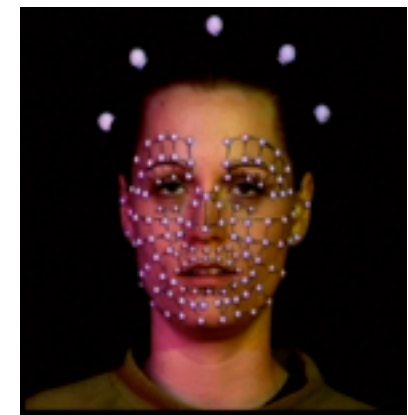
[XYZRGB '09]



[Baran & Popović '07]



[Vicon '08]



Performance Retargeting



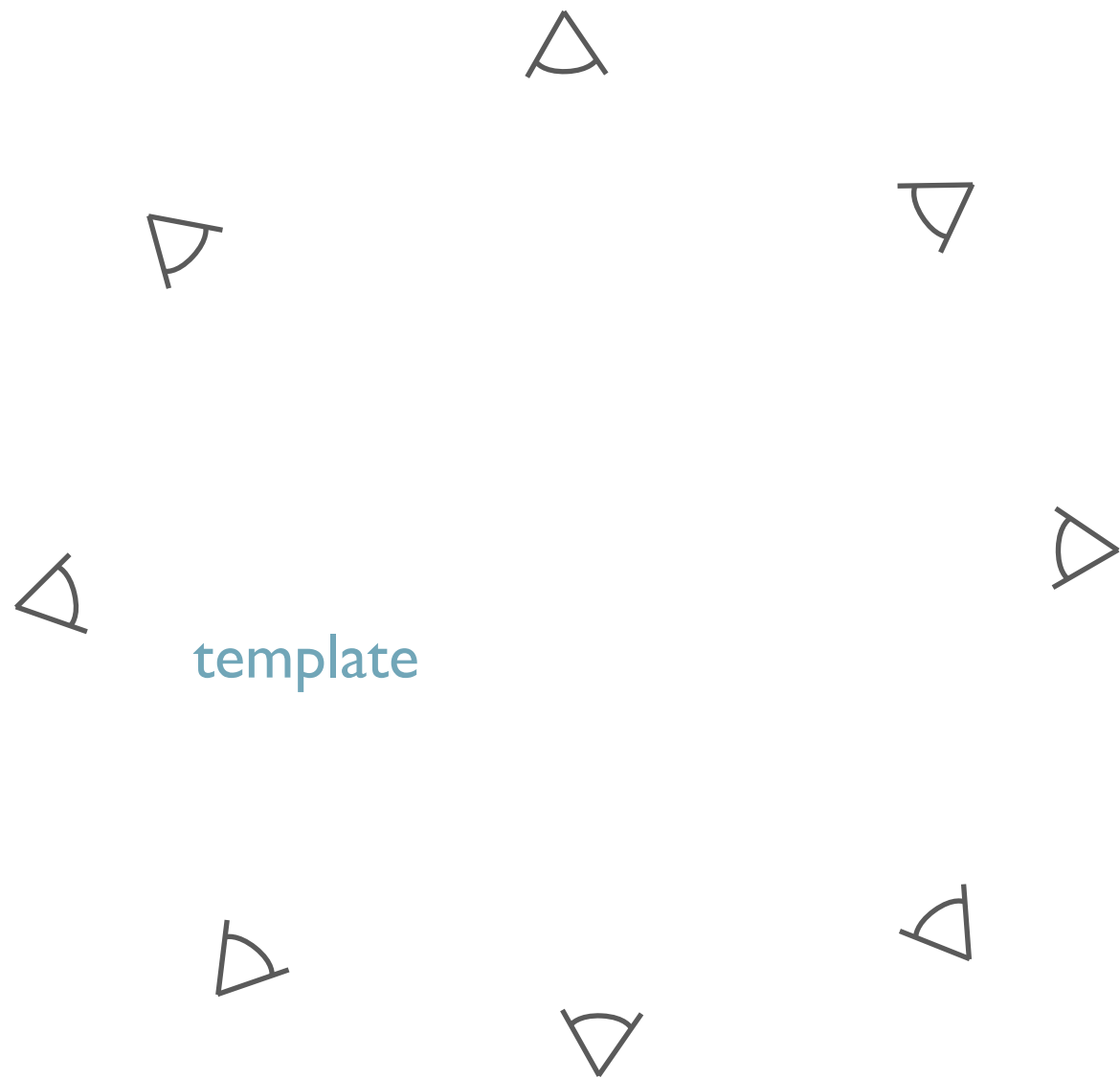
Performance Retargeting



Performance Retargeting

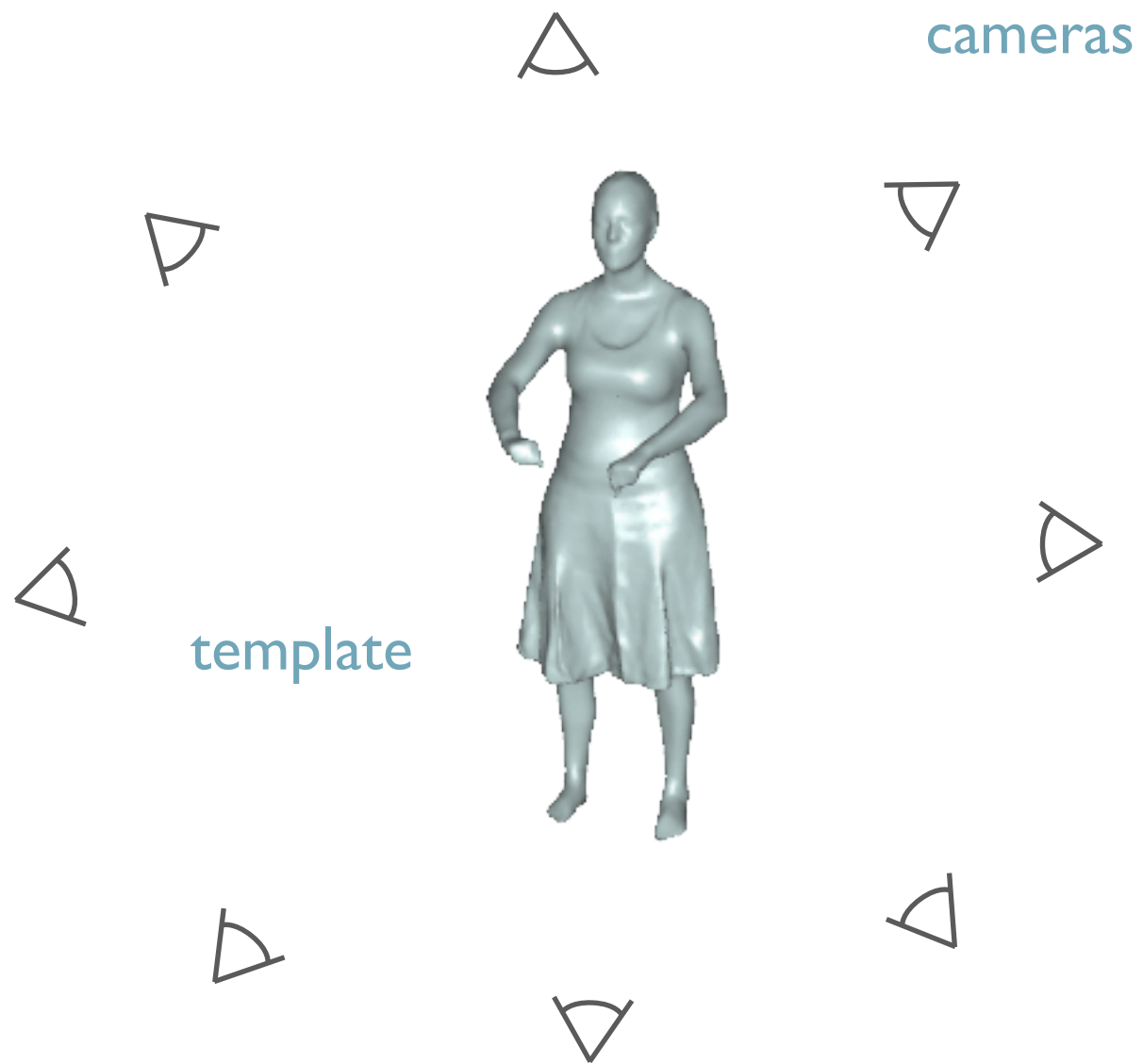


Markerless Performance Capture



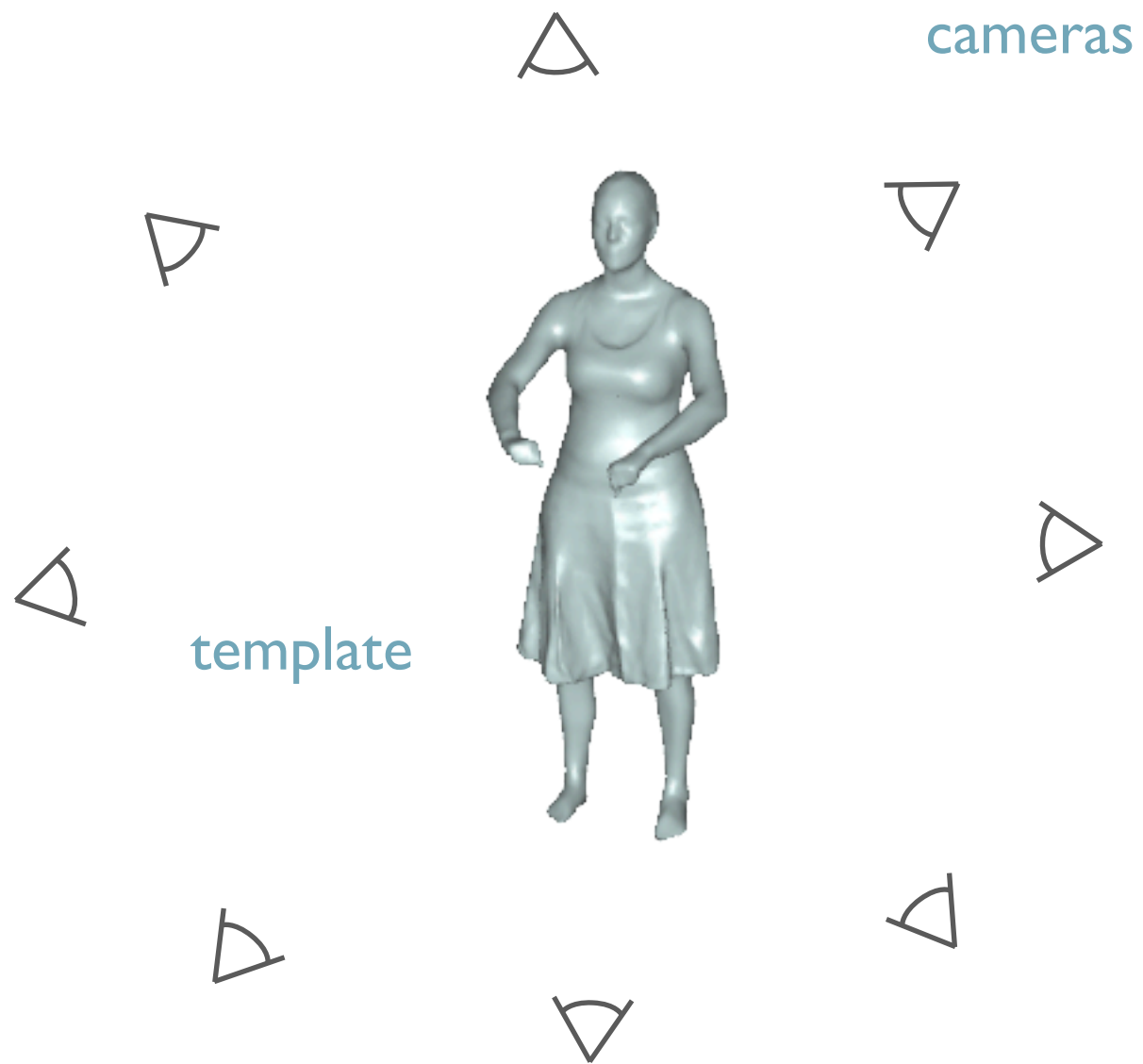
[de Aguiar et al. '08]

Markerless Performance Capture



[de Aguiar et al. '08]

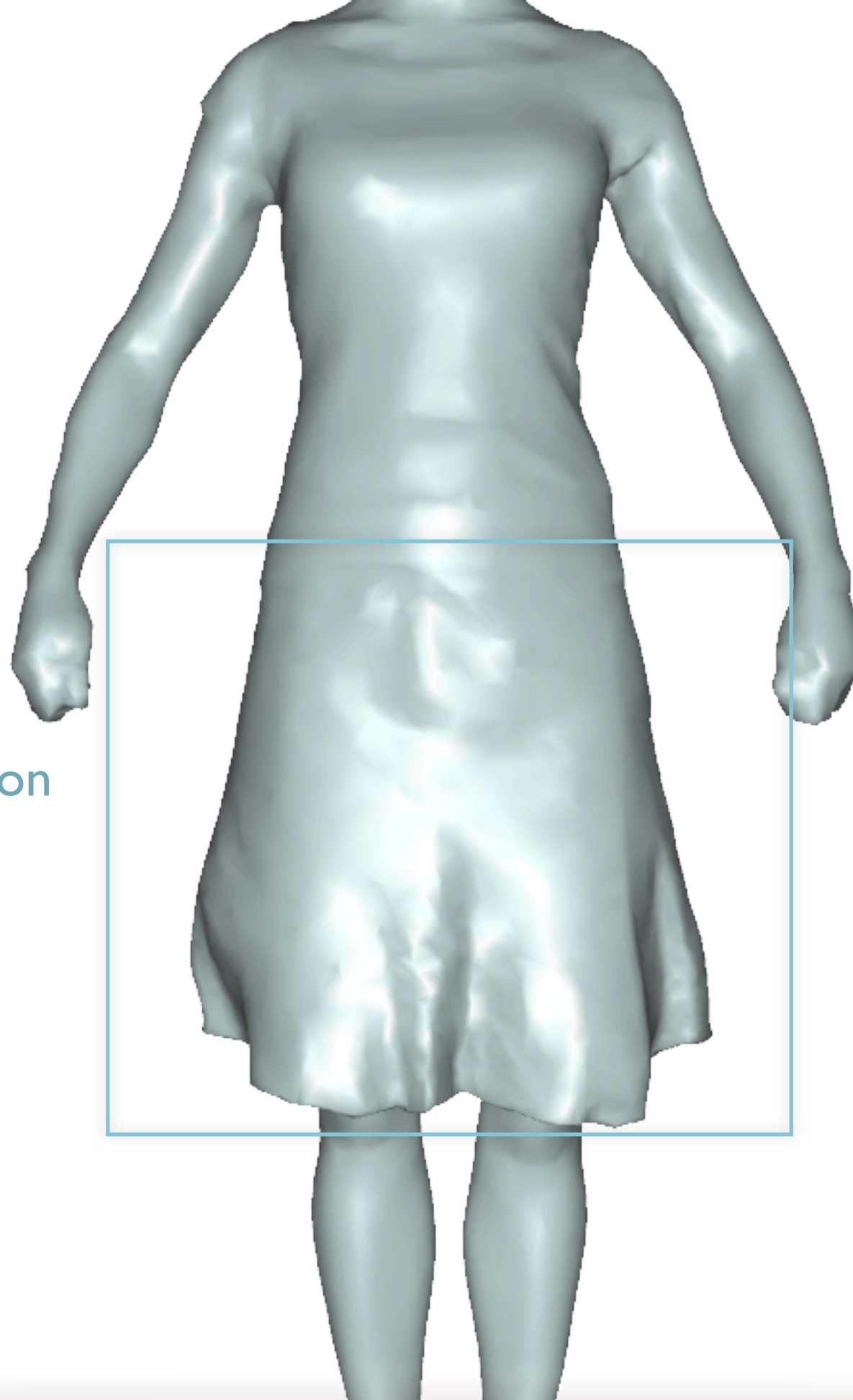
Markerless Performance Capture



[de Aguiar et al. '08]

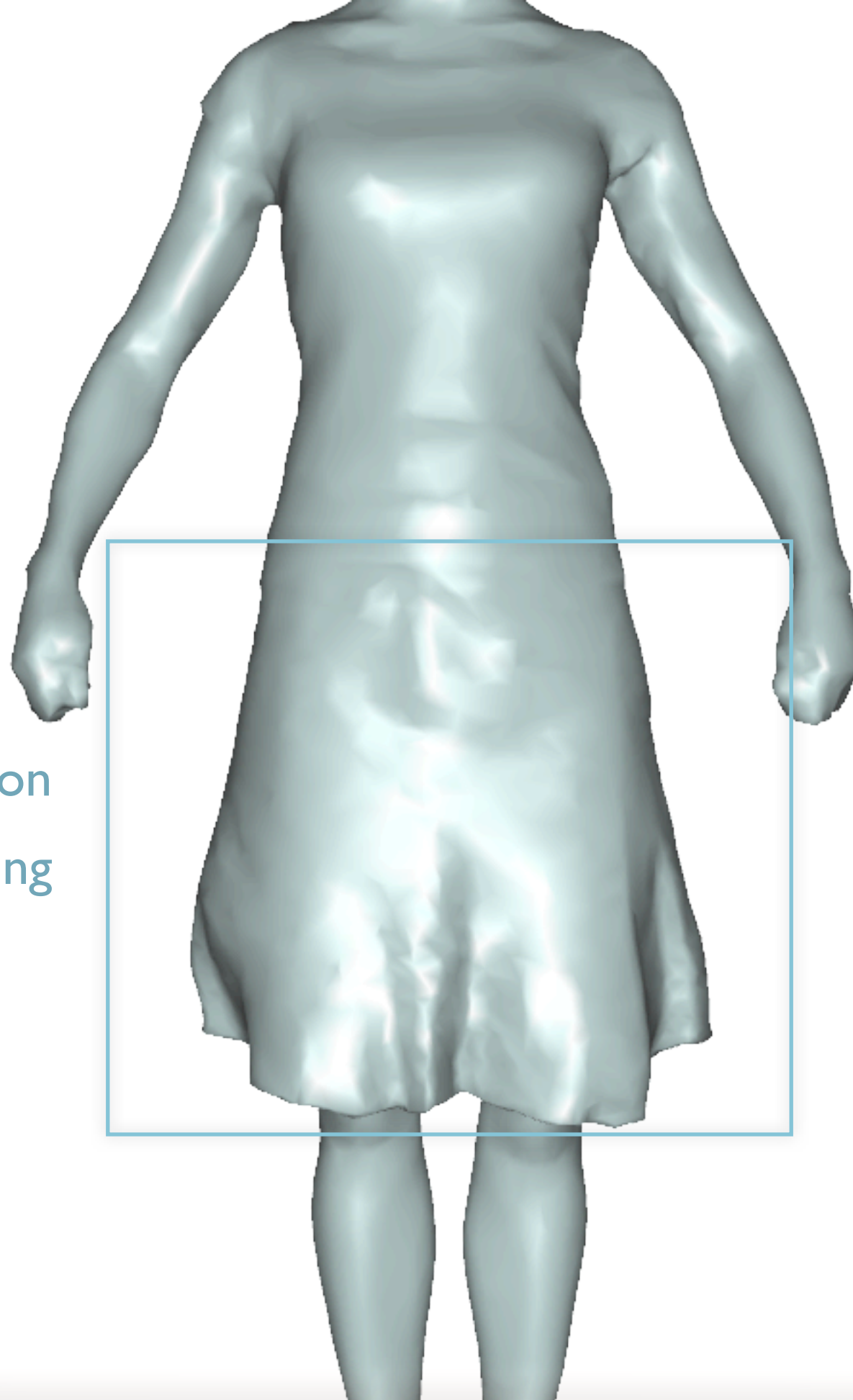


[Vlasic et al. '08]



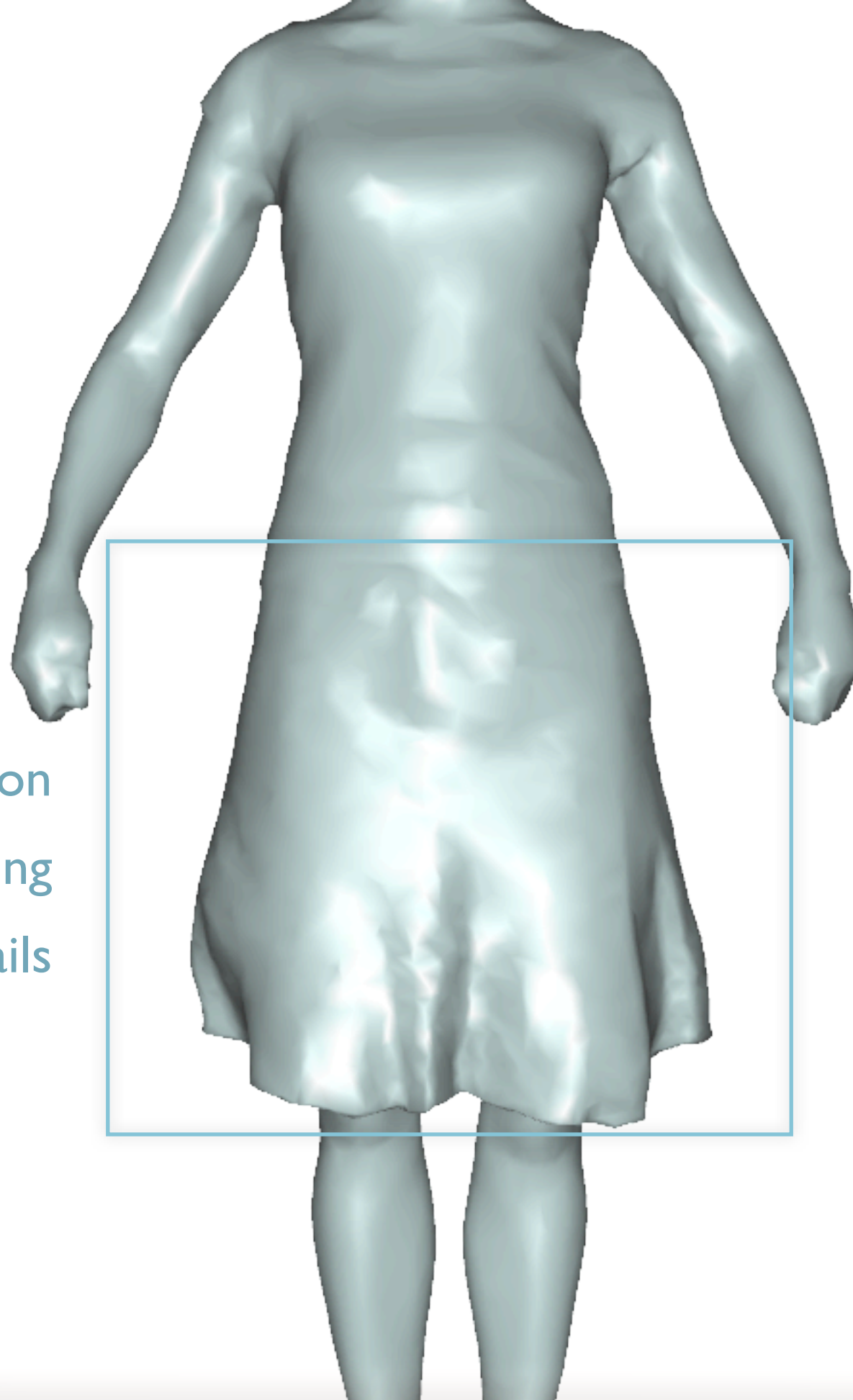
Elastic Deformation

[Vlasic et al. '08]



Elastic Deformation
Sparse Tracking

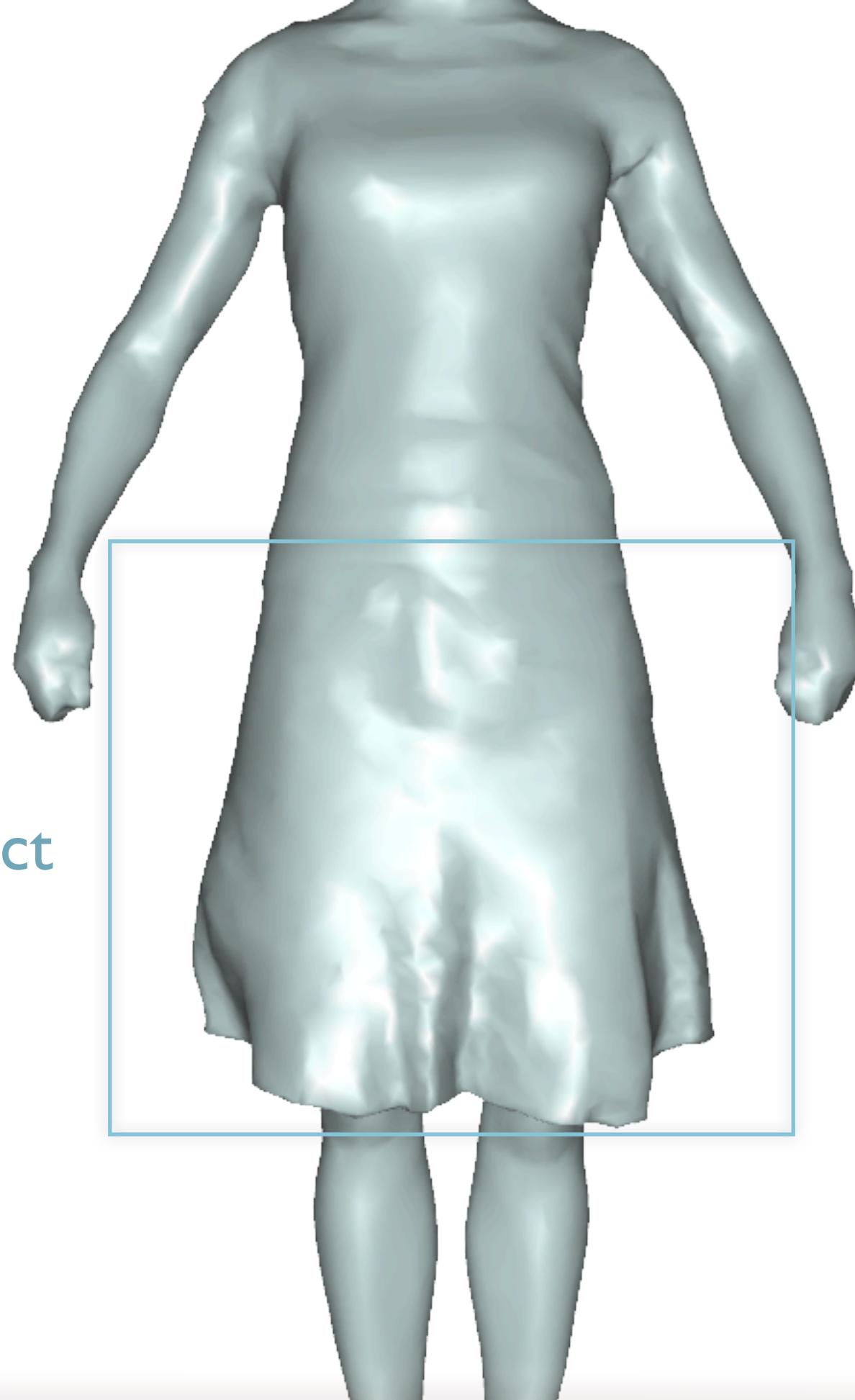
[Vlasic et al. '08]



Elastic Deformation
Sparse Tracking
Baked-in Details

[Vlasic et al. '08]

Jelly Effect

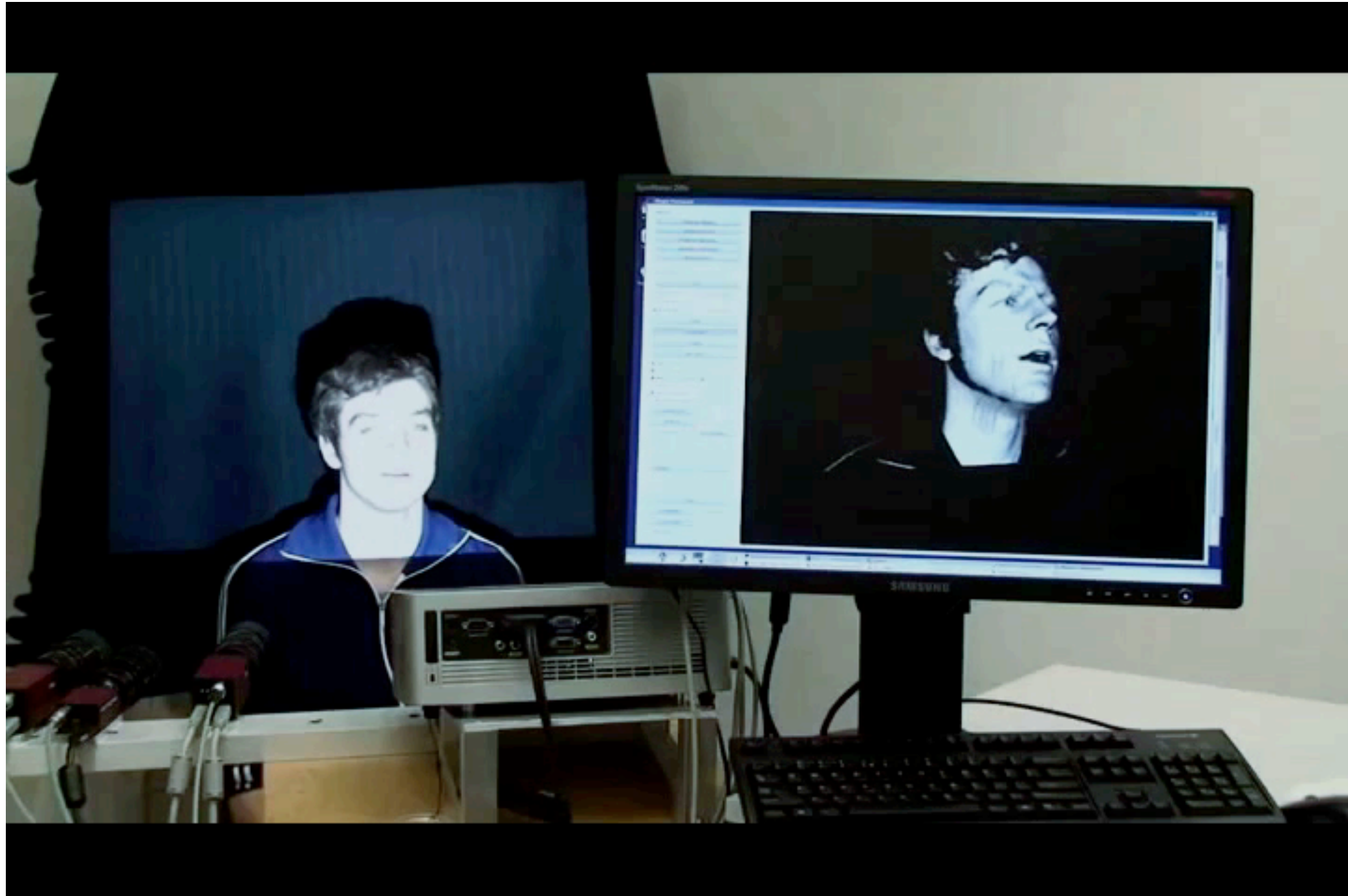


[Vlasic et al. '08]



[Vlasic et al. '08]

Real-time Dense Acquisition



Structured Light Based on Phase-Shift Stereo [Weise et al. '07]

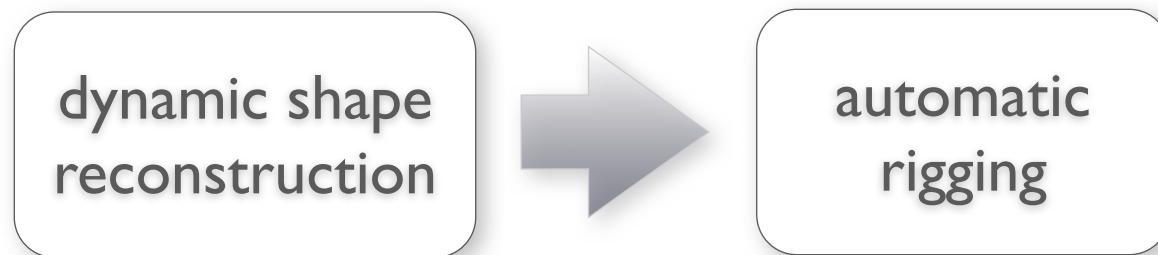
Animation Reconstruction



Animation Reconstruction



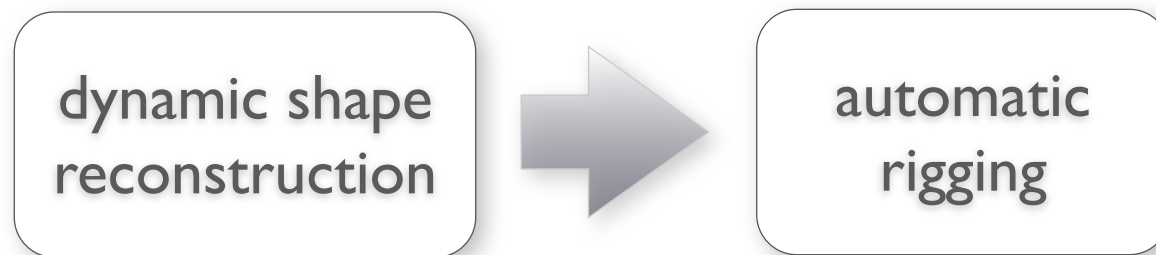
Animation Reconstruction



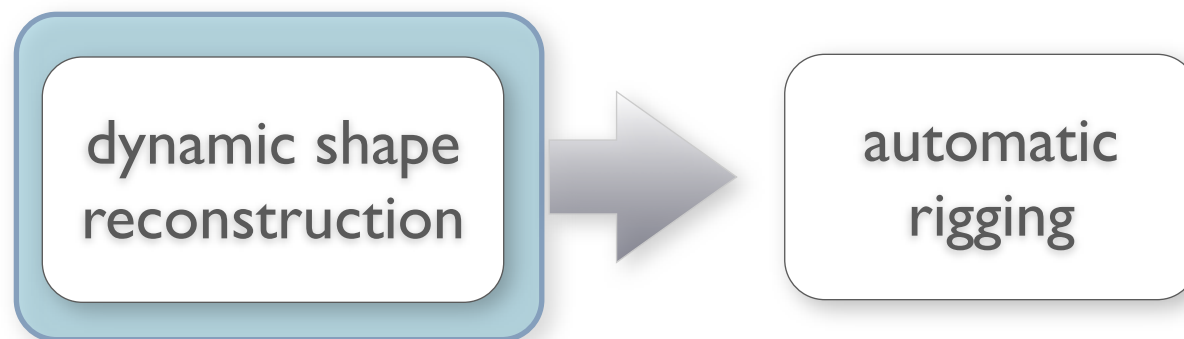
Animation Reconstruction



Animation Reconstruction



Animation Reconstruction



Objective

[Li et al. '09]



Input 3D Scan Sequence



Space-time Reconstruction

Challenges



Challenges



Challenges



Correspondence Issues

[Süssmuth et al. '08]



Challenges



Correspondence Issues

[Süssmuth et al. '08]



Topology Issues

[Wand et al. '09]



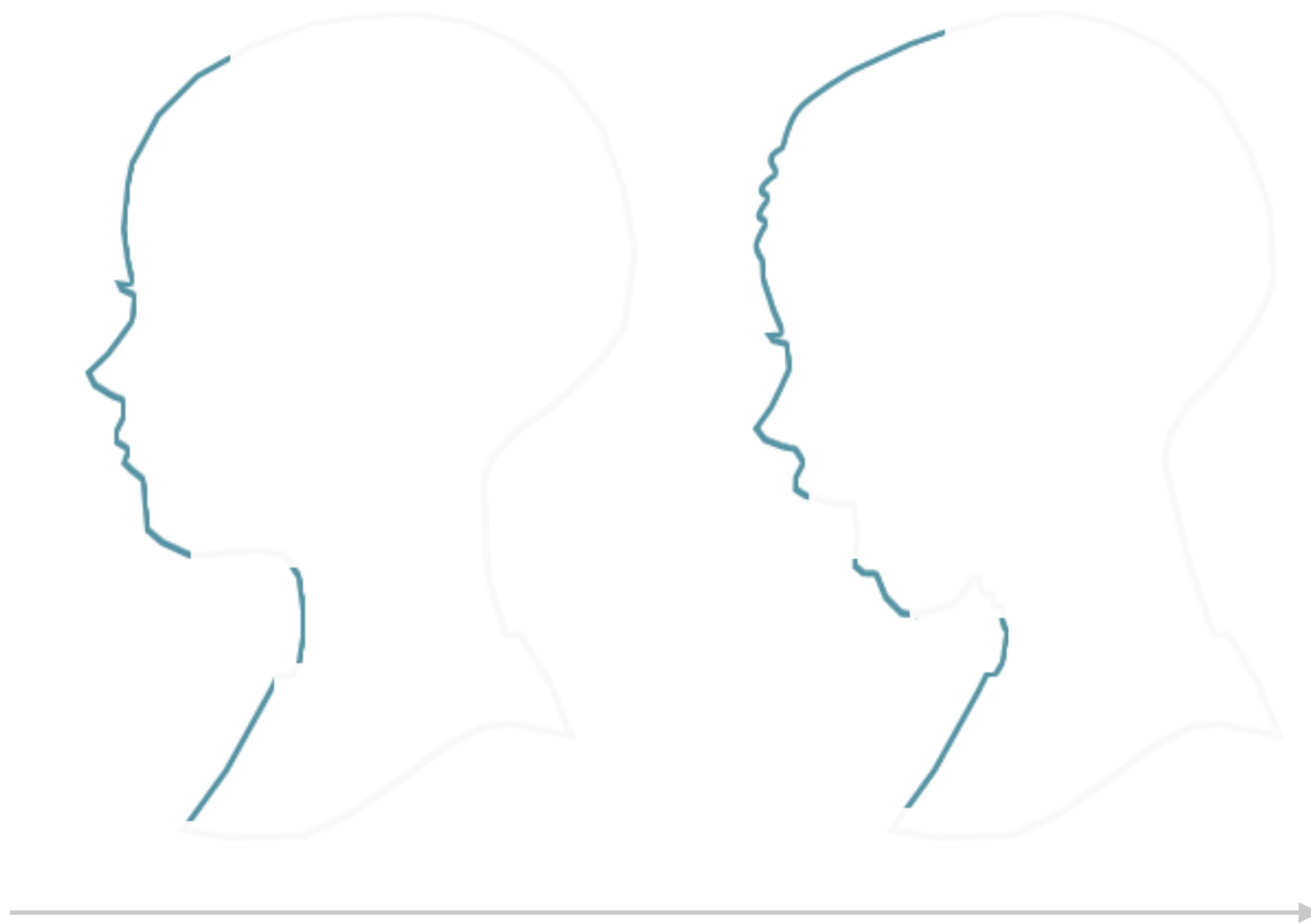
Deforming Physical Subject



Partial Scans



Partial and Non-Rigid Registration



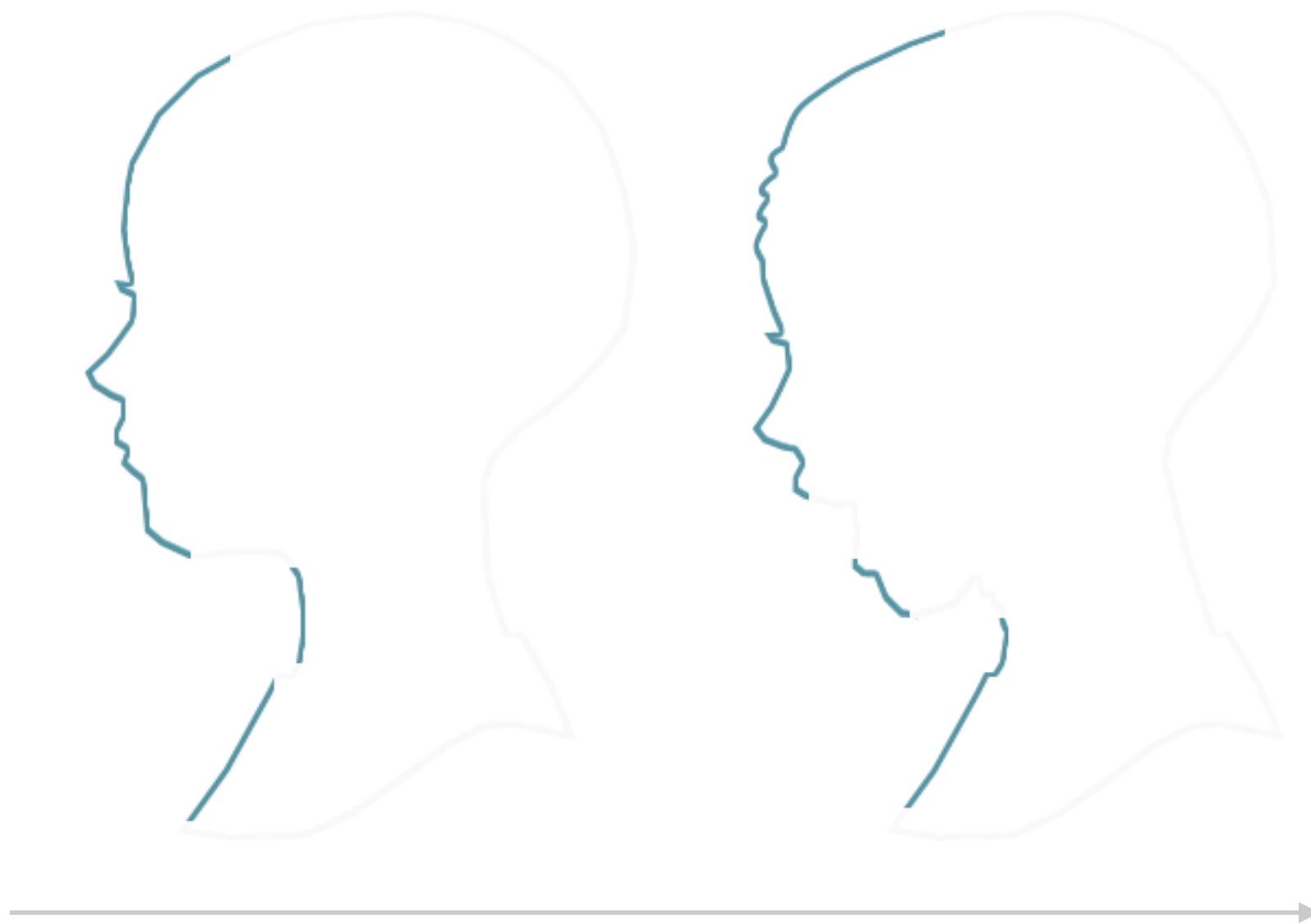
Partial and Non-Rigid Registration



Partial and Non-Rigid Registration



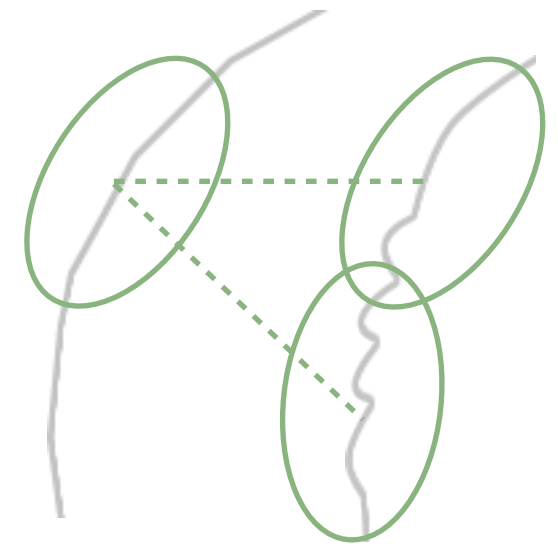
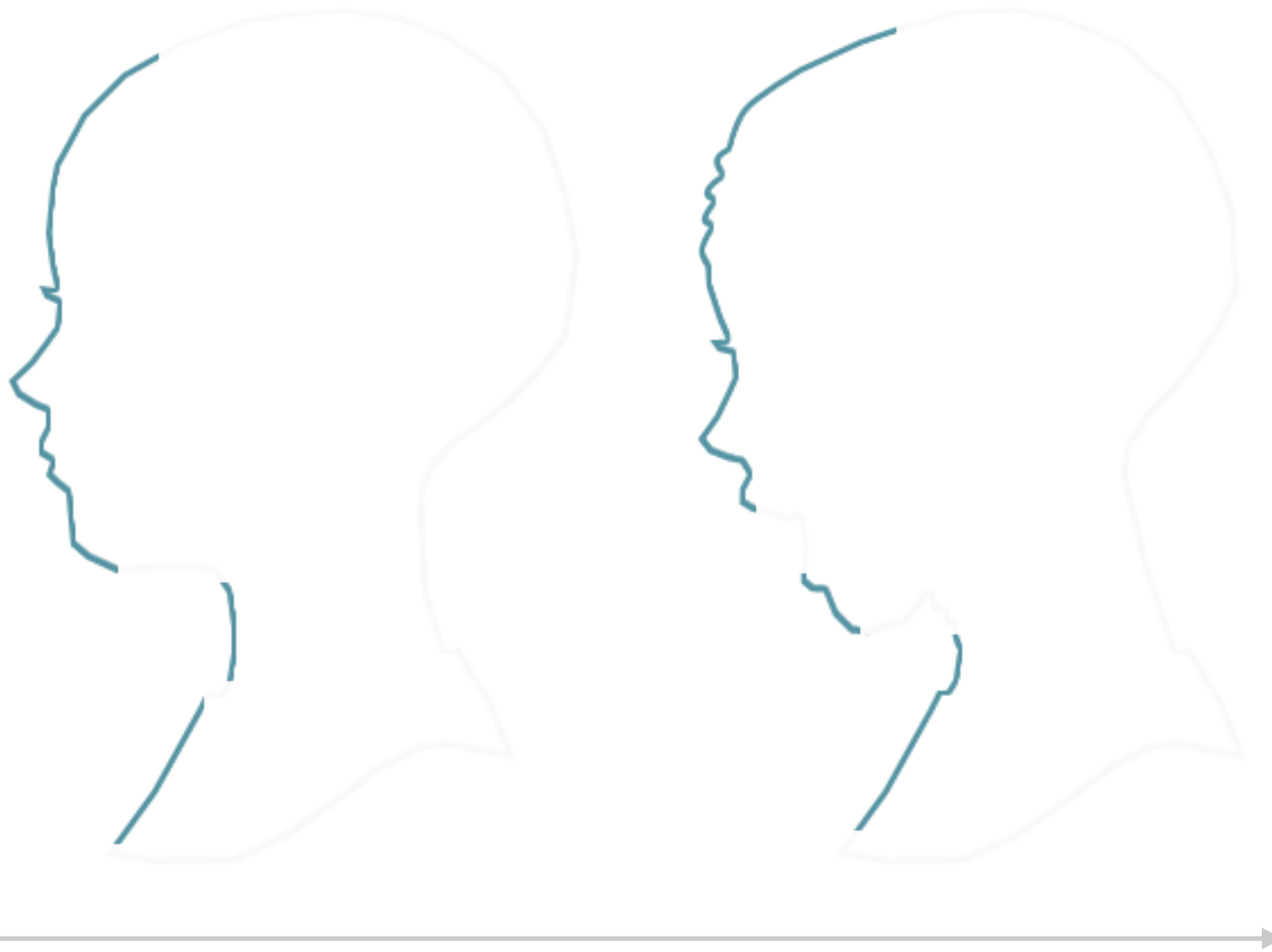
Partial and Non-Rigid Registration



Partial and Non-Rigid Registration



Partial and Non-Rigid Registration



Small-Scale Dynamics



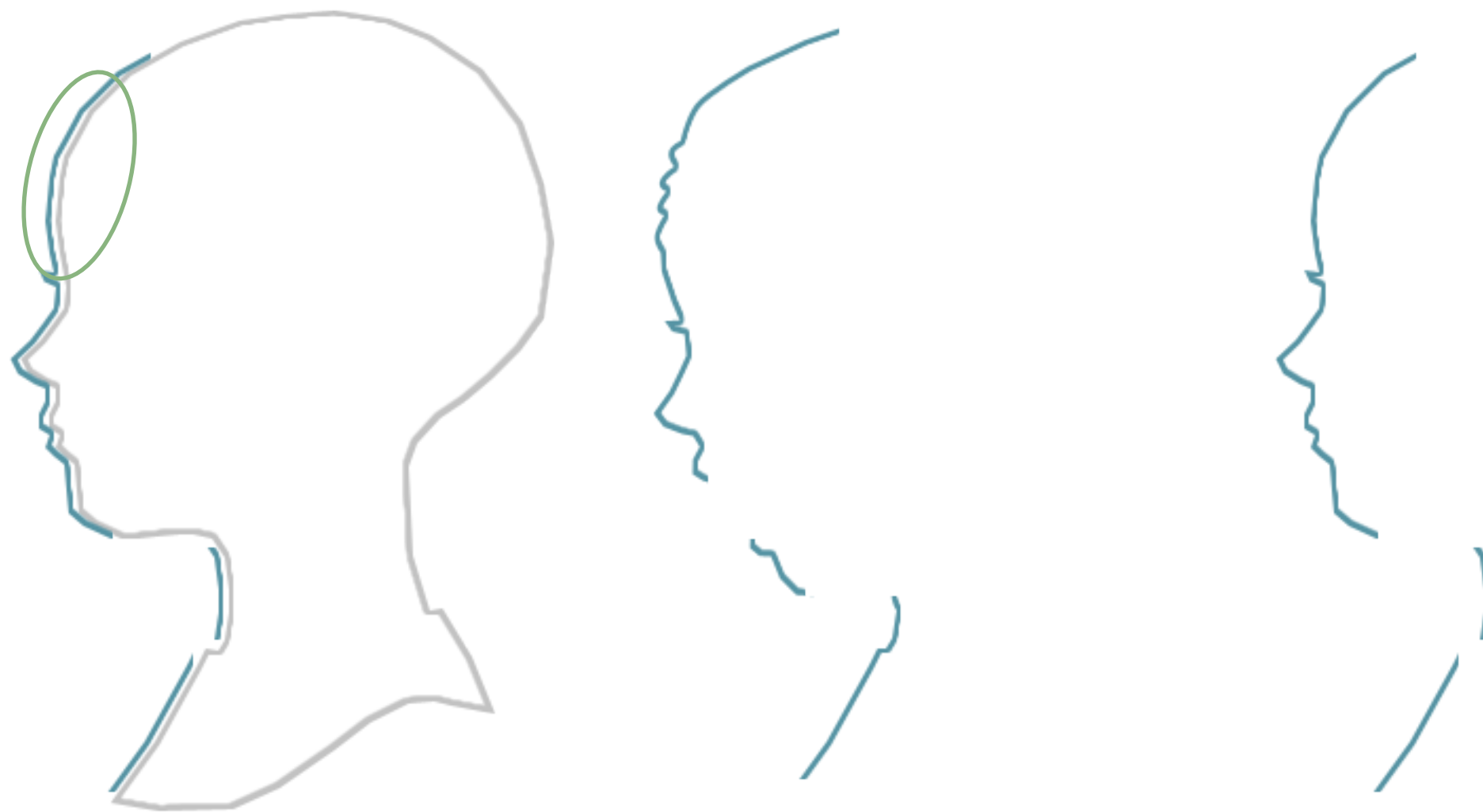
Bi-Resolution Approach



Warping a **coarse** template

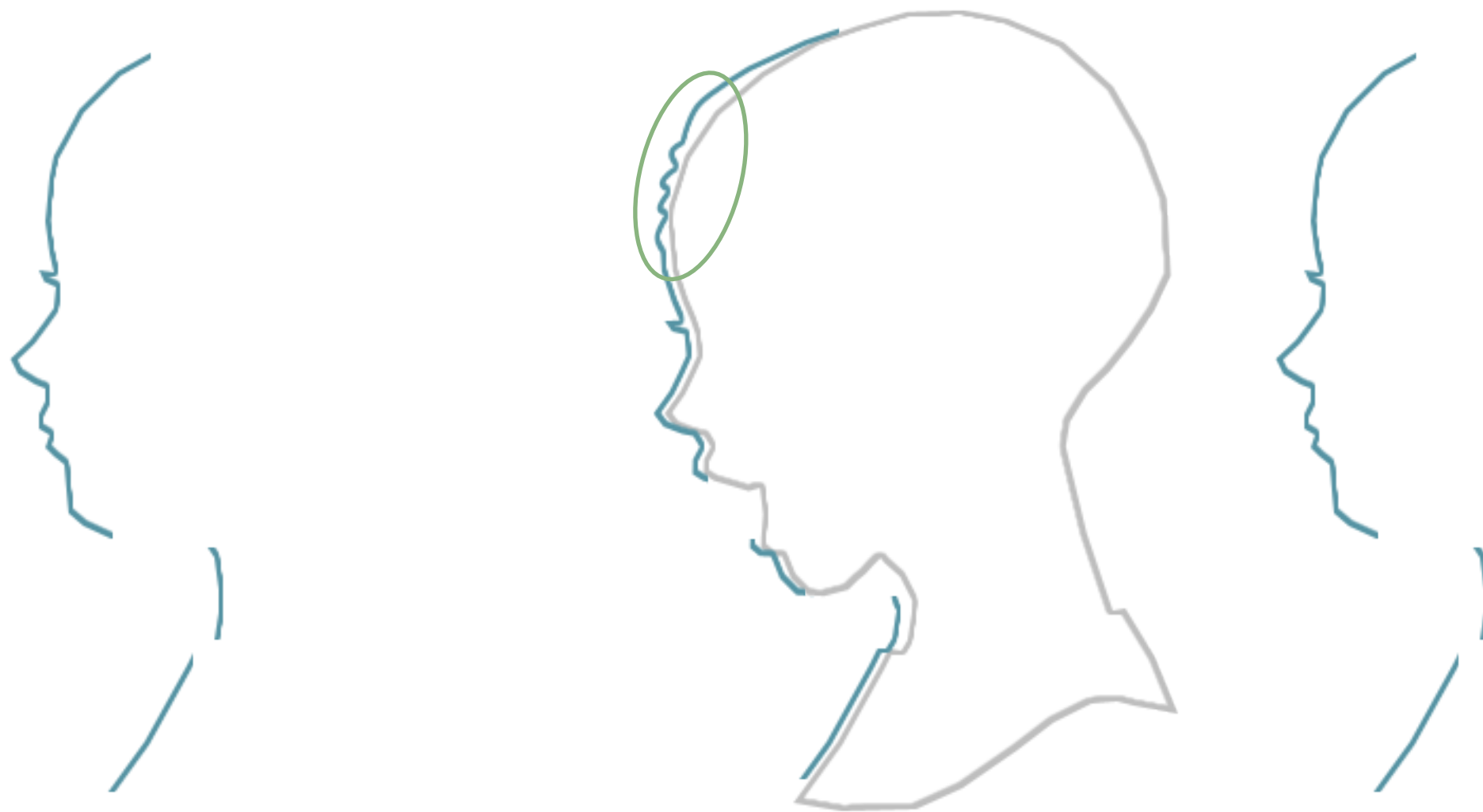


Bi-Resolution Approach



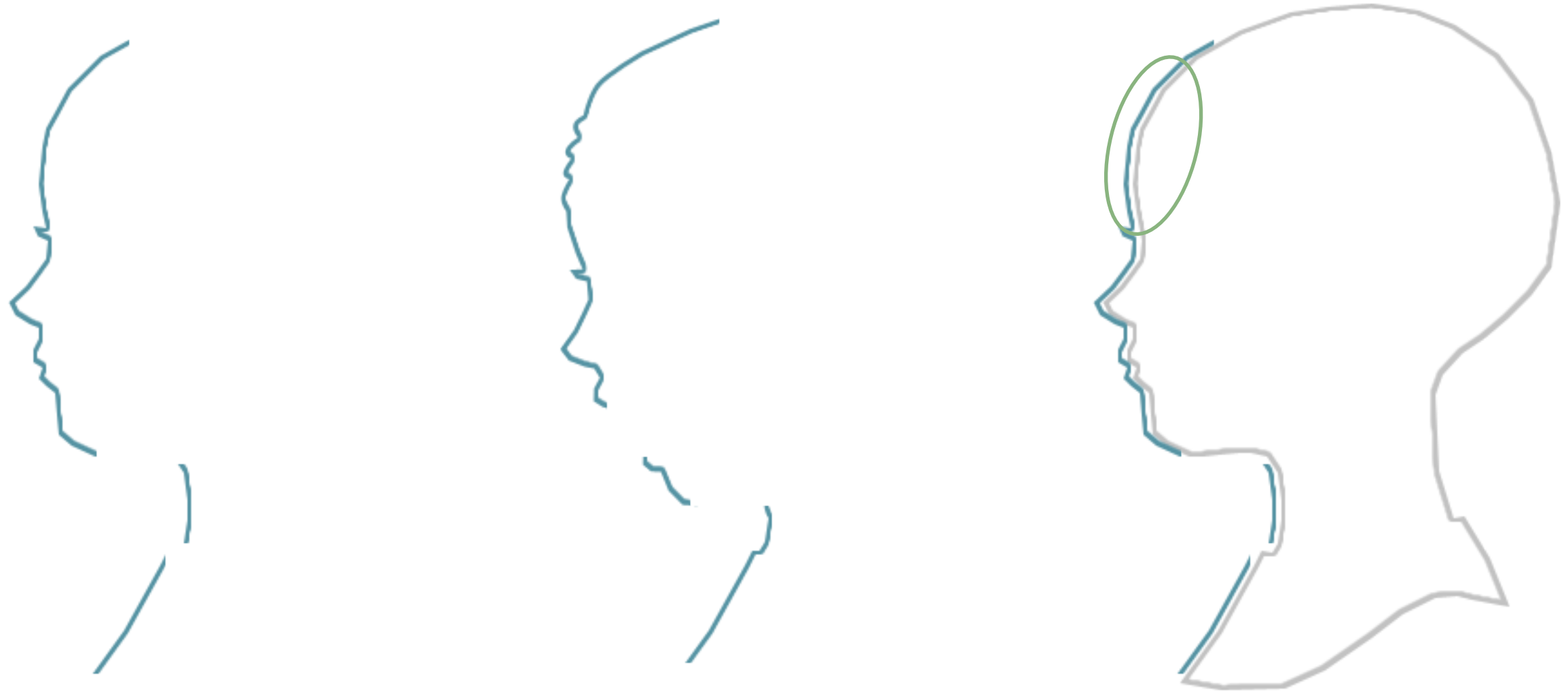
Warping a **coarse** template

Bi-Resolution Approach



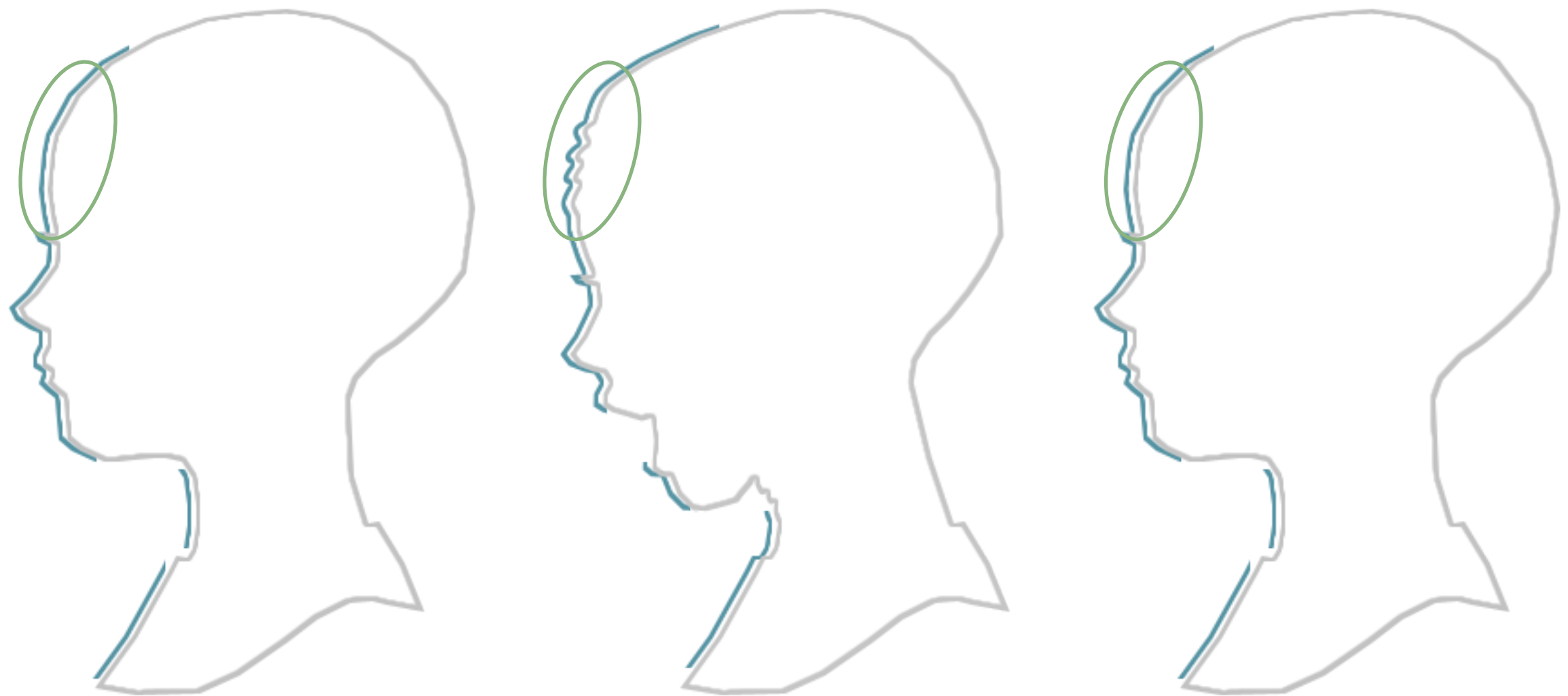
Warping a **coarse** template

Bi-Resolution Approach



Warping a **coarse** template

Bi-Resolution Approach



Synthesizing **small scale** details

Reconstruction Framework



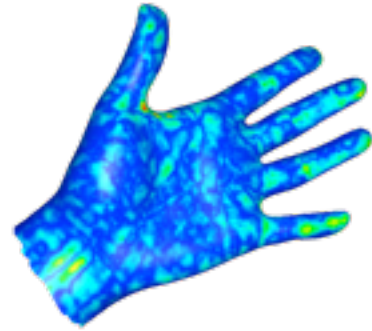
Reconstruction Framework



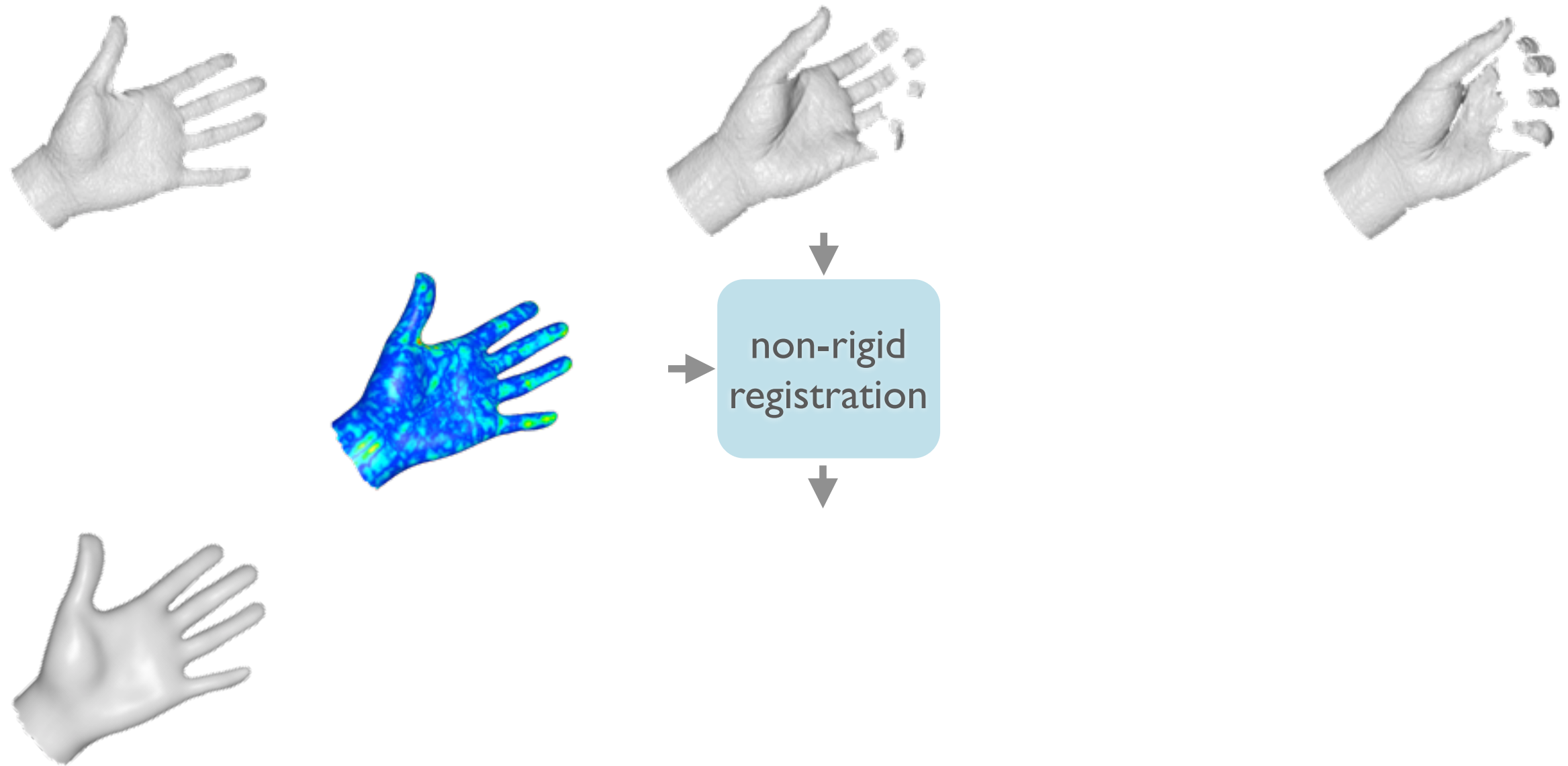
Reconstruction Framework



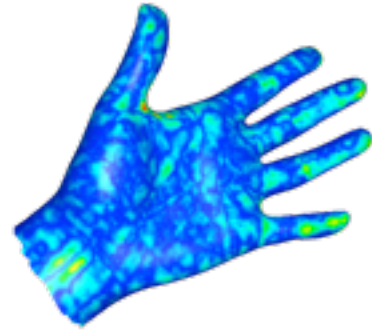
Reconstruction Framework



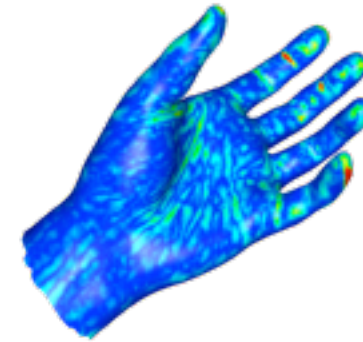
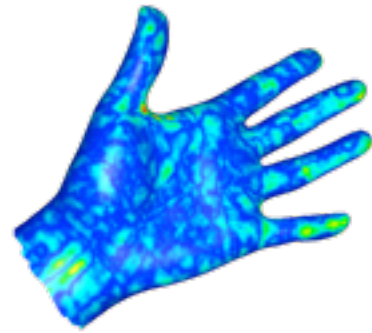
Reconstruction Framework



Reconstruction Framework



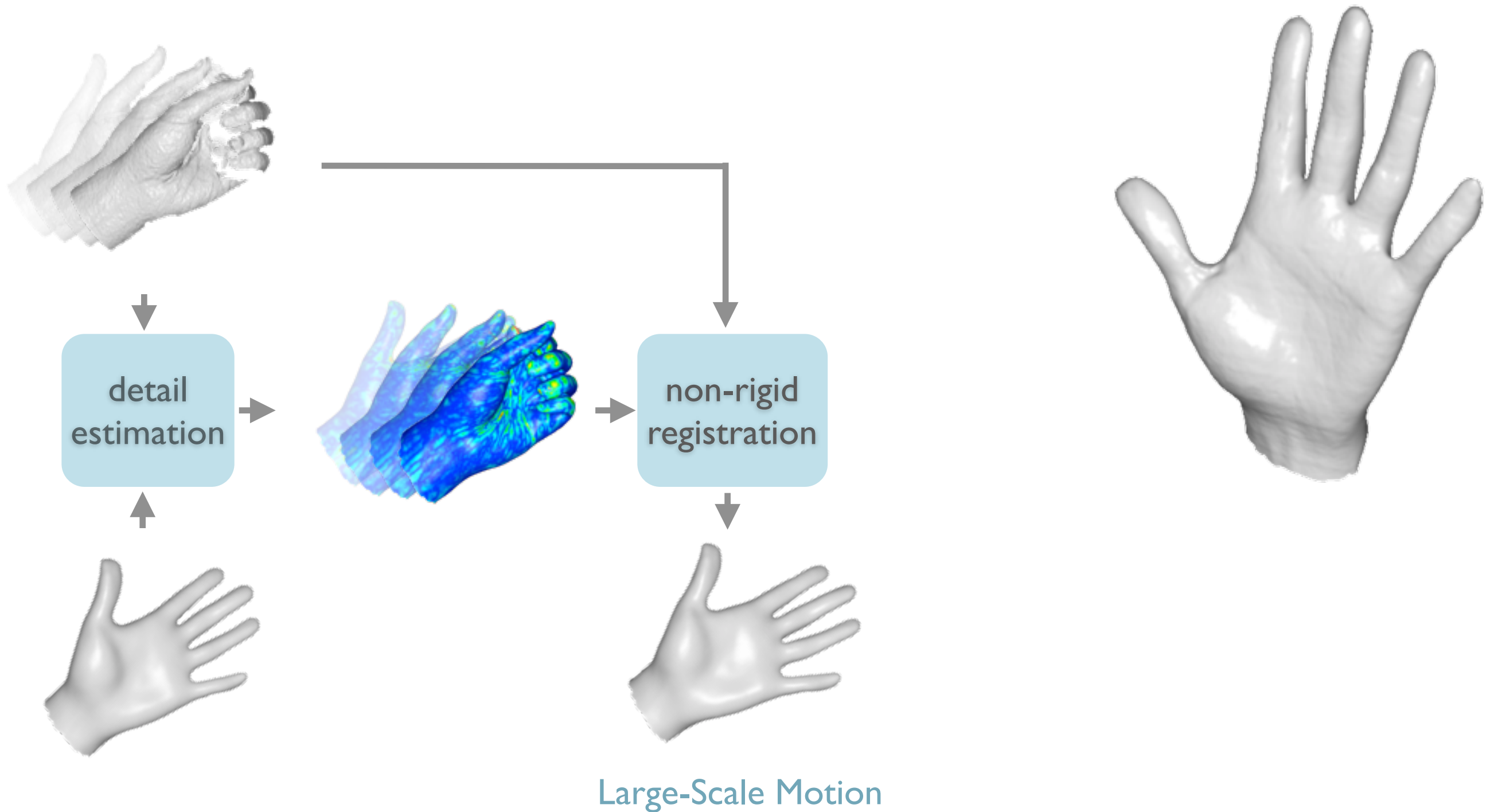
Reconstruction Framework



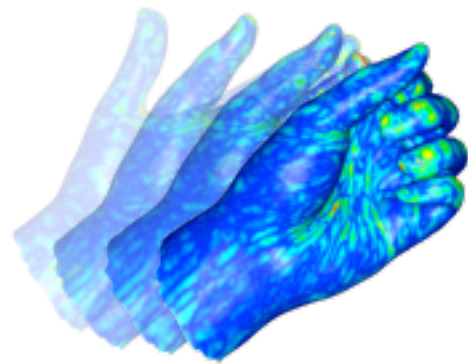
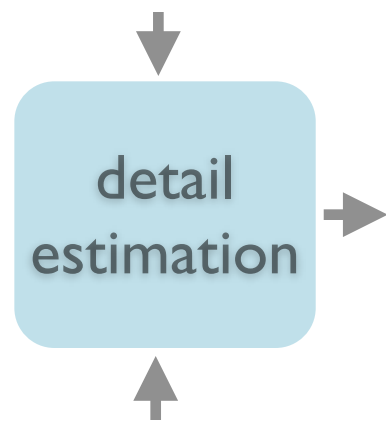
Reconstruction Framework



Reconstruction Framework



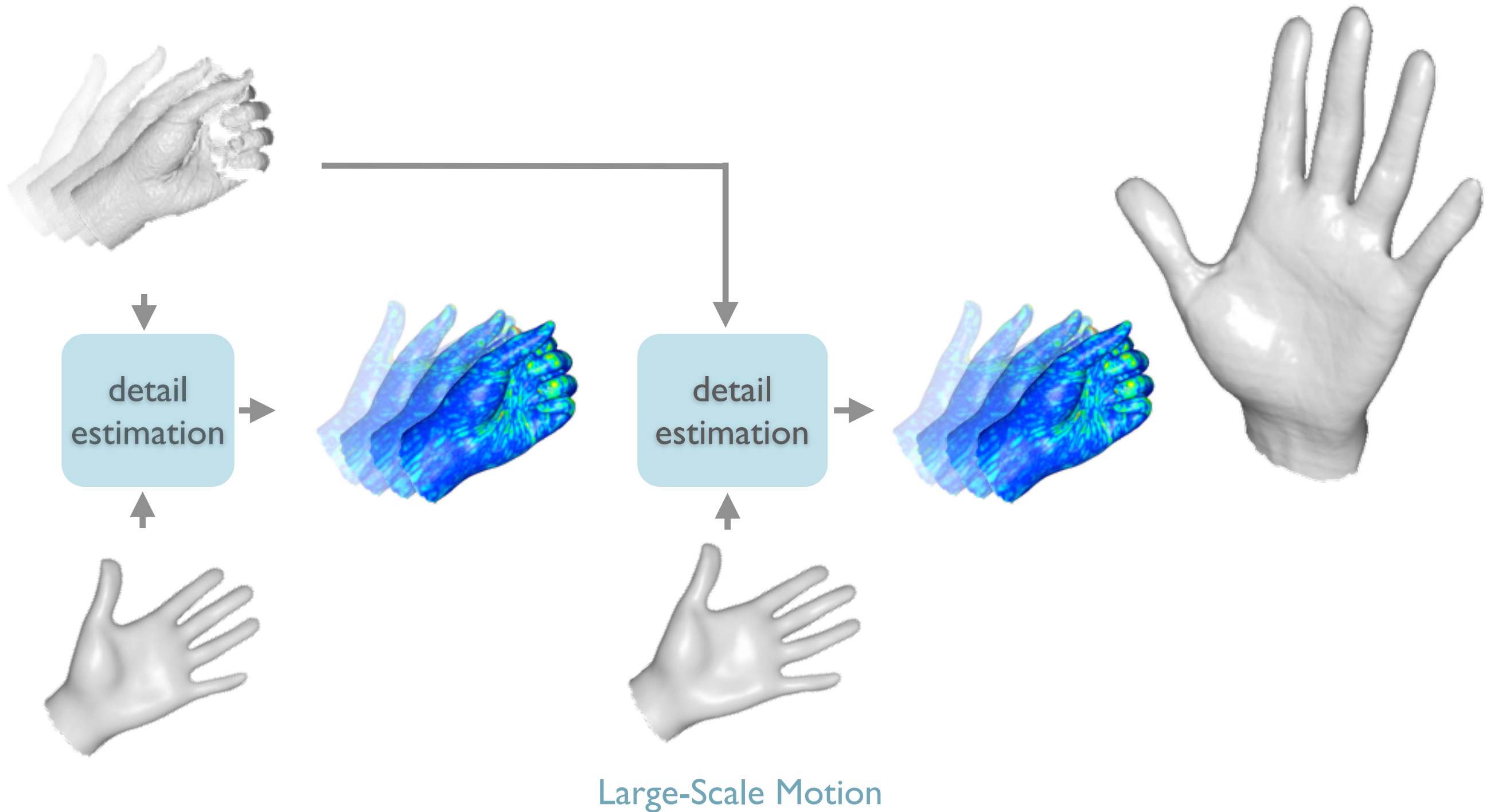
Reconstruction Framework



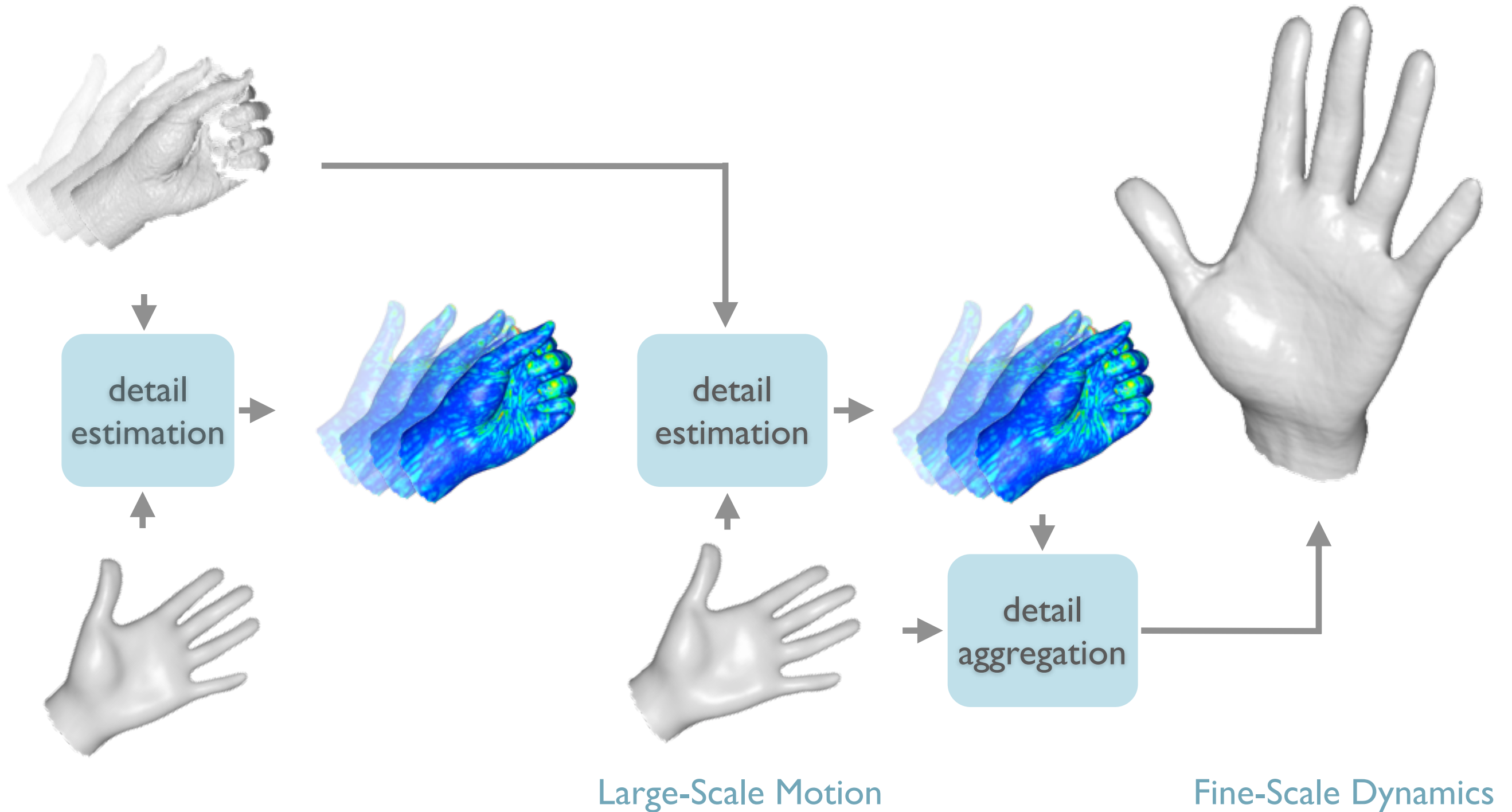
Large-Scale Motion



Reconstruction Framework



Reconstruction Framework



Sequential Non-Rigid Registration

input data



data provided by Stanford and MPI Saarbrücken

Sequential Non-Rigid Registration

input data

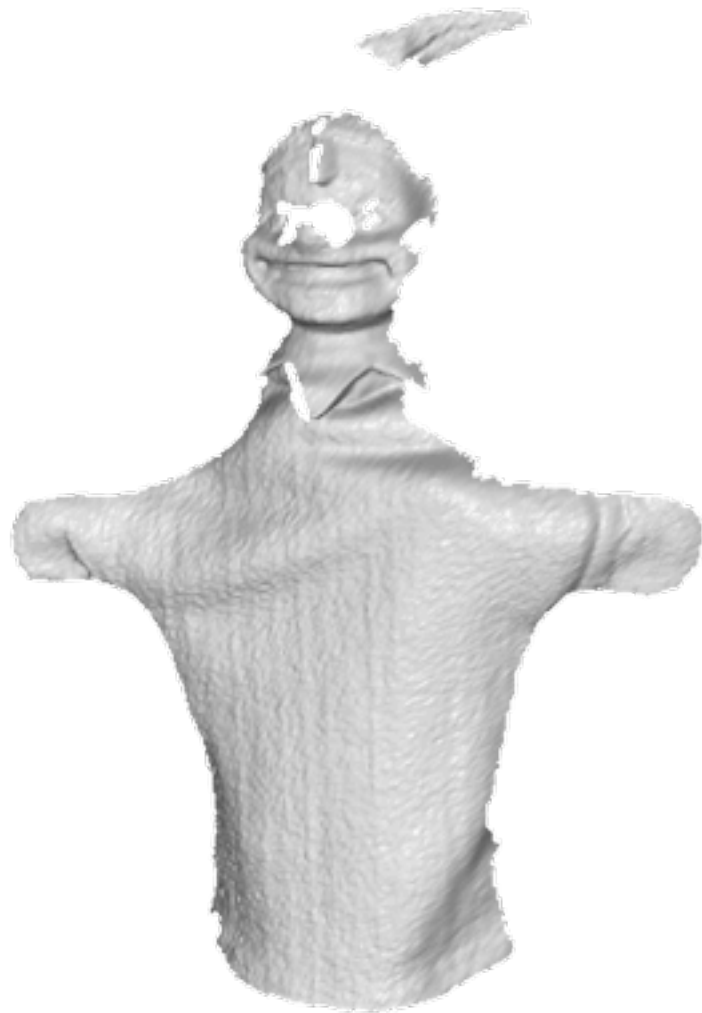


template fitting

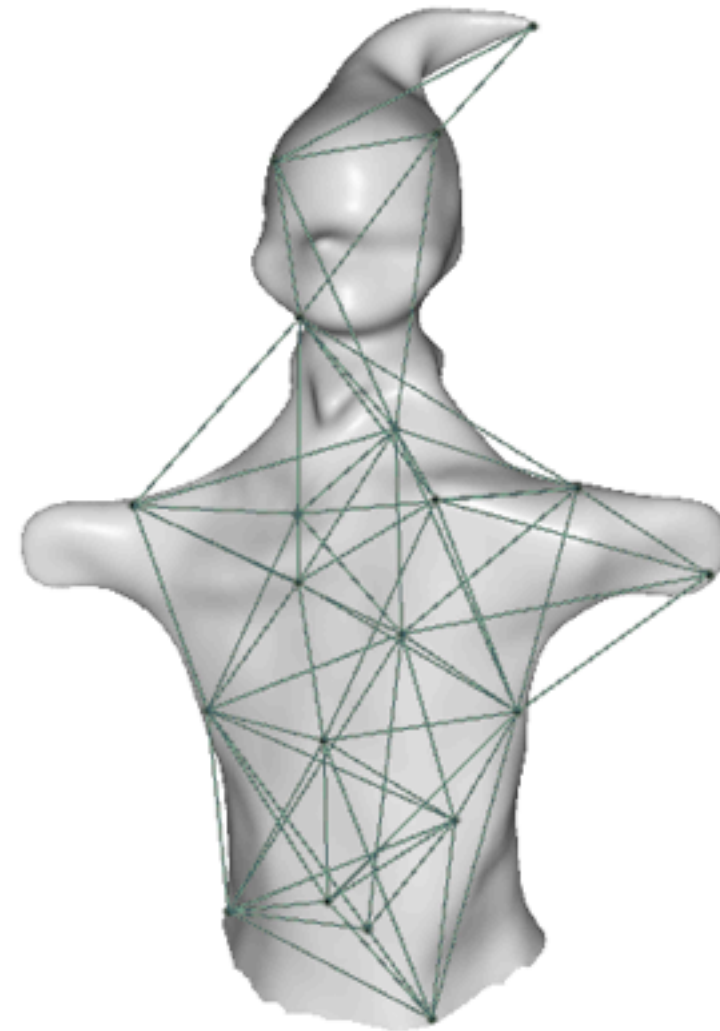


data provided by Stanford and MPI Saarbrücken

Adaptive Deformation Model



Input Scans



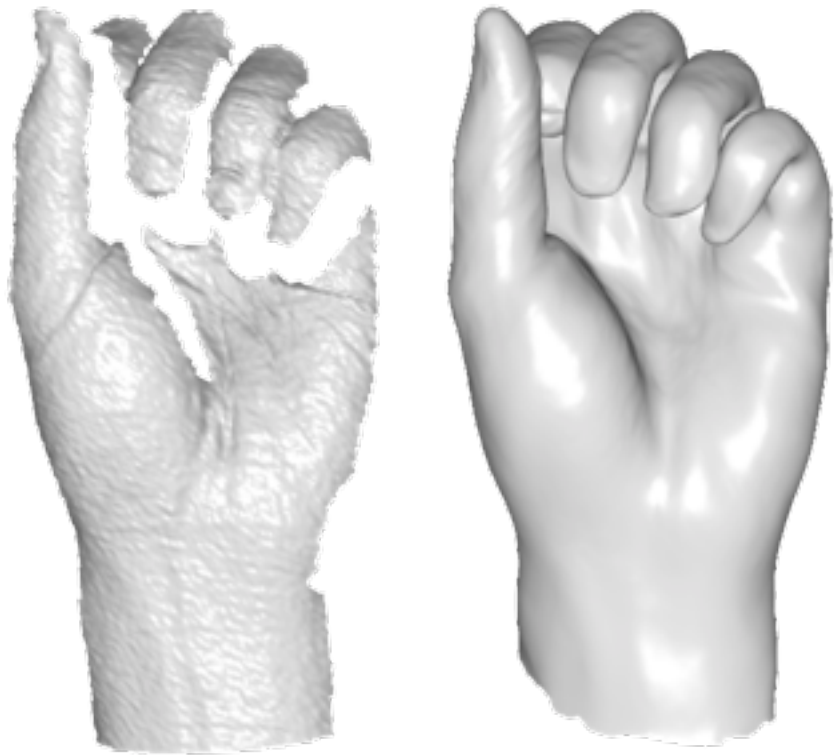
Warped Template with Graph



Detail Aggregation



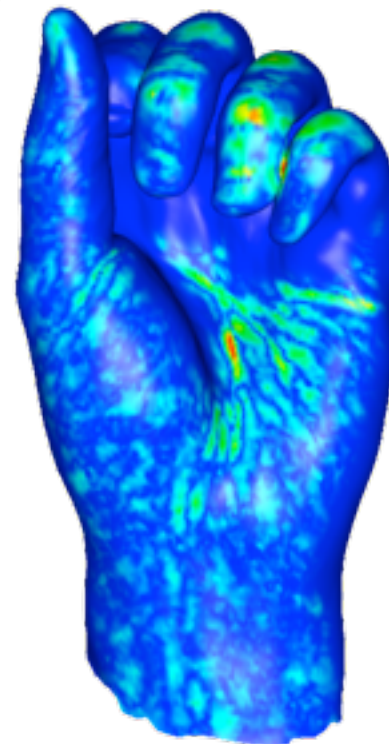
Detail Aggregation



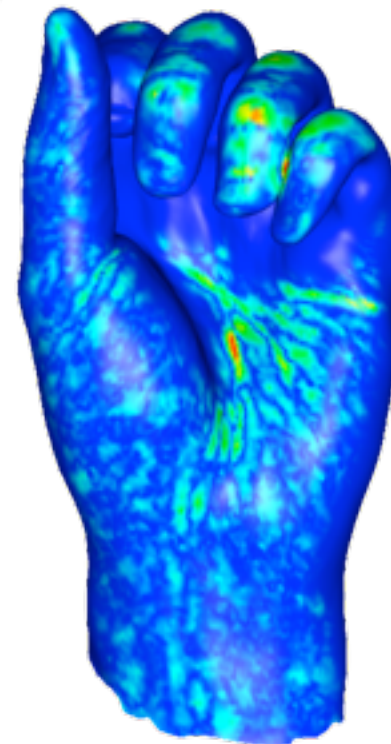
Detail Aggregation



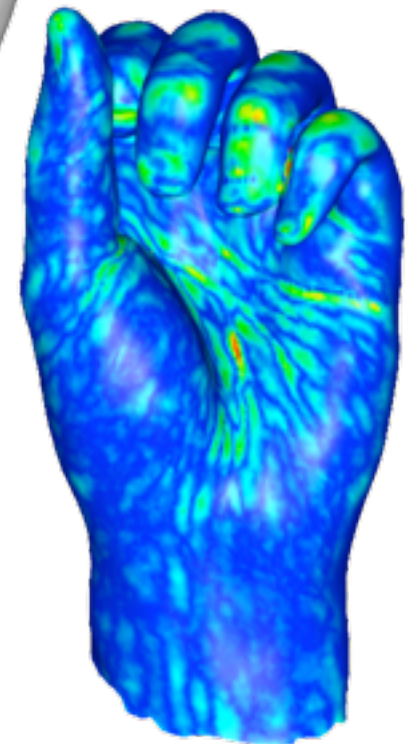
Single Frame
Synthesis



Detail Aggregation



Single Frame
Synthesis

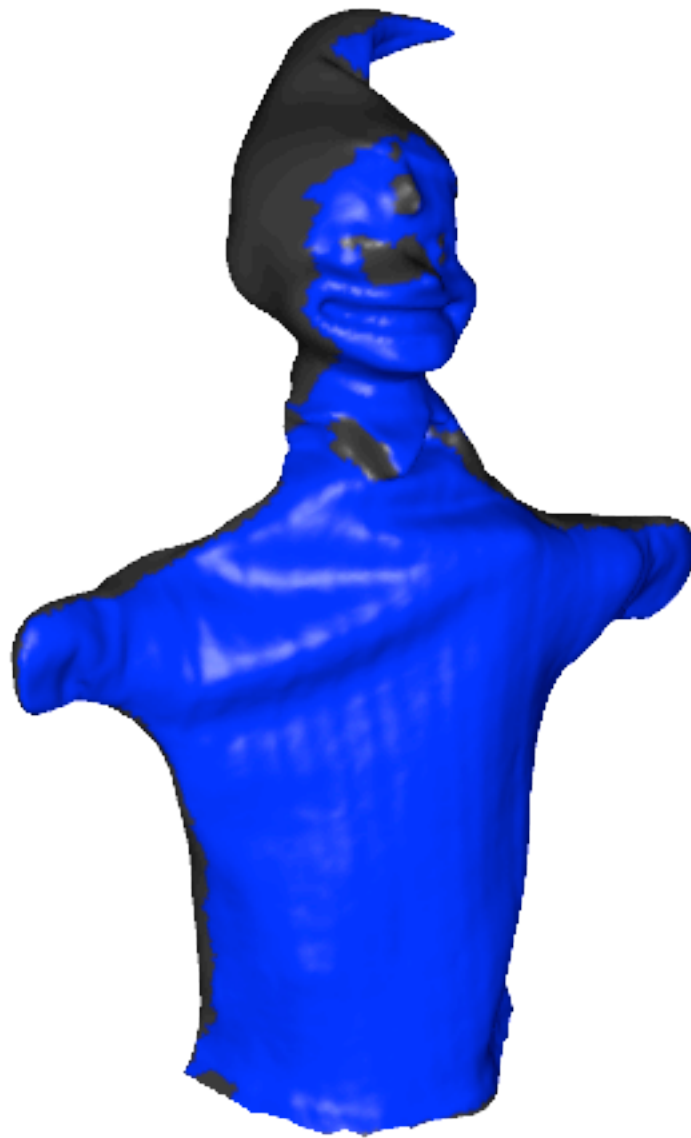


Multi-Frame
Aggregation

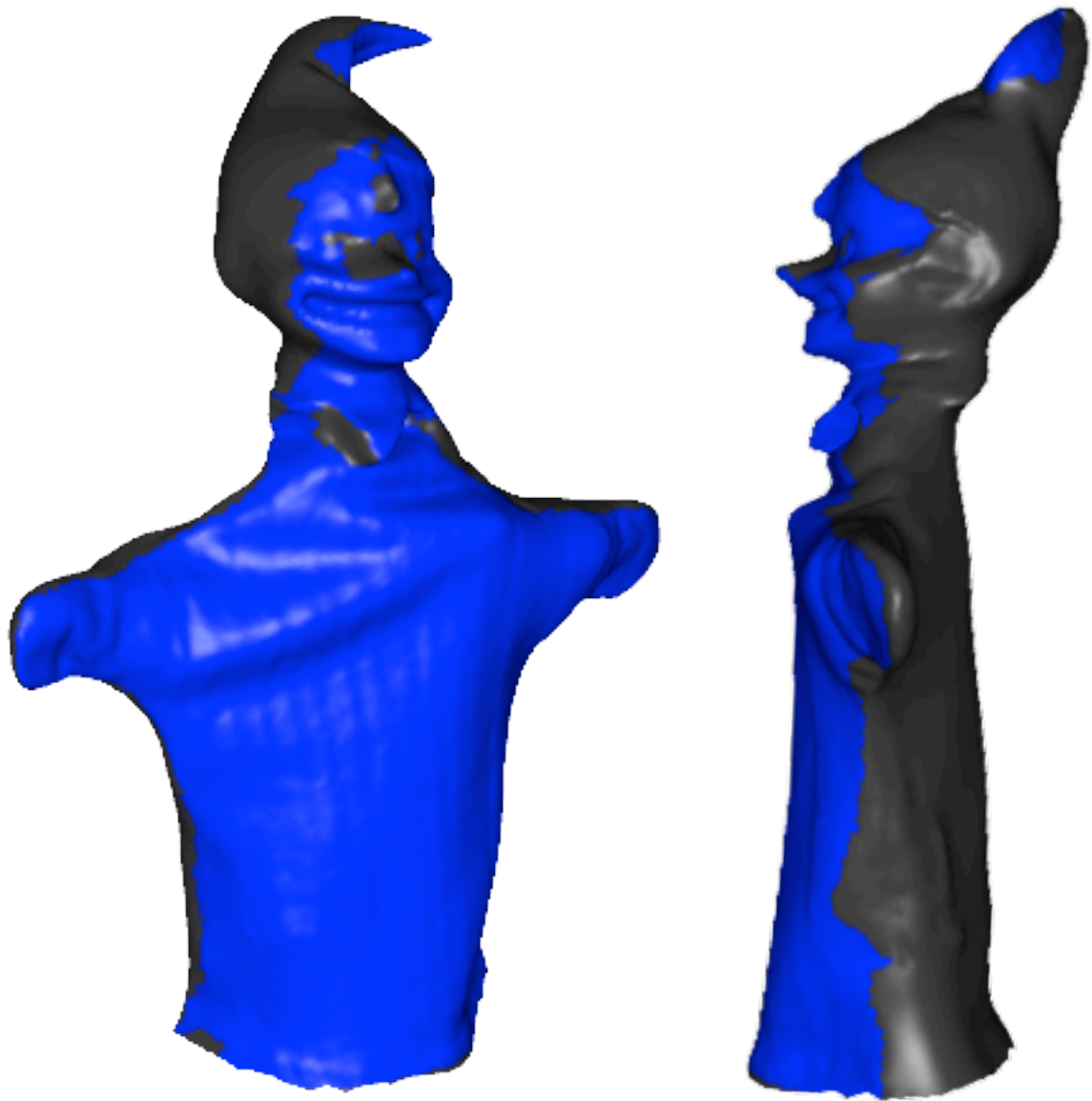
Forward-Backward Pass



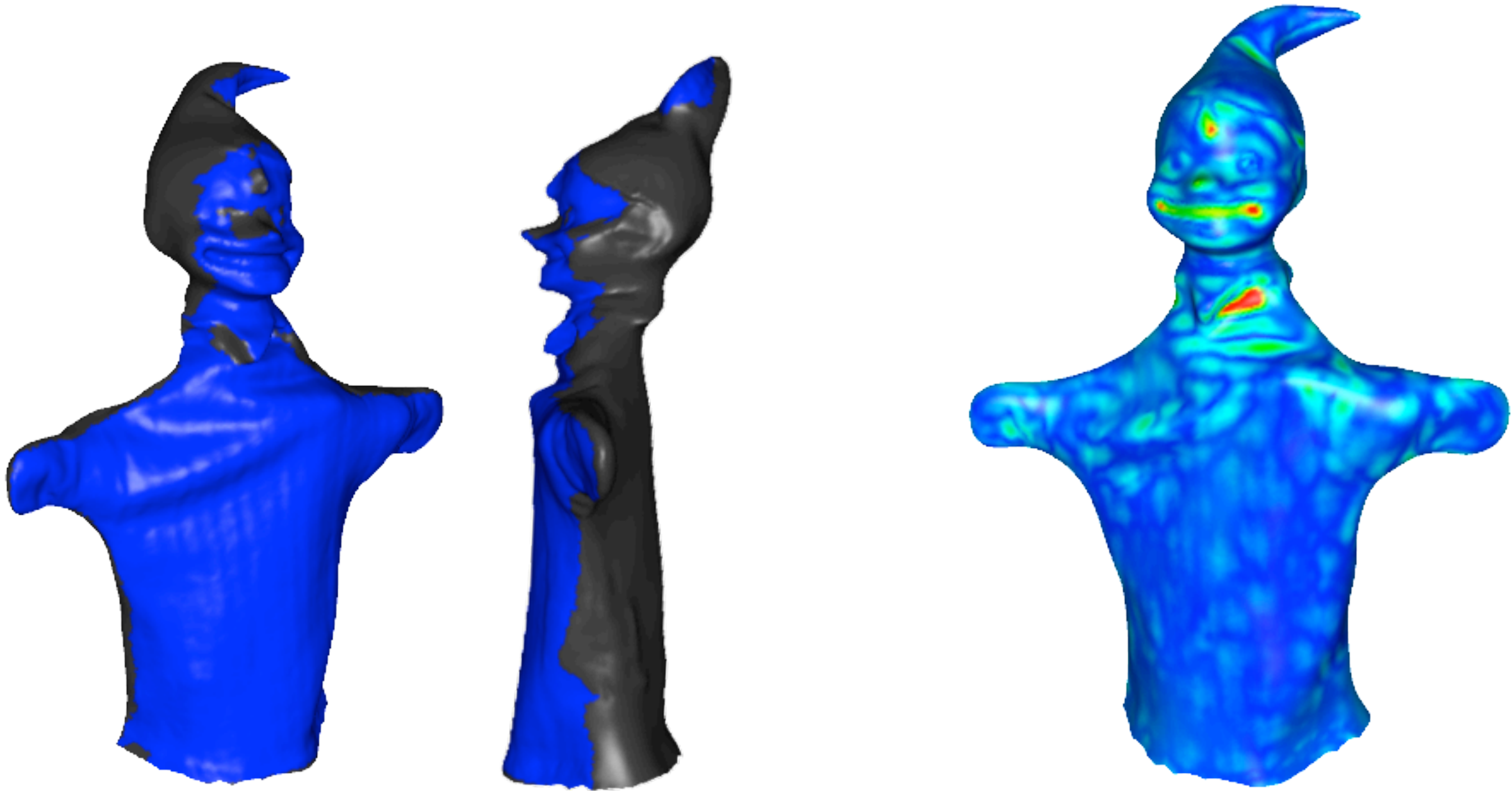
Forward-Backward Pass



Forward-Backward Pass

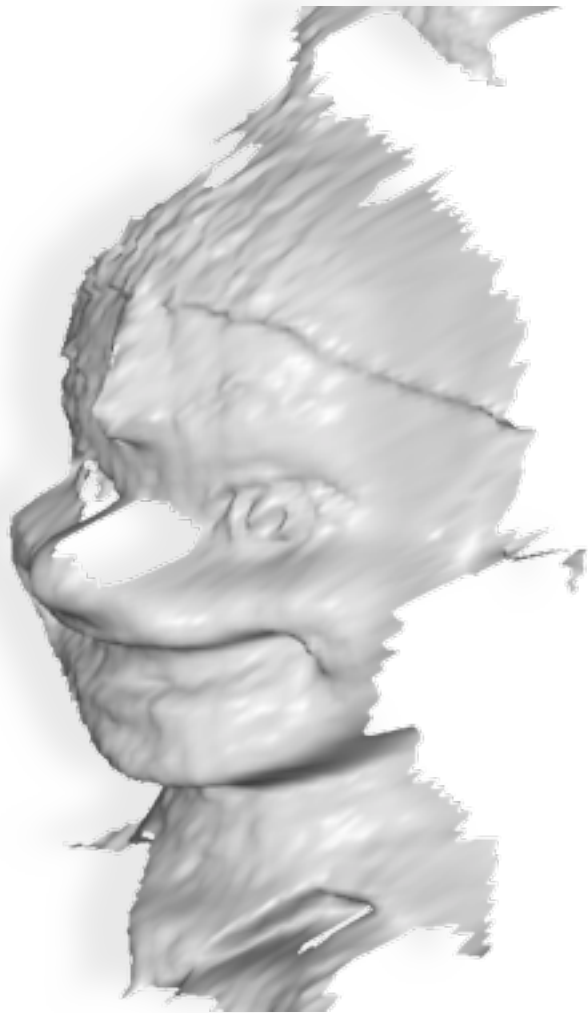


Forward-Backward Pass



Super Resolution

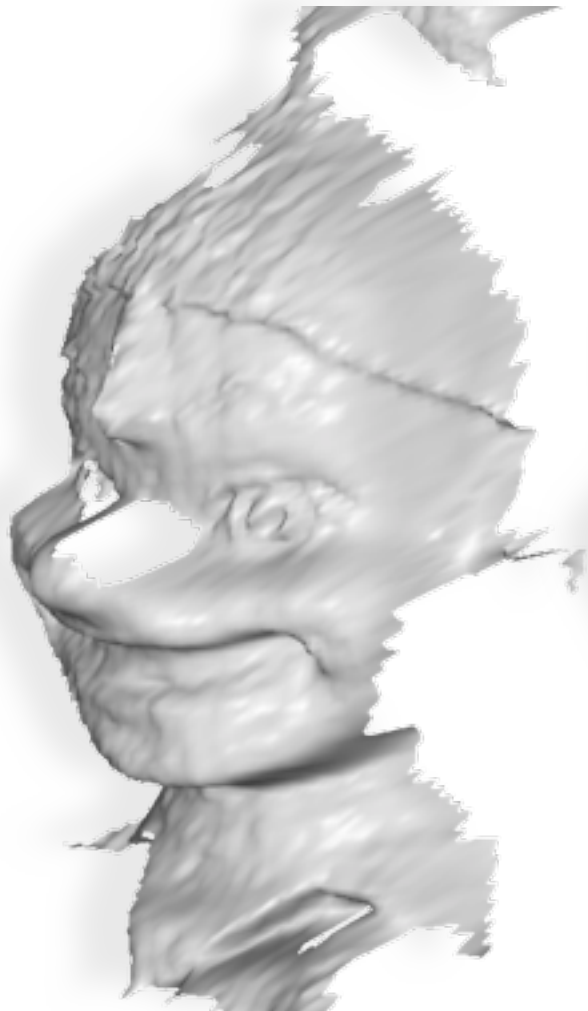
Input Scan



Super Resolution

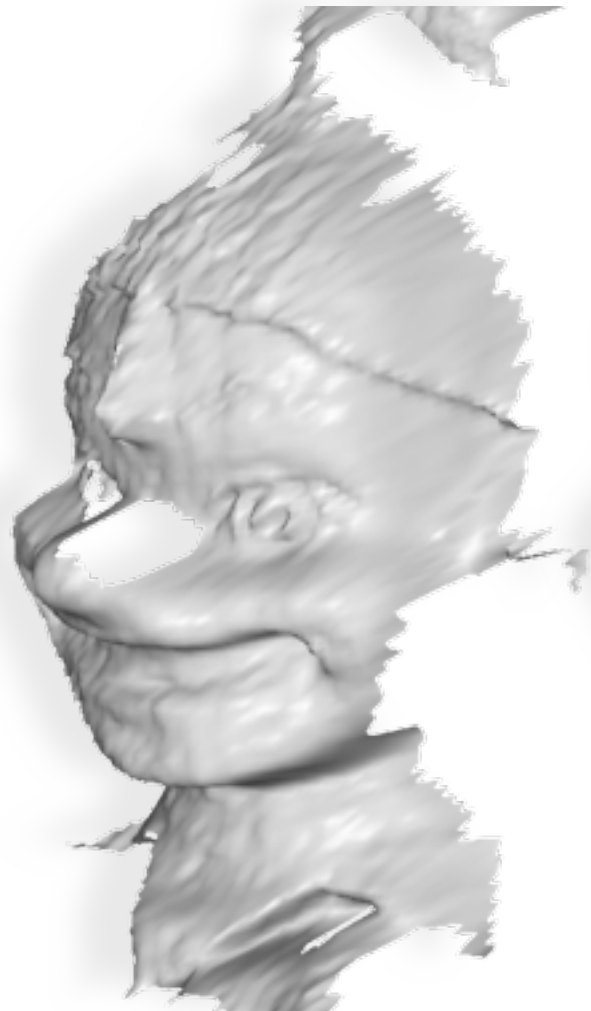
Input Scan

Warped Template



Super Resolution

Input Scan



Warped Template

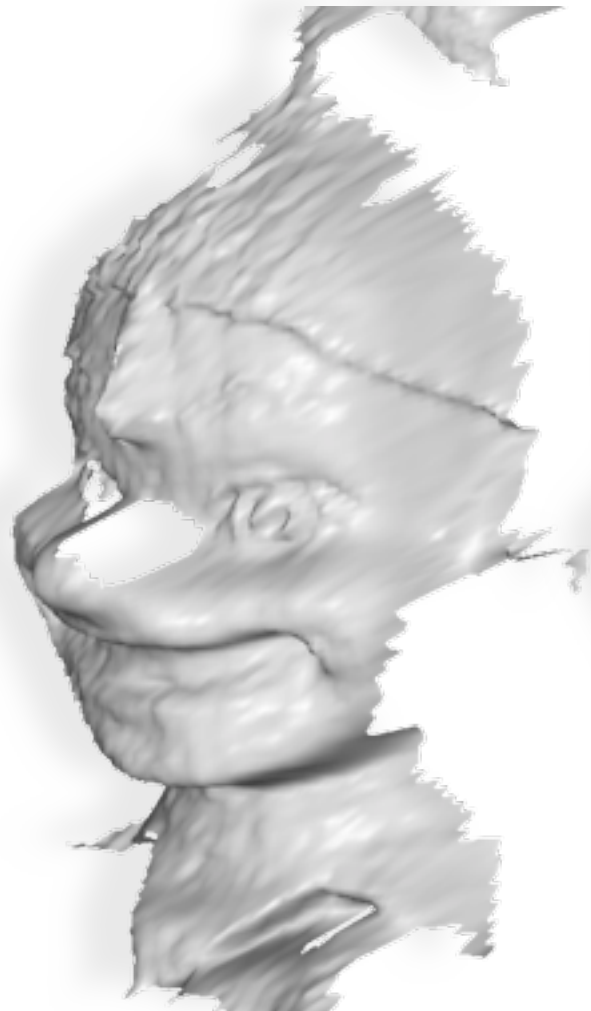


Reconstruction



Super Resolution

Input Scan



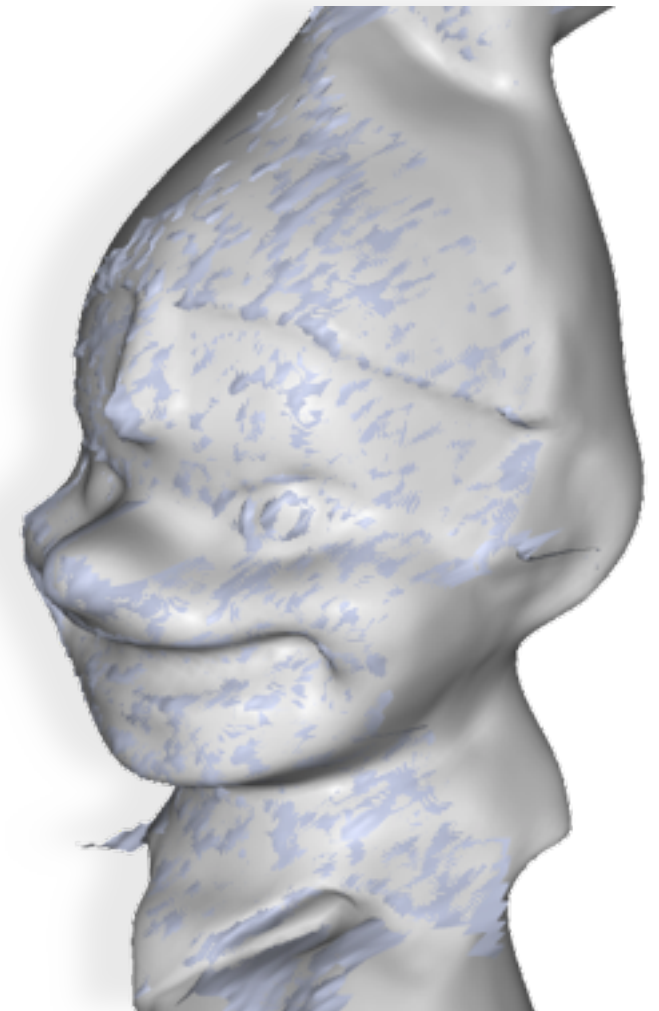
Warped Template



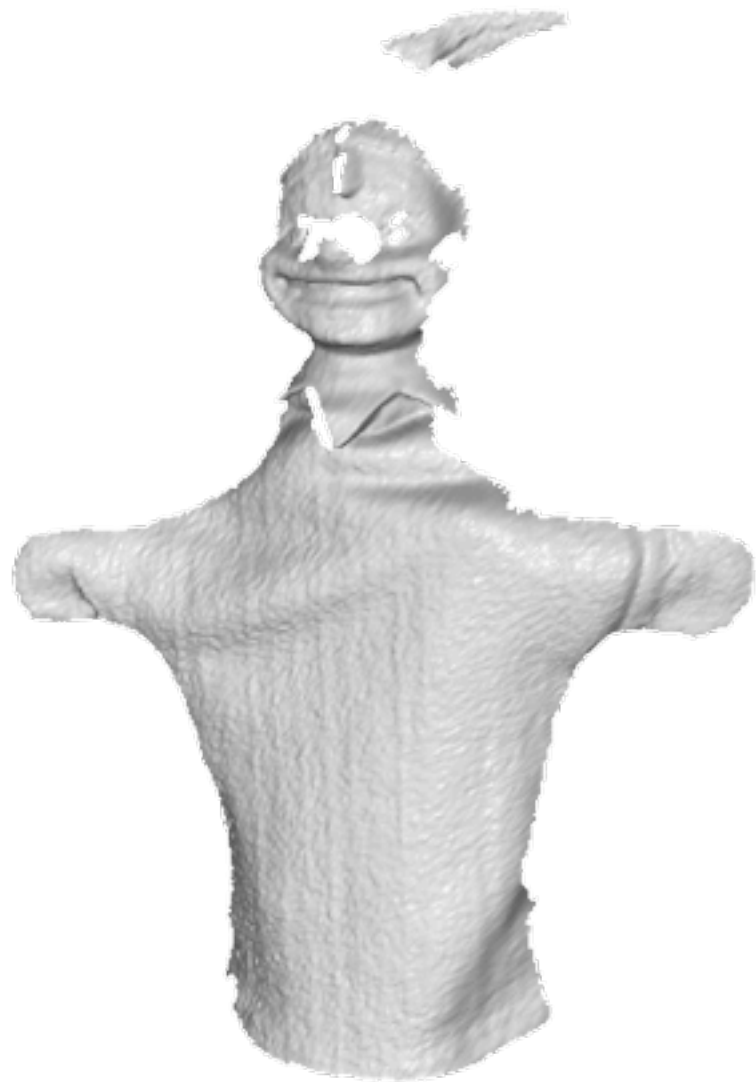
Reconstruction



Overlaid Scan



Final Reconstruction – 100 Frames



Input Scans



Reconstruction



Textured Reconstruction



Crumpling Paper Bag – 85 Frames



Input Scans



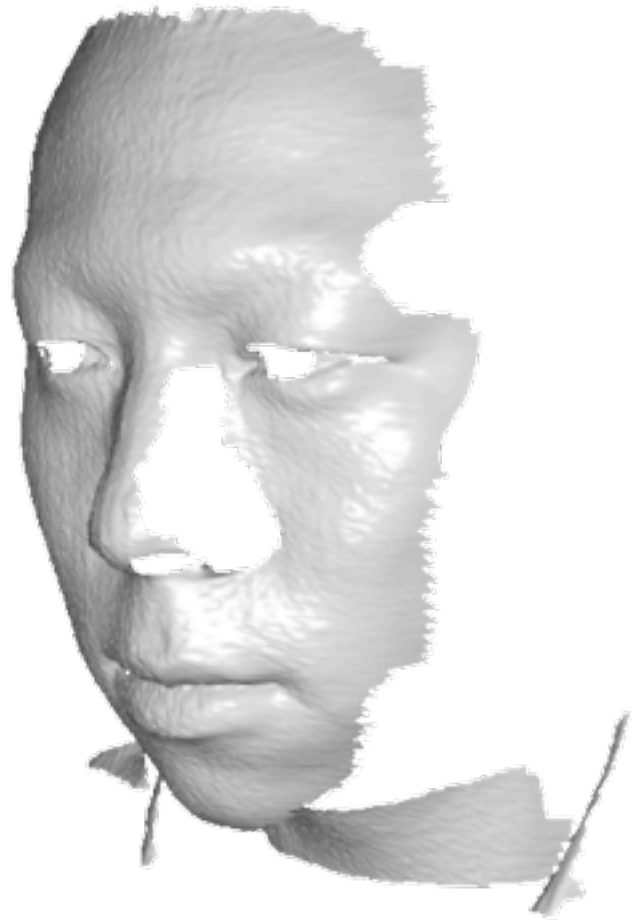
Reconstruction



Textured Reconstruction



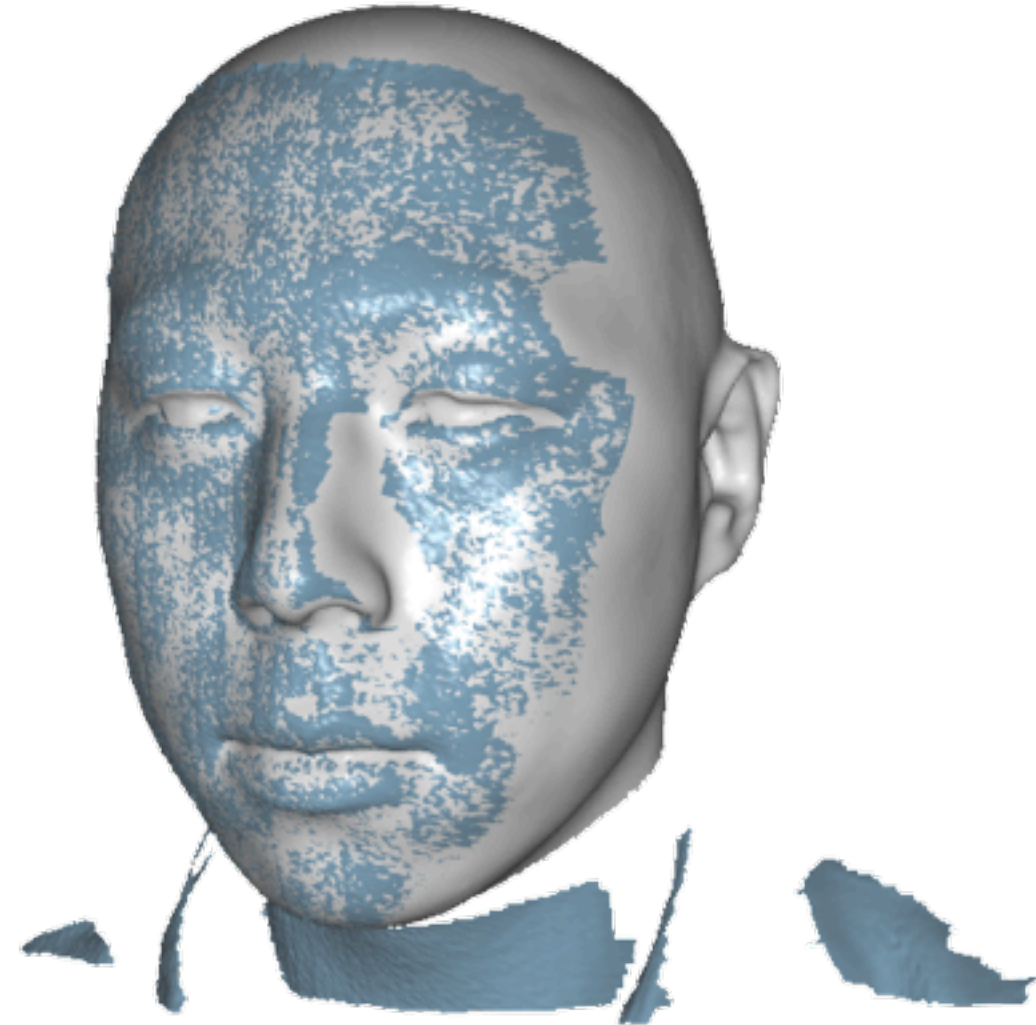
Facial Expressions – 200 Frames



Input Scans

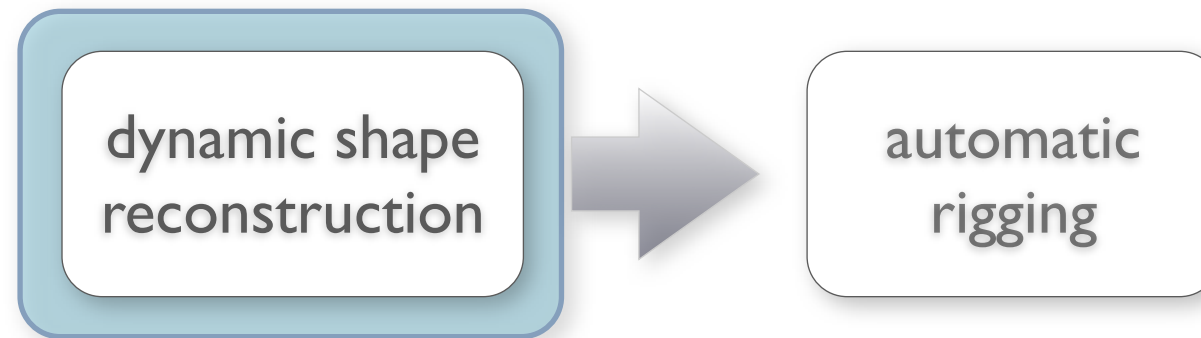


Reconstruction

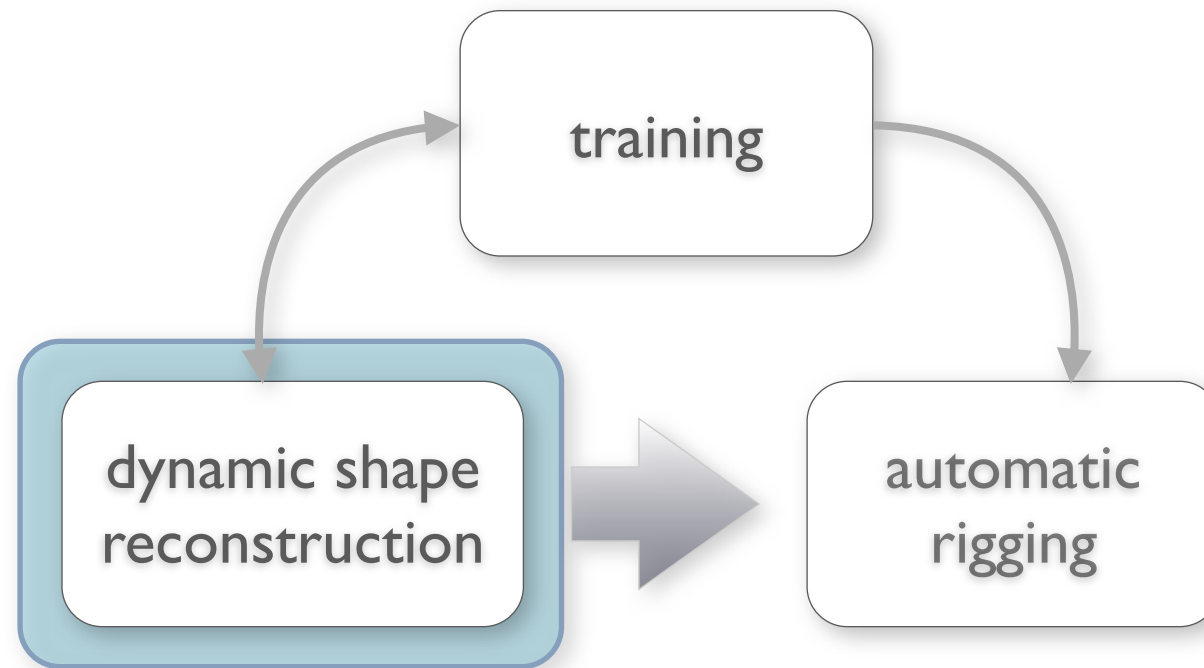


Overlaid Scans

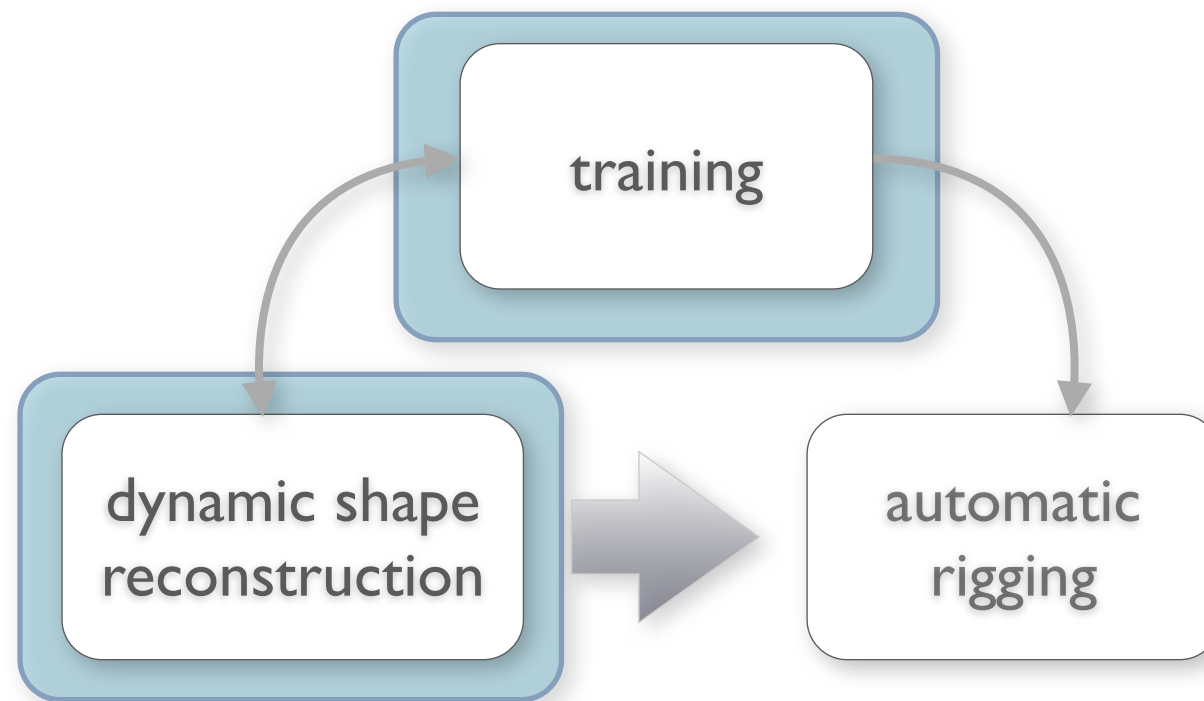
Limitations: Drift



Limitations: Drift



Limitations: Drift

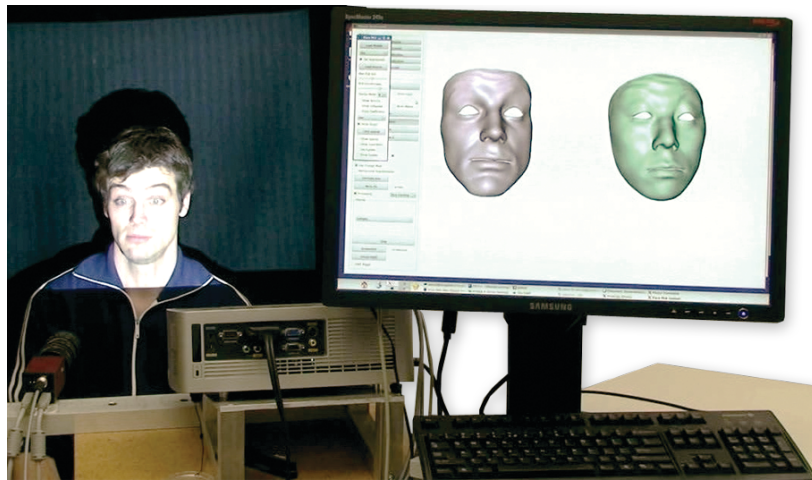


Facial Animation

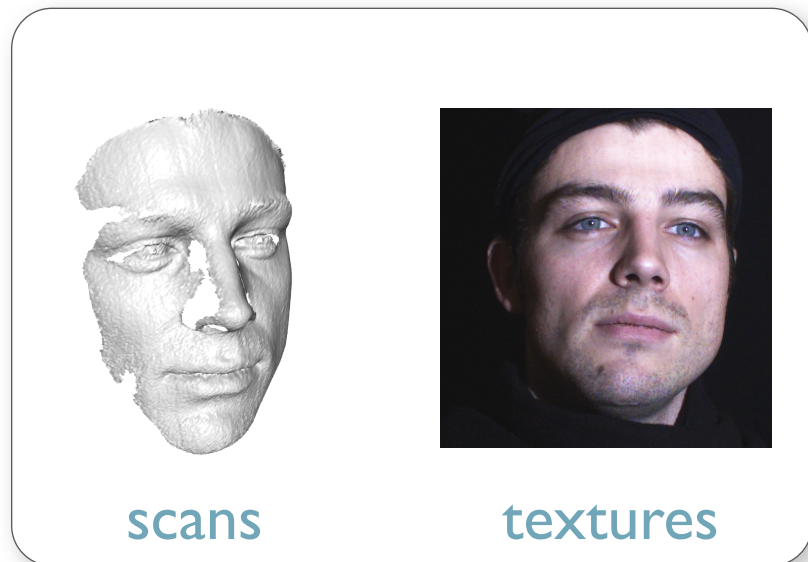
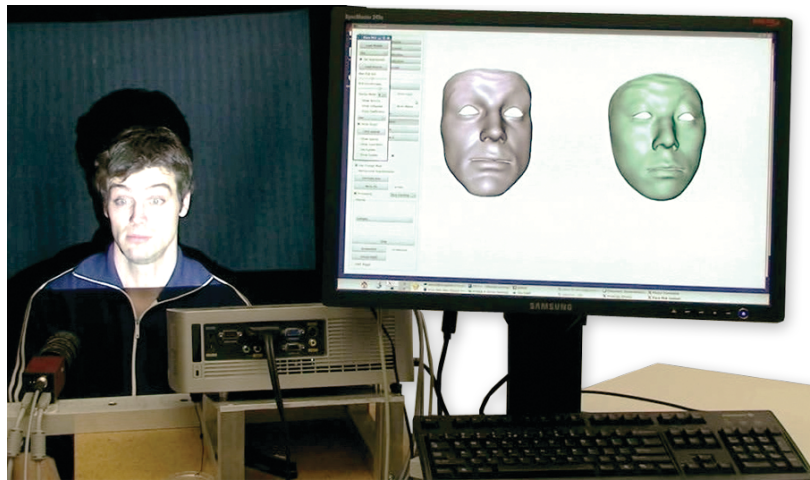
[Weise et al. '09]



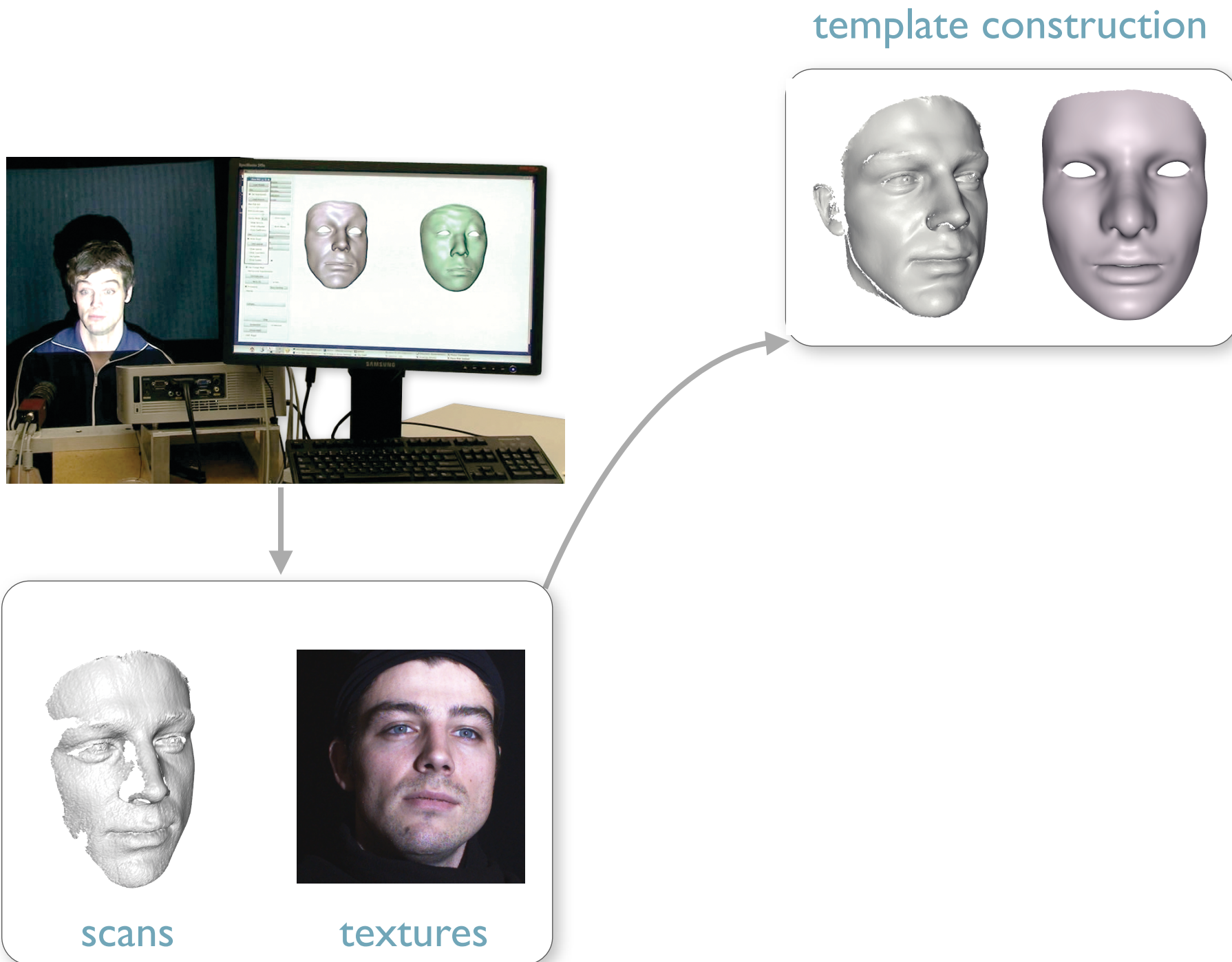
System Overview



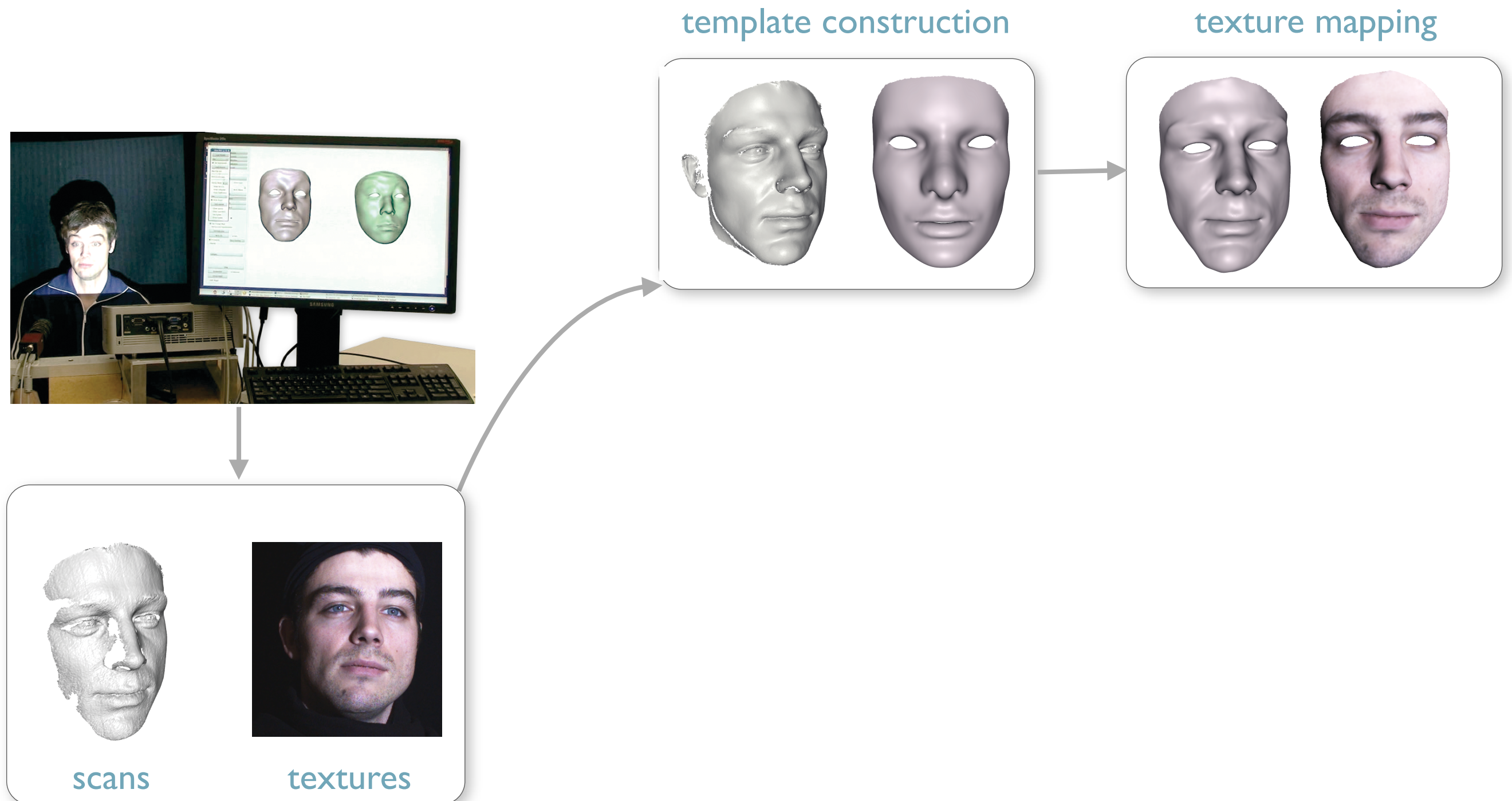
System Overview



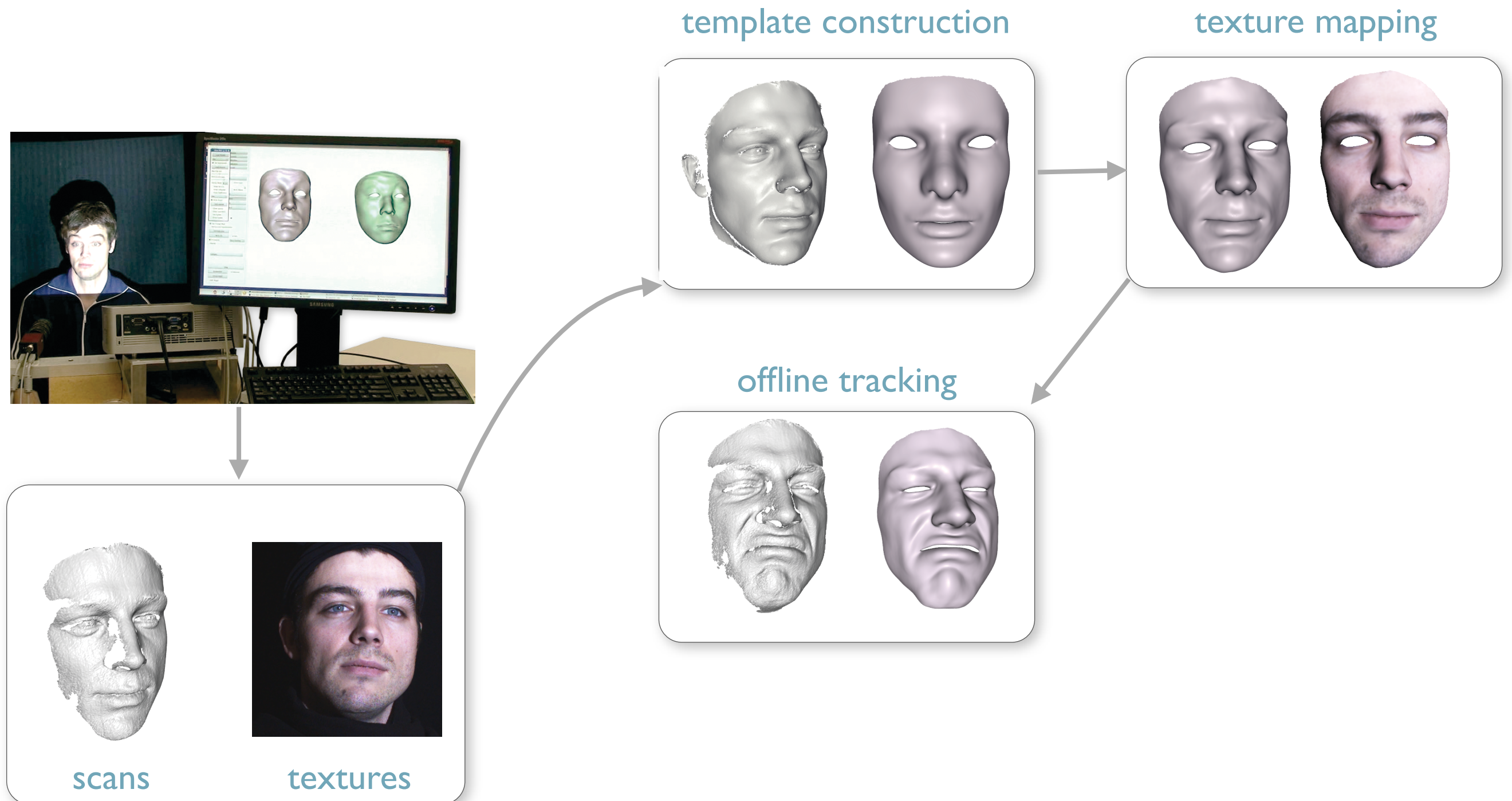
System Overview



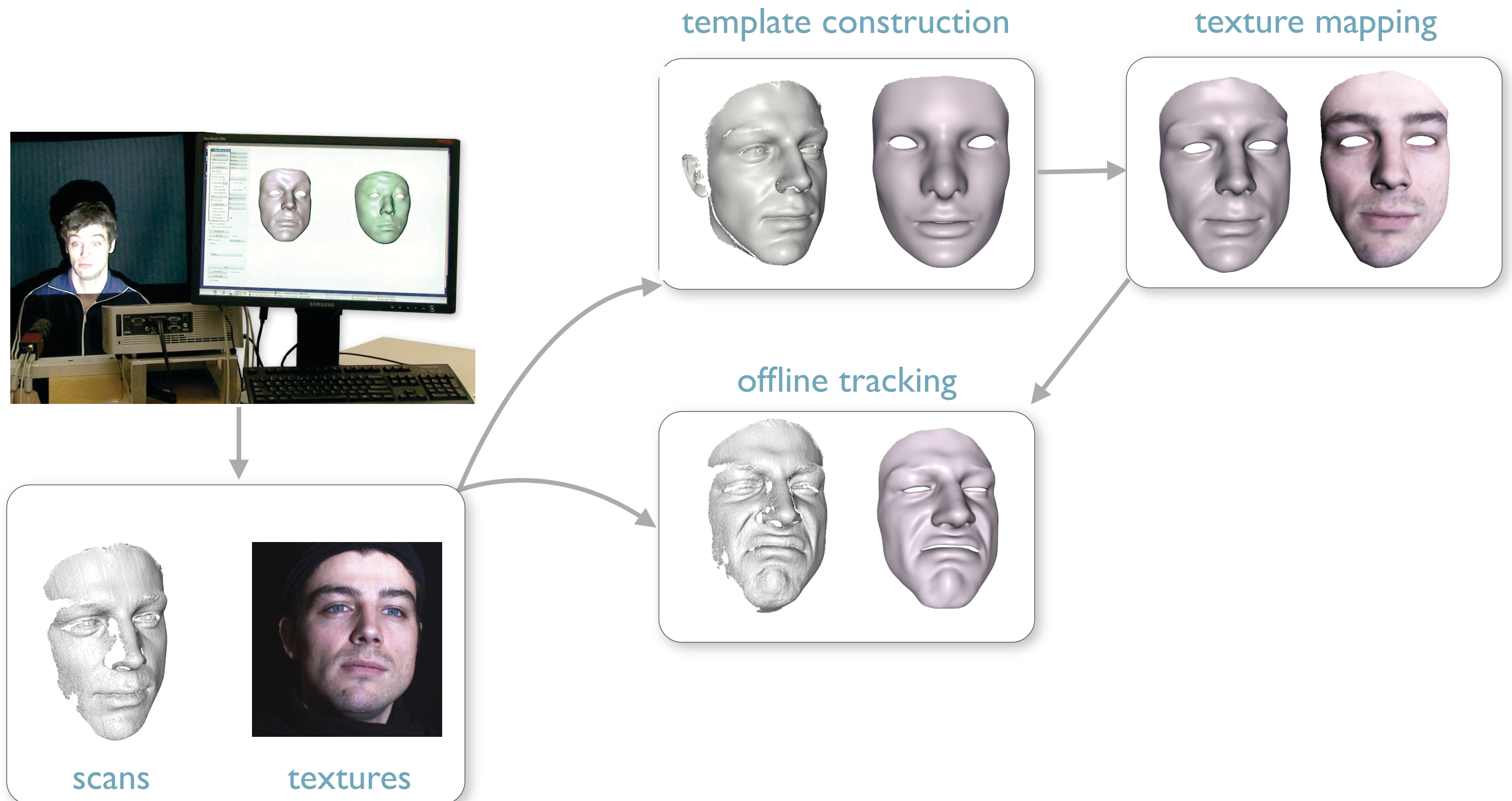
System Overview



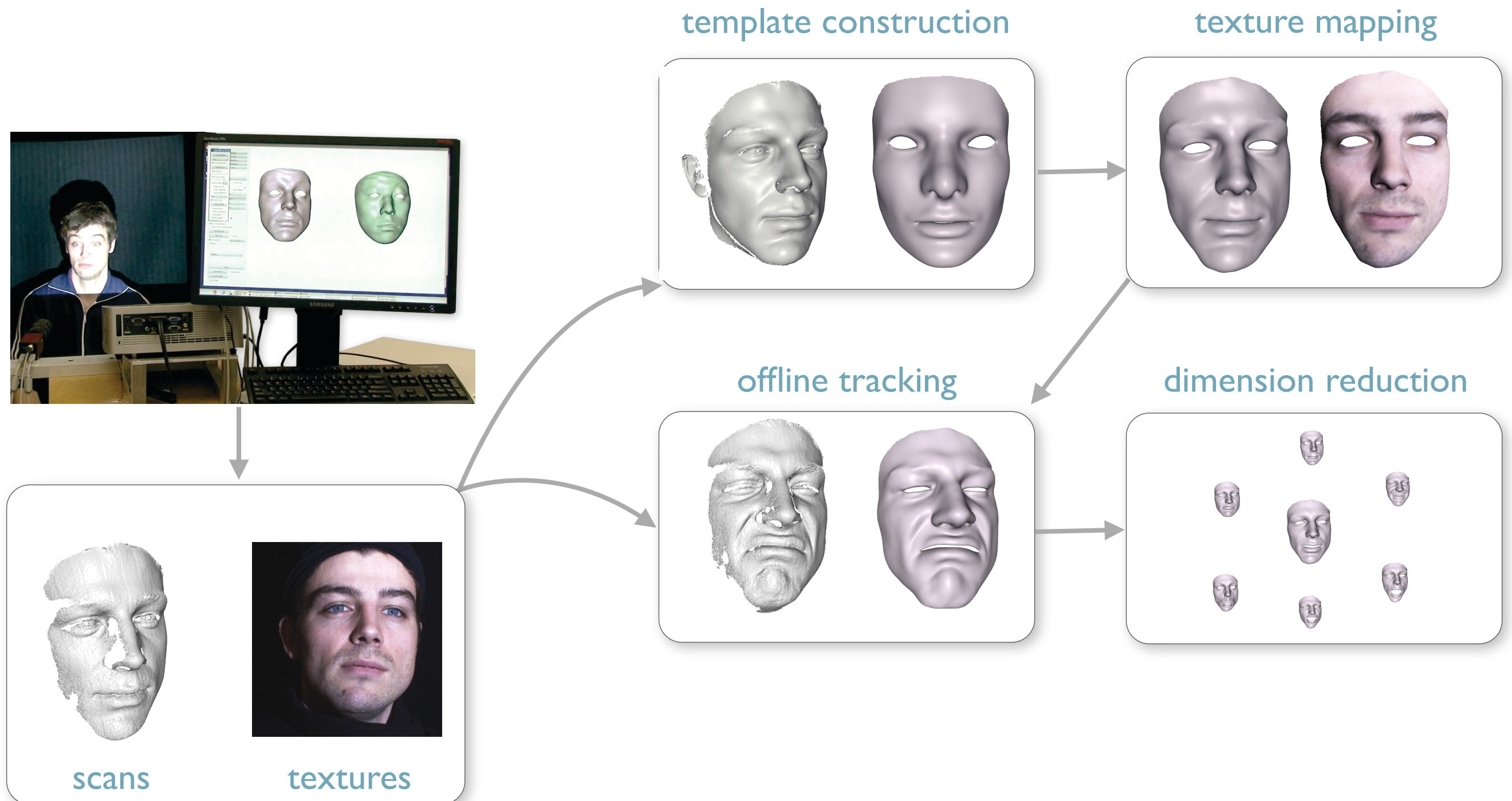
System Overview



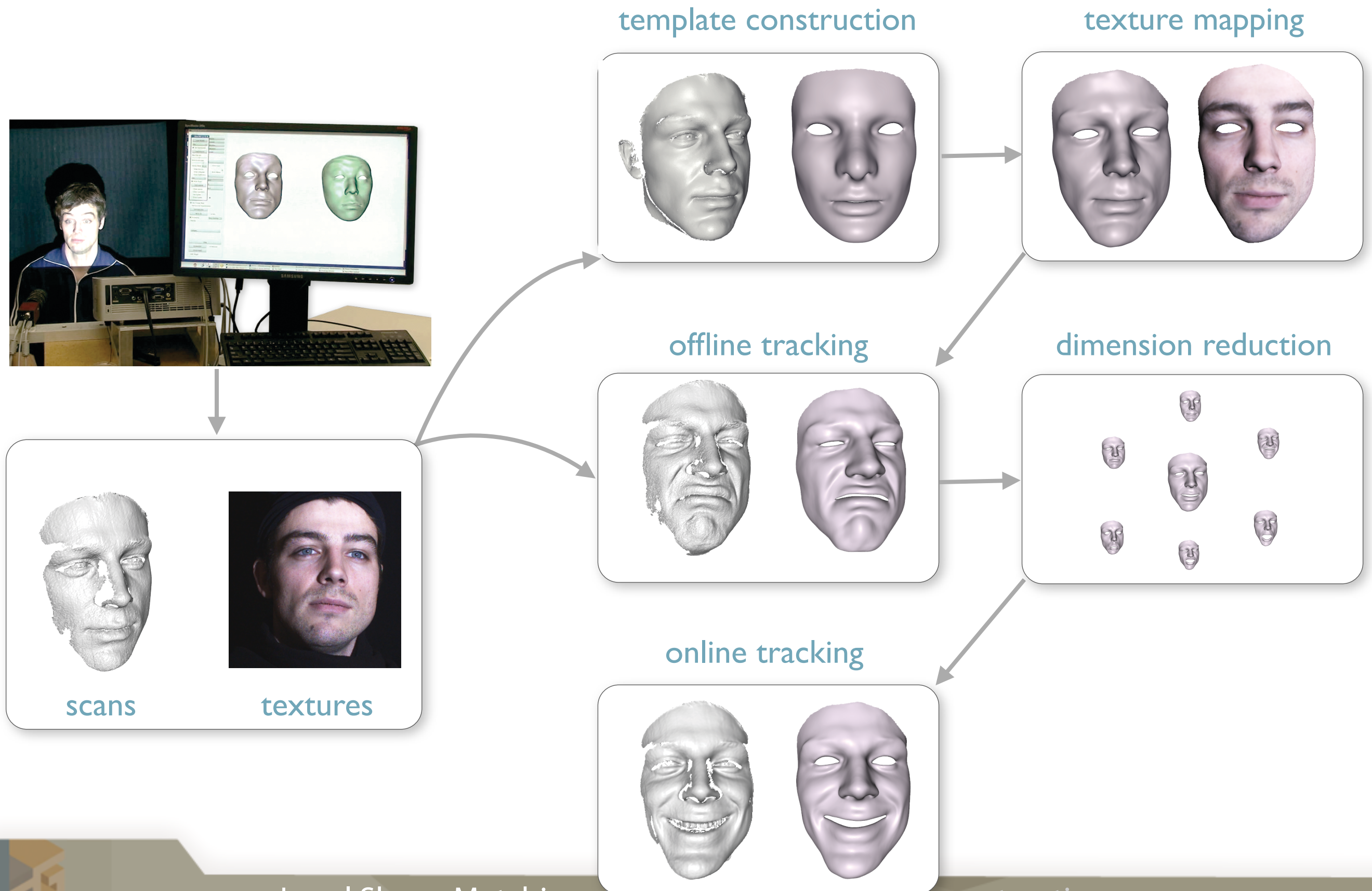
System Overview



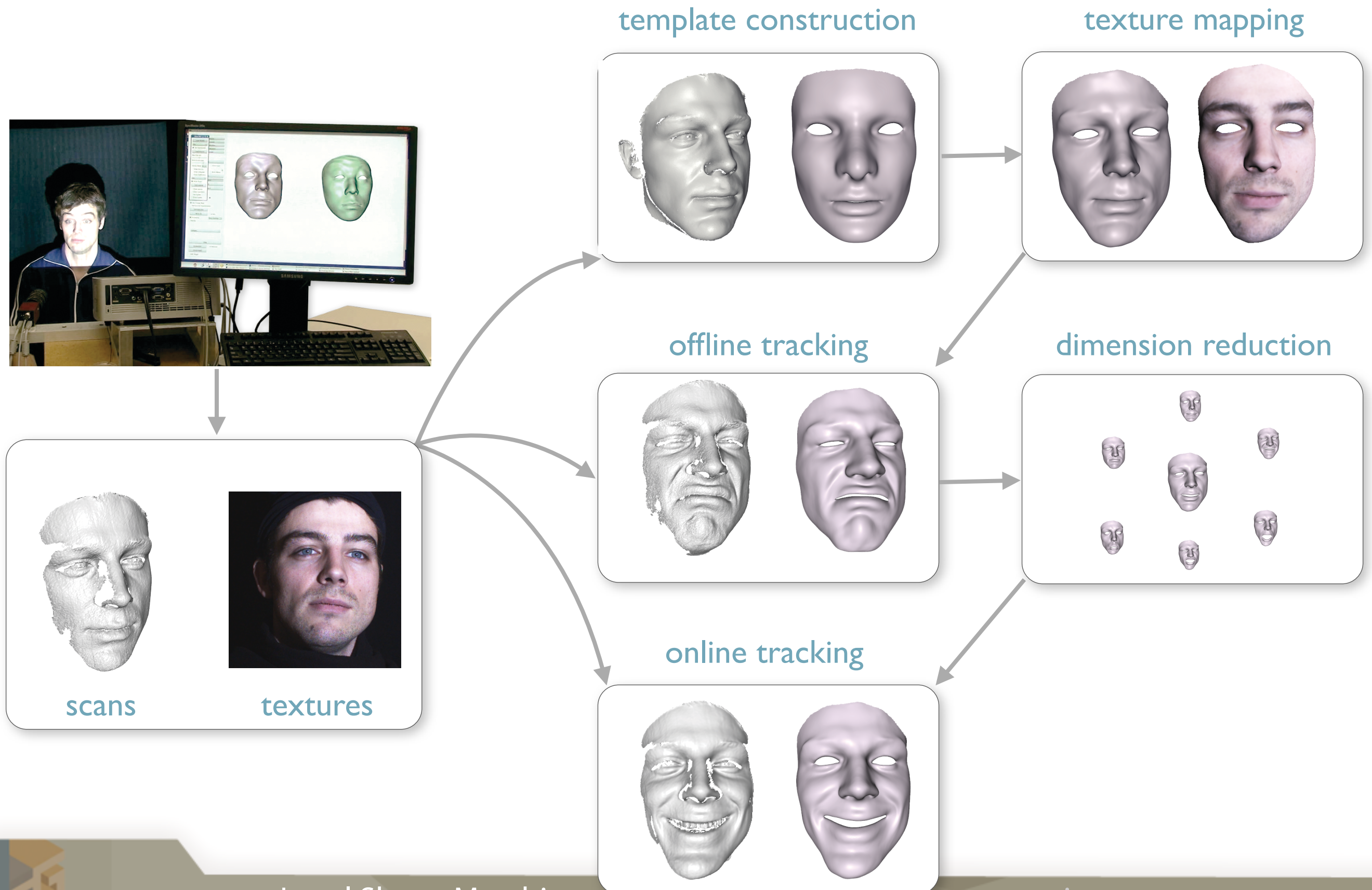
System Overview



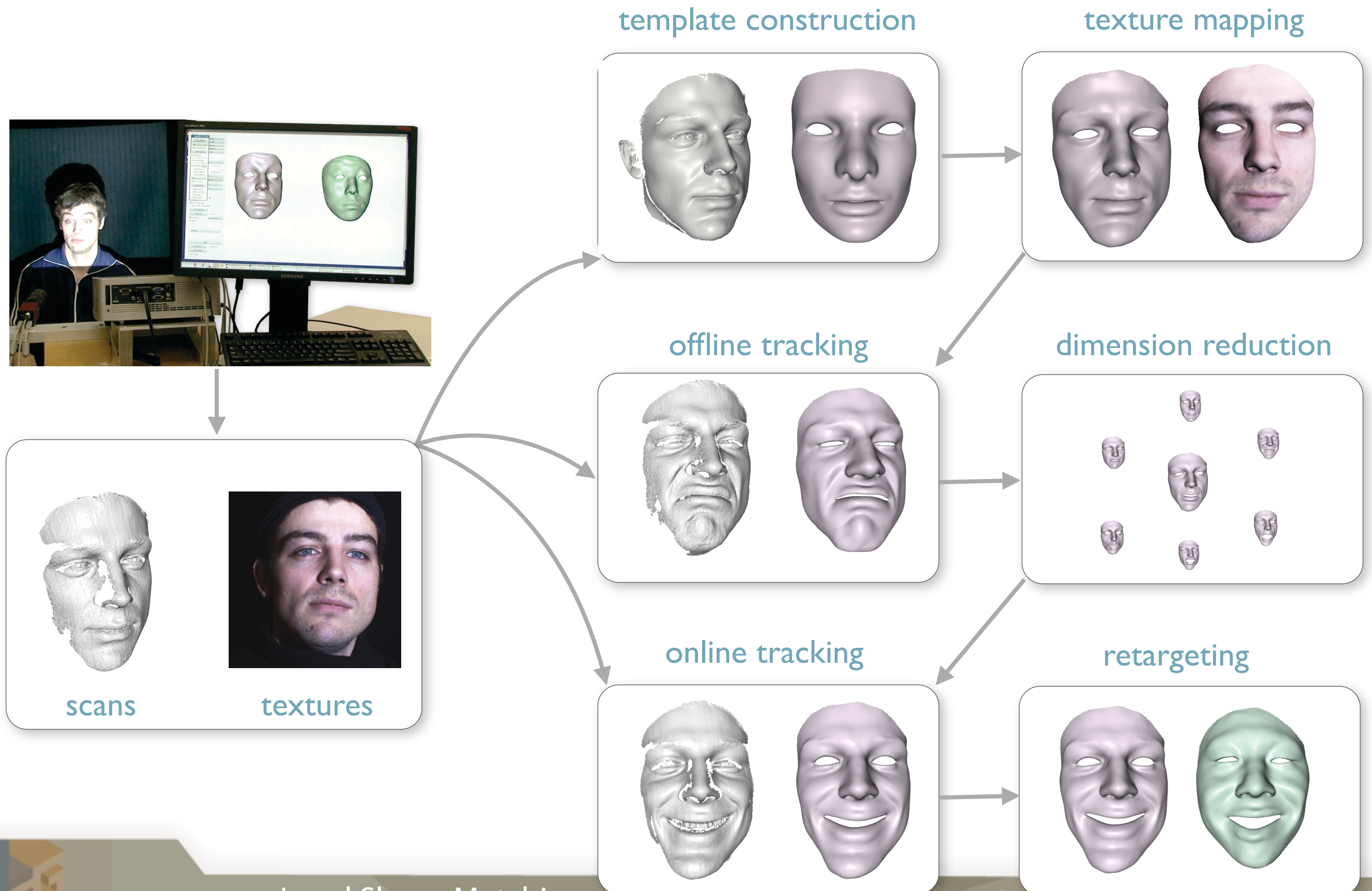
System Overview



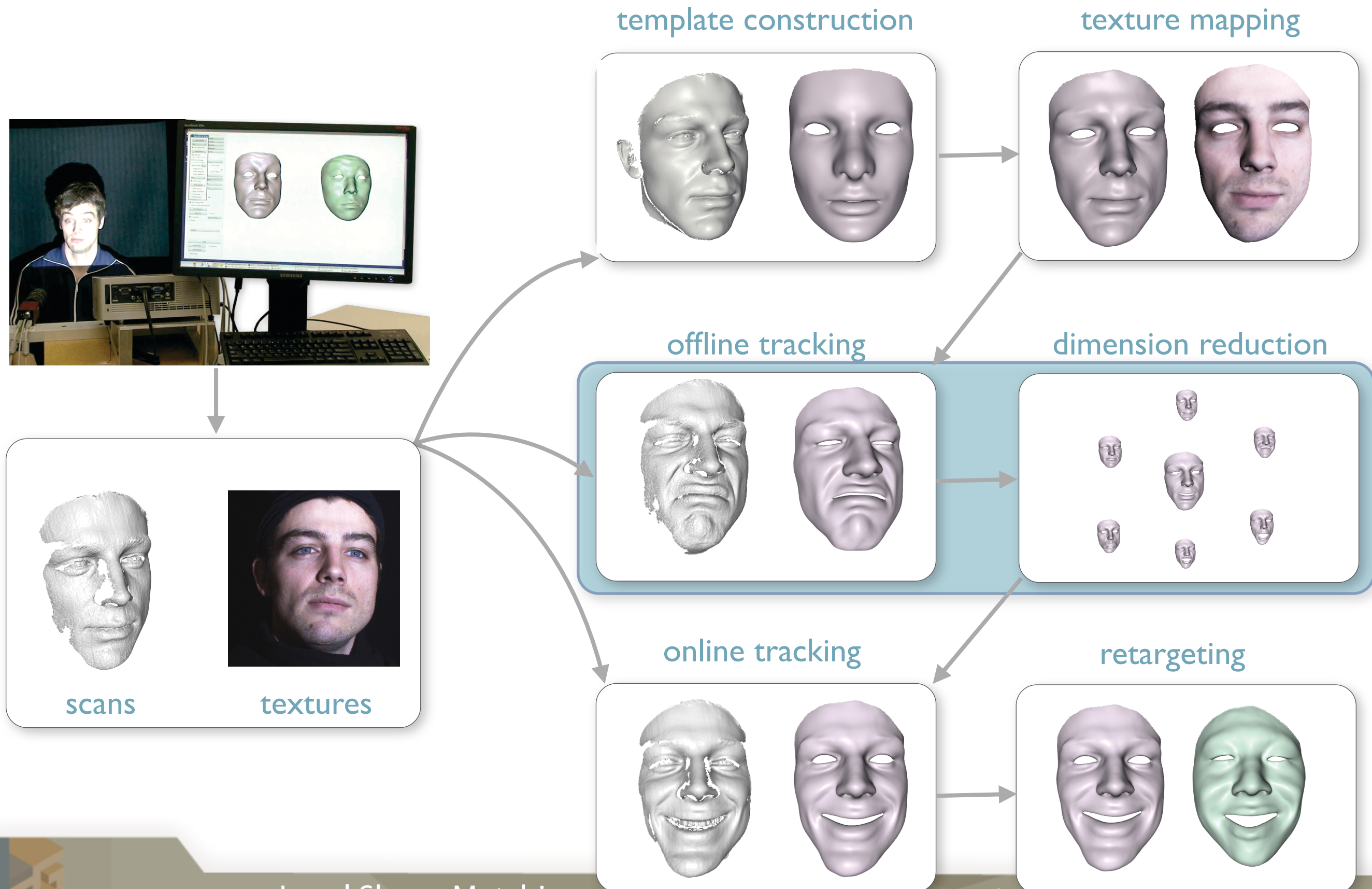
System Overview



System Overview



System Overview



Dimension Reduction



Dimension Reduction



Dimension Reduction



Principal Component Analysis

Dimension Reduction



Principal Component Analysis



Dimension Reduction



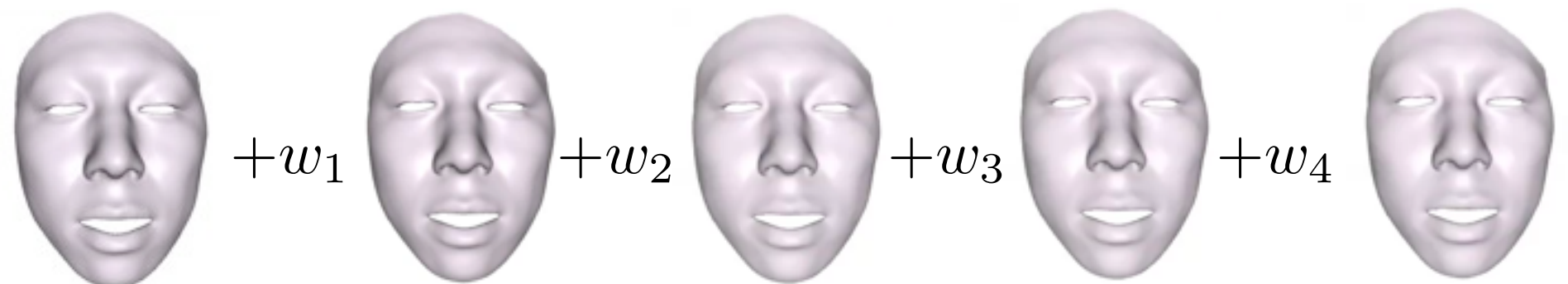
Principal Component Analysis



Dimension Reduction



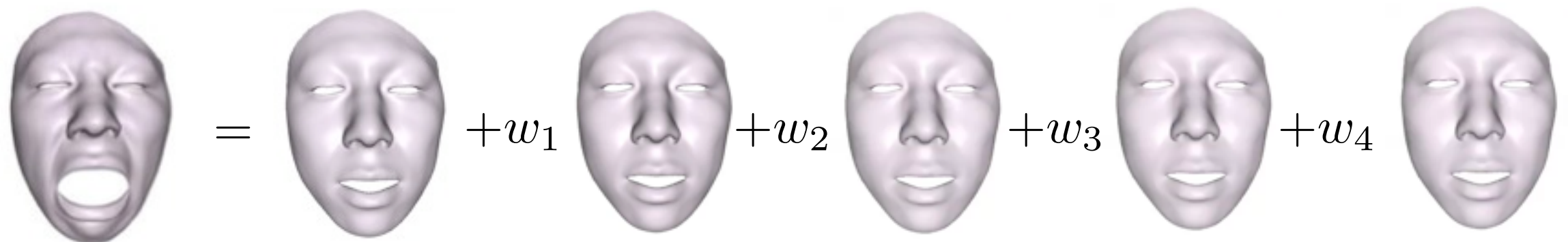
Principal Component Analysis



Dimension Reduction



Principal Component Analysis



Limitations: Varying Topology



Temporally Coherent Shape Completion [Li et al. '11]

partial data

reconstruction

partial data

reconstruction



Temporally Coherent Shape Completion [Li et al. '11]



partial data



reconstruction



partial data



reconstruction



Temporally Coherent Shape Completion [Li et al. '11]



partial data



reconstruction



partial data



reconstruction



Light Stage 6 Capture



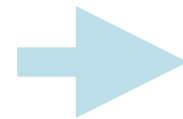
Lightstage 6 (USC-ICT)

[Vlasic et al. '09]

Light Stage 6 Capture



Lightstage 6 (USC-ICT)



8 Normal Maps / Frame

[Vlasic et al. '09]

Reconstruction



per view reconstruction

Reconstruction



per view reconstruction

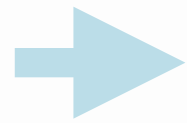


non-rigid registration

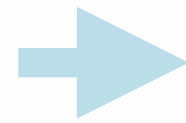
Reconstruction



per view reconstruction



non-rigid registration



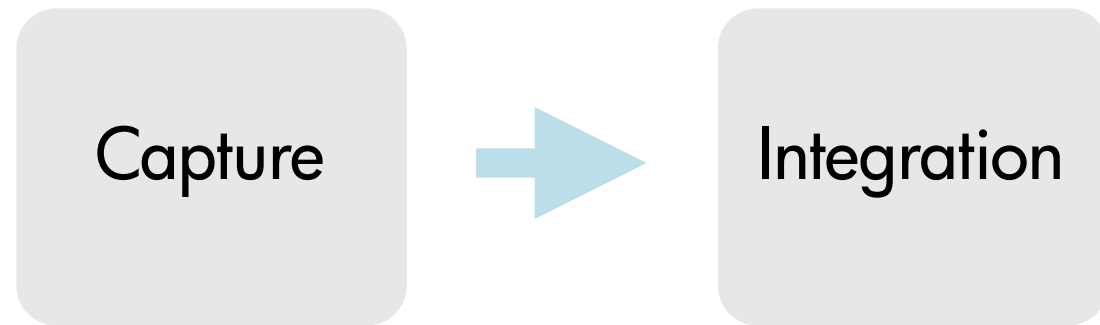
poisson reconstruction

Reconstruction

Capture



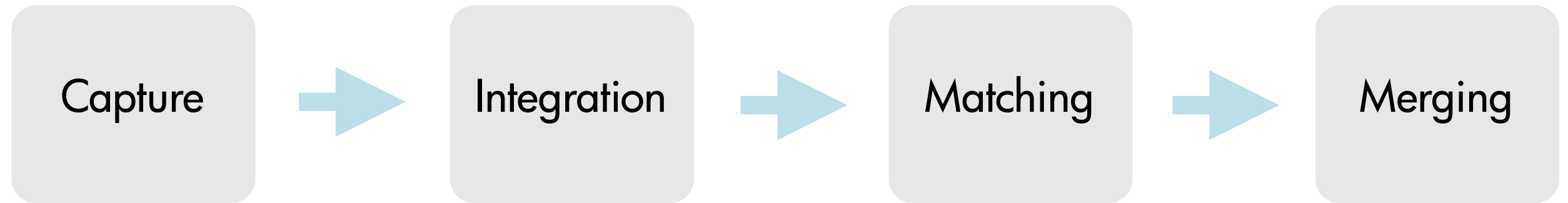
Reconstruction



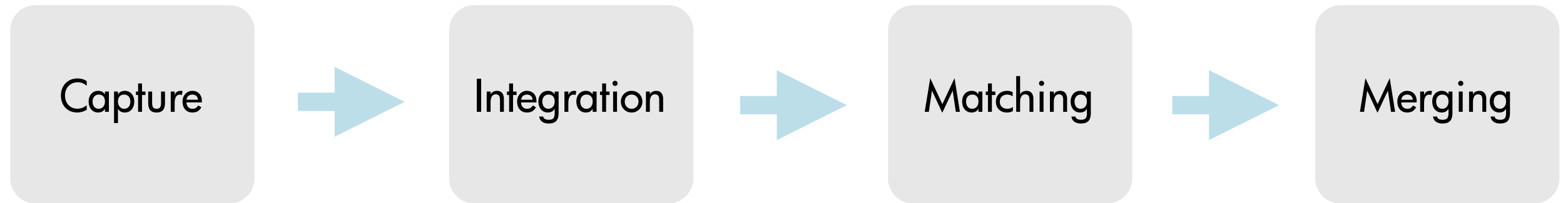
Reconstruction



Reconstruction



Reconstruction



input scans

Naive Shape Completion



hole filled



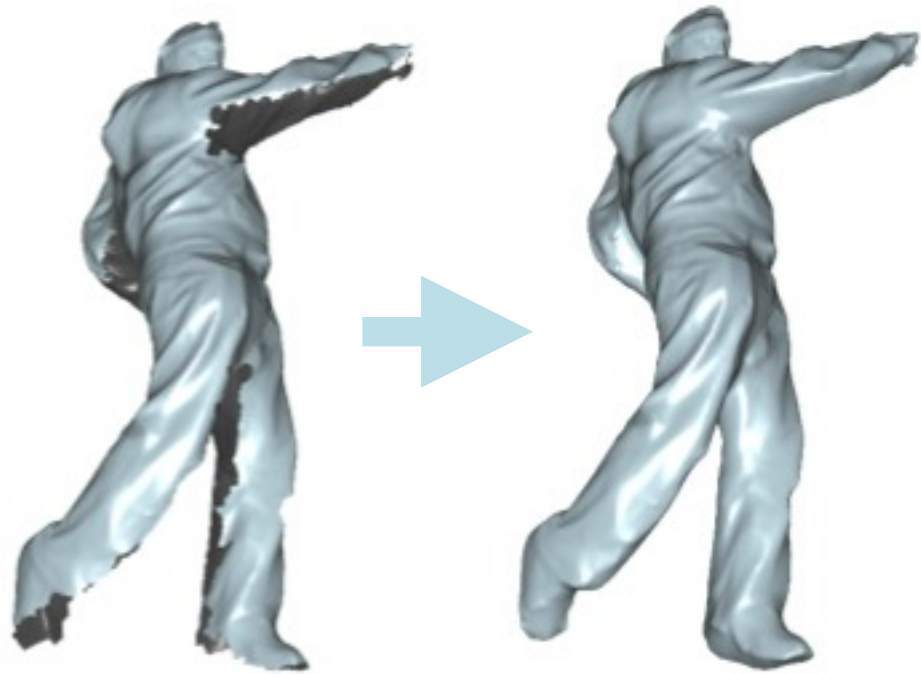
Dynamic Shape Completion



input scan



Dynamic Shape Completion

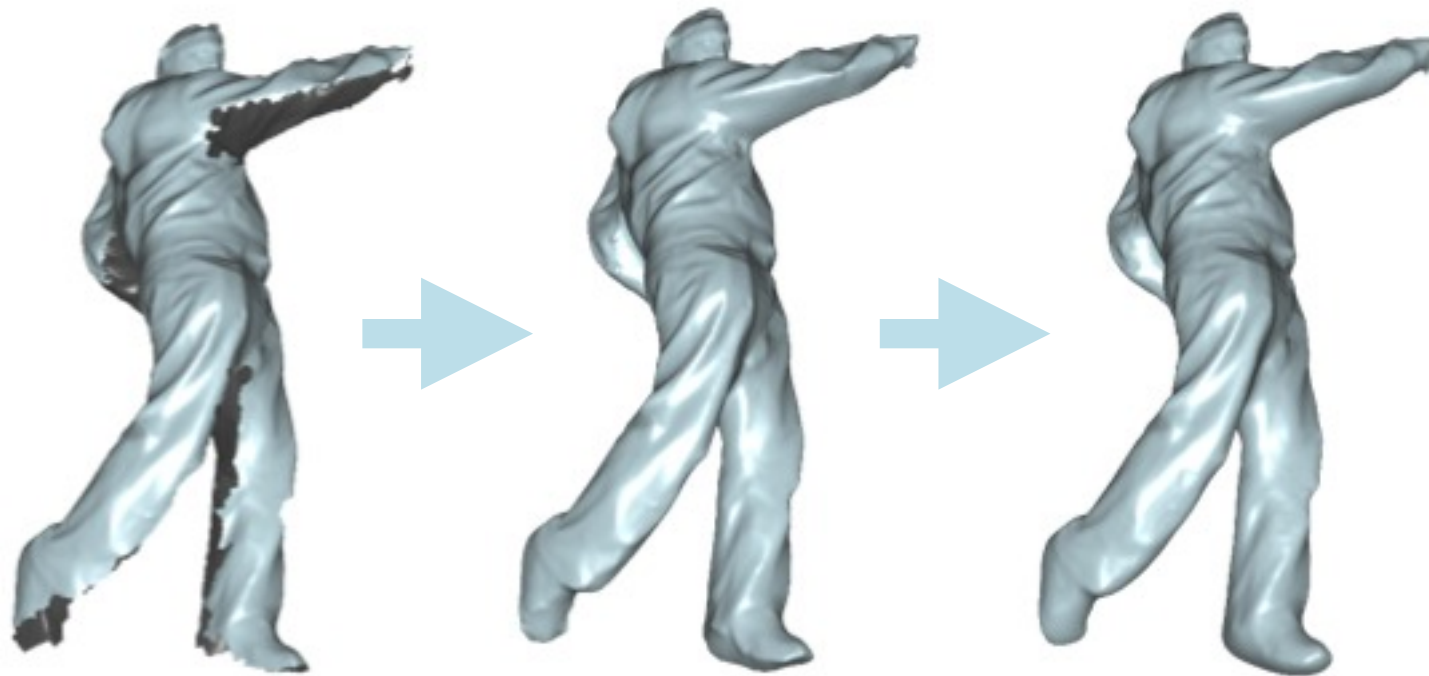


input scan

visual hull hole filling



Dynamic Shape Completion



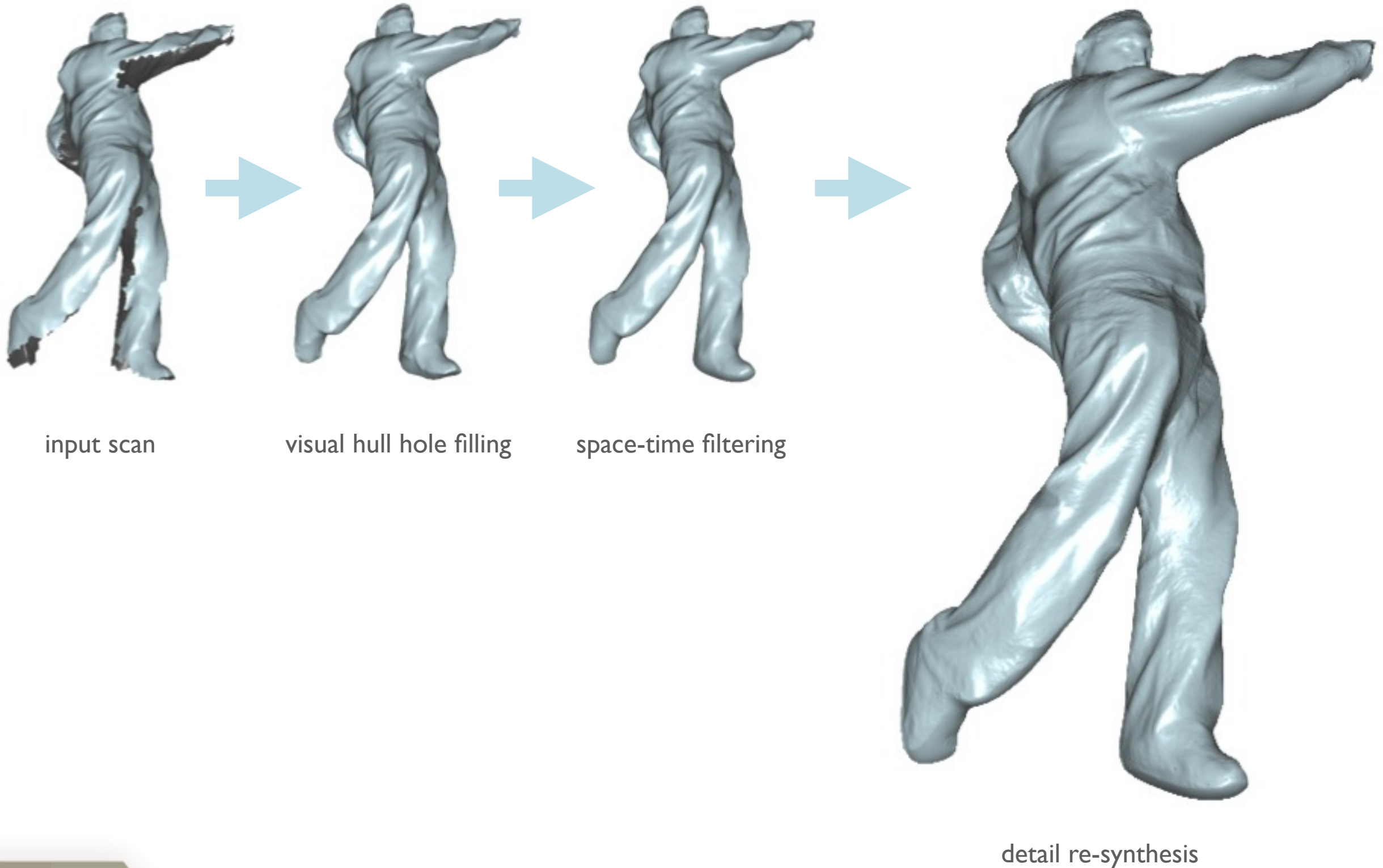
input scan

visual hull hole filling

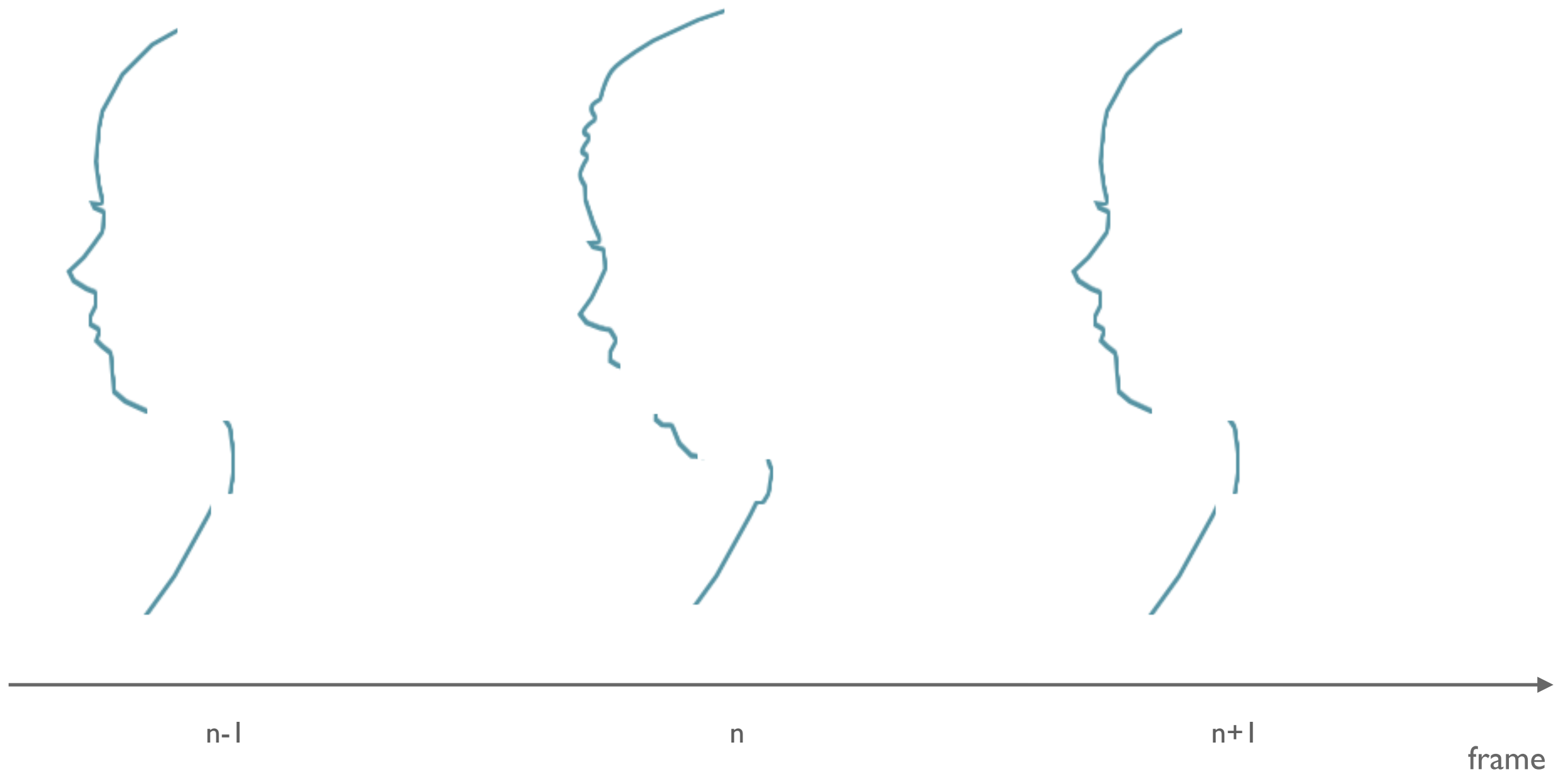
space-time filtering



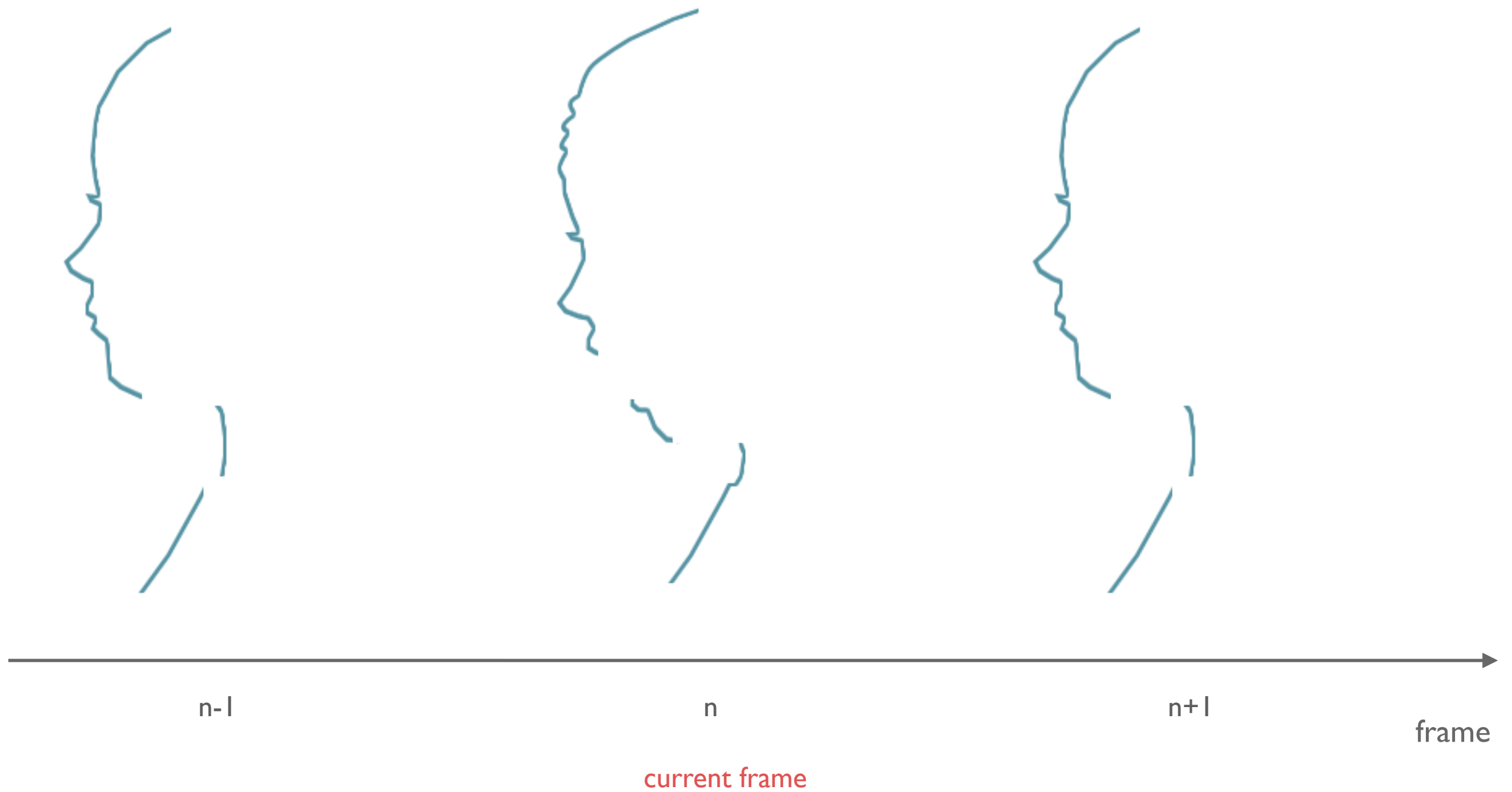
Dynamic Shape Completion



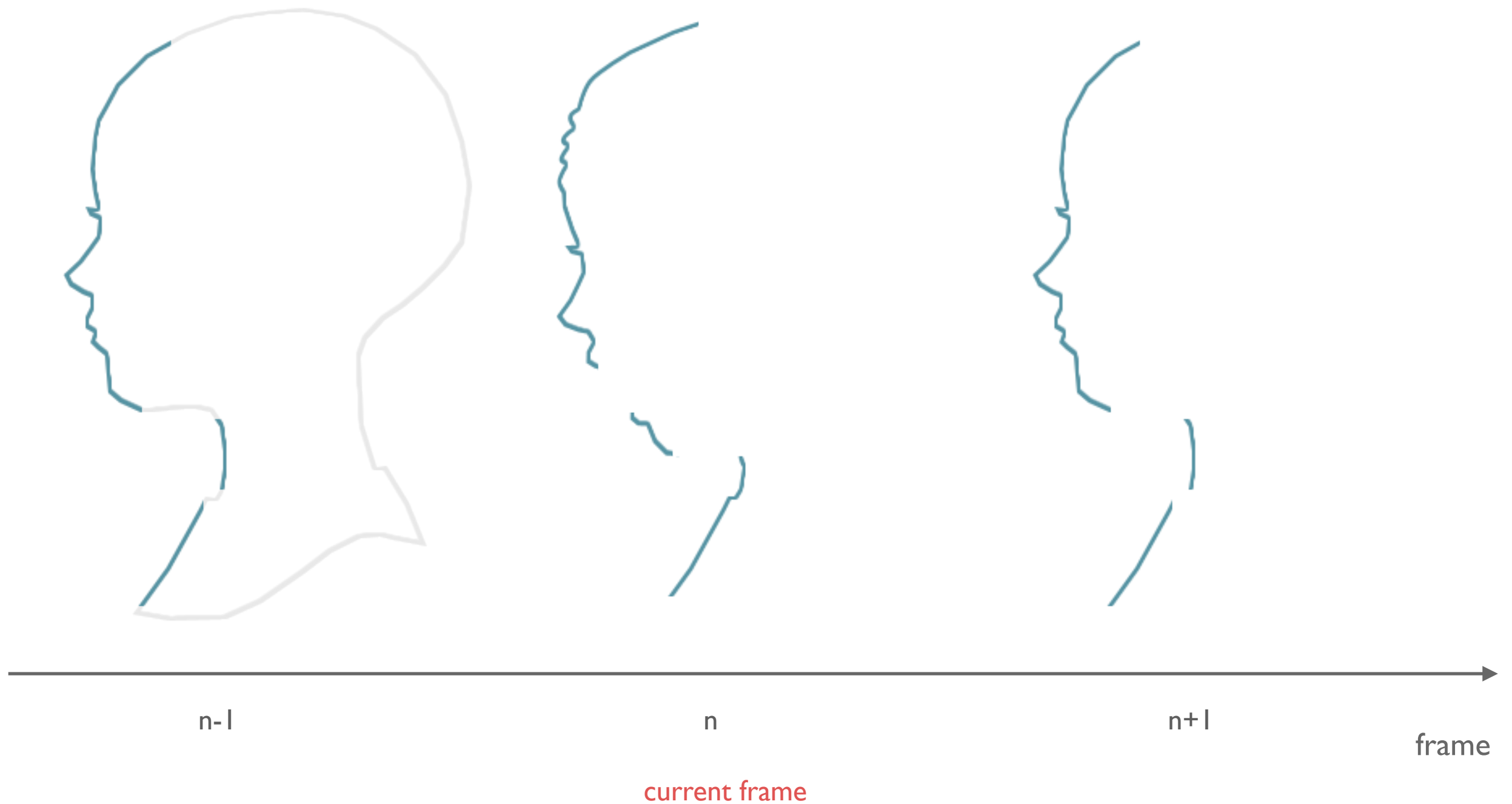
Temporal Filtering



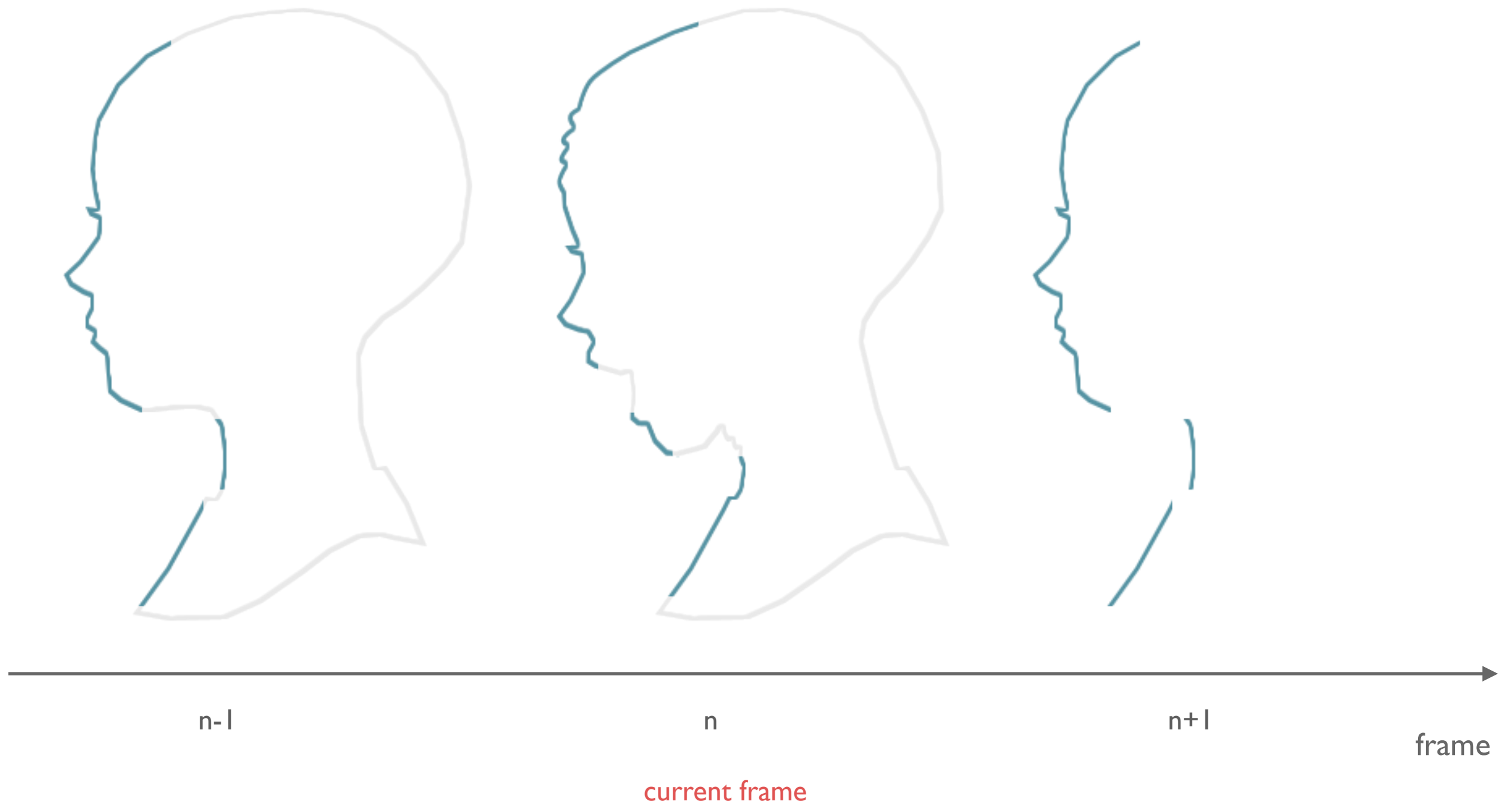
Temporal Filtering



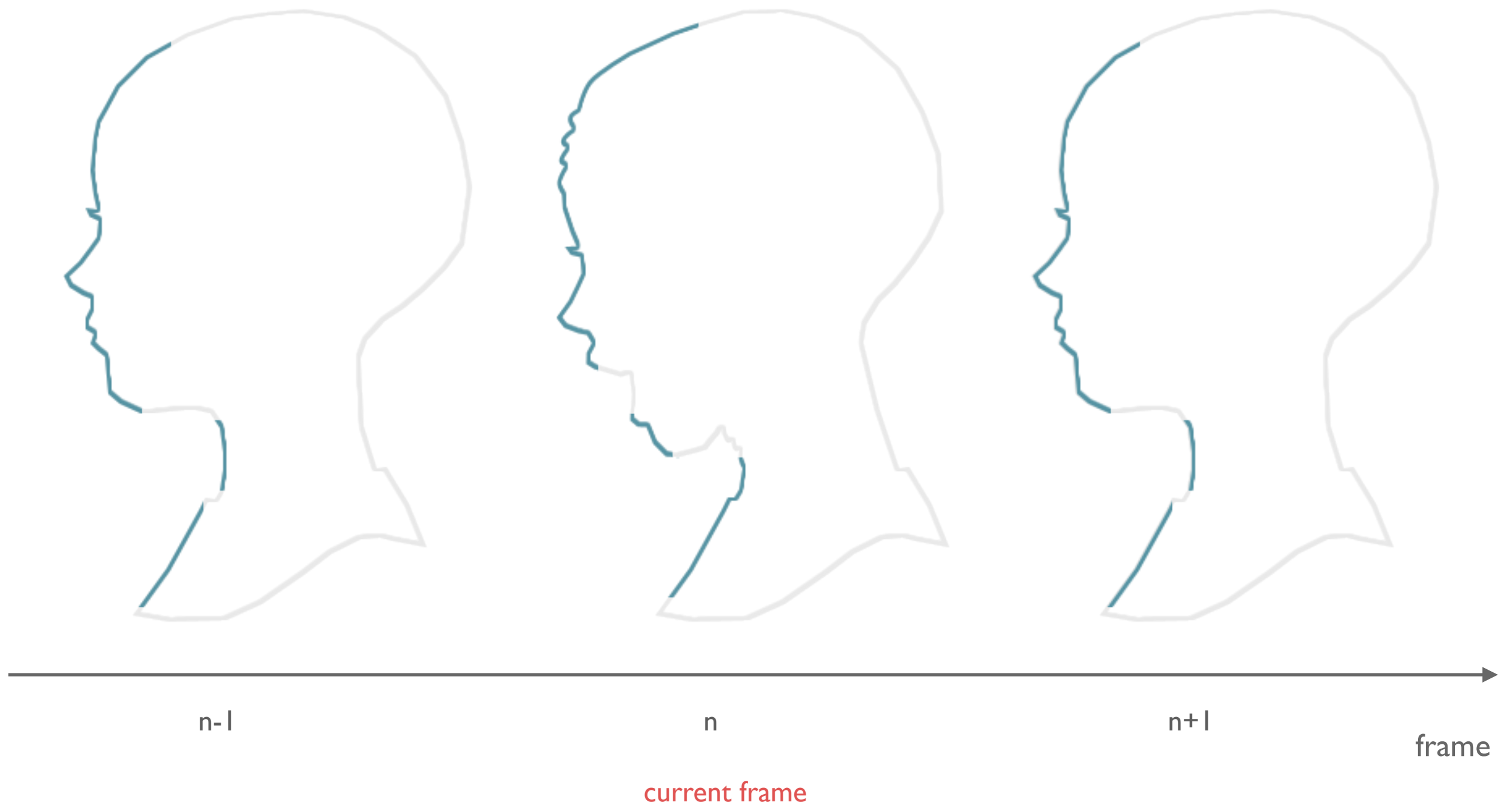
Temporal Filtering



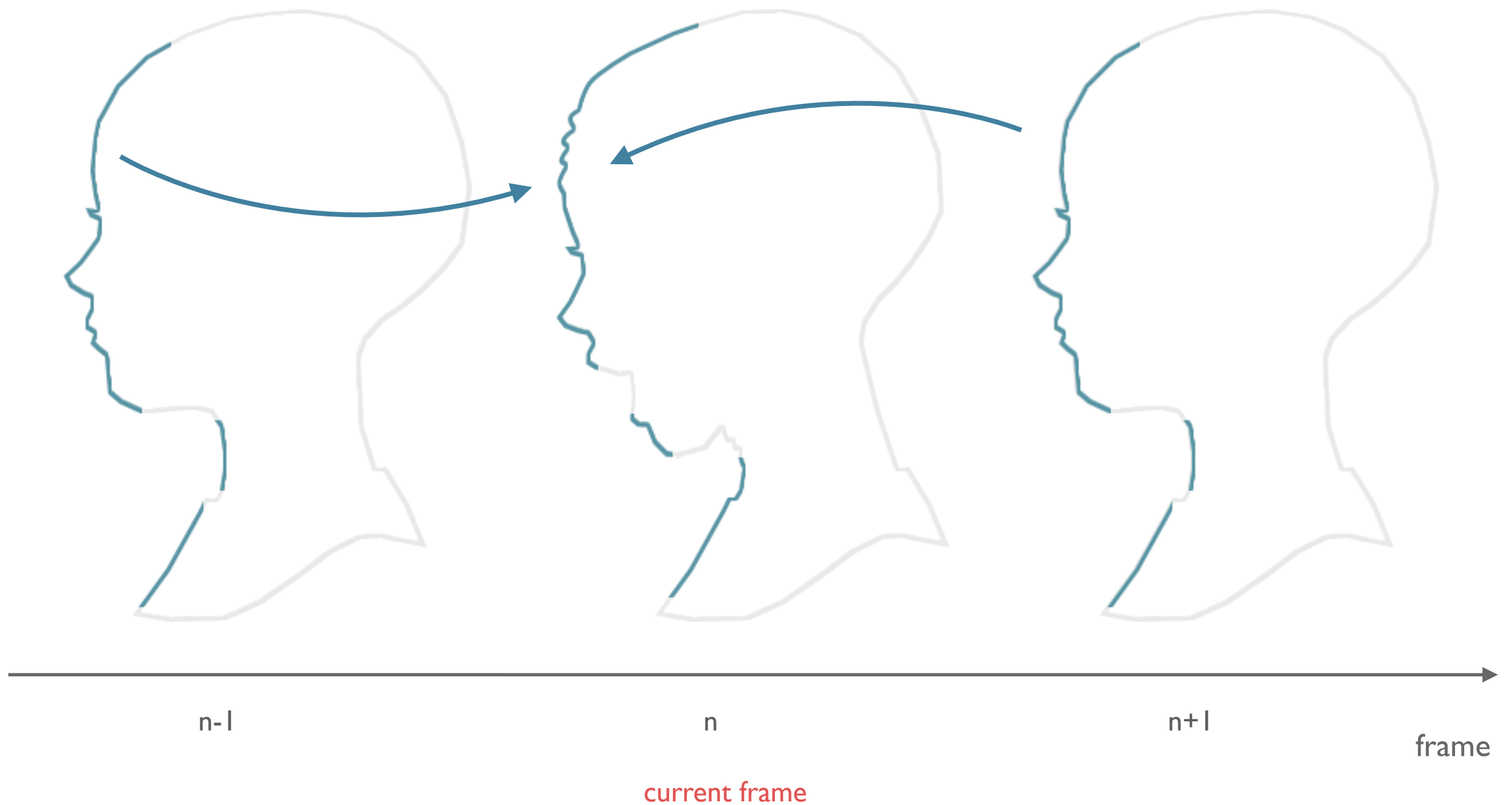
Temporal Filtering



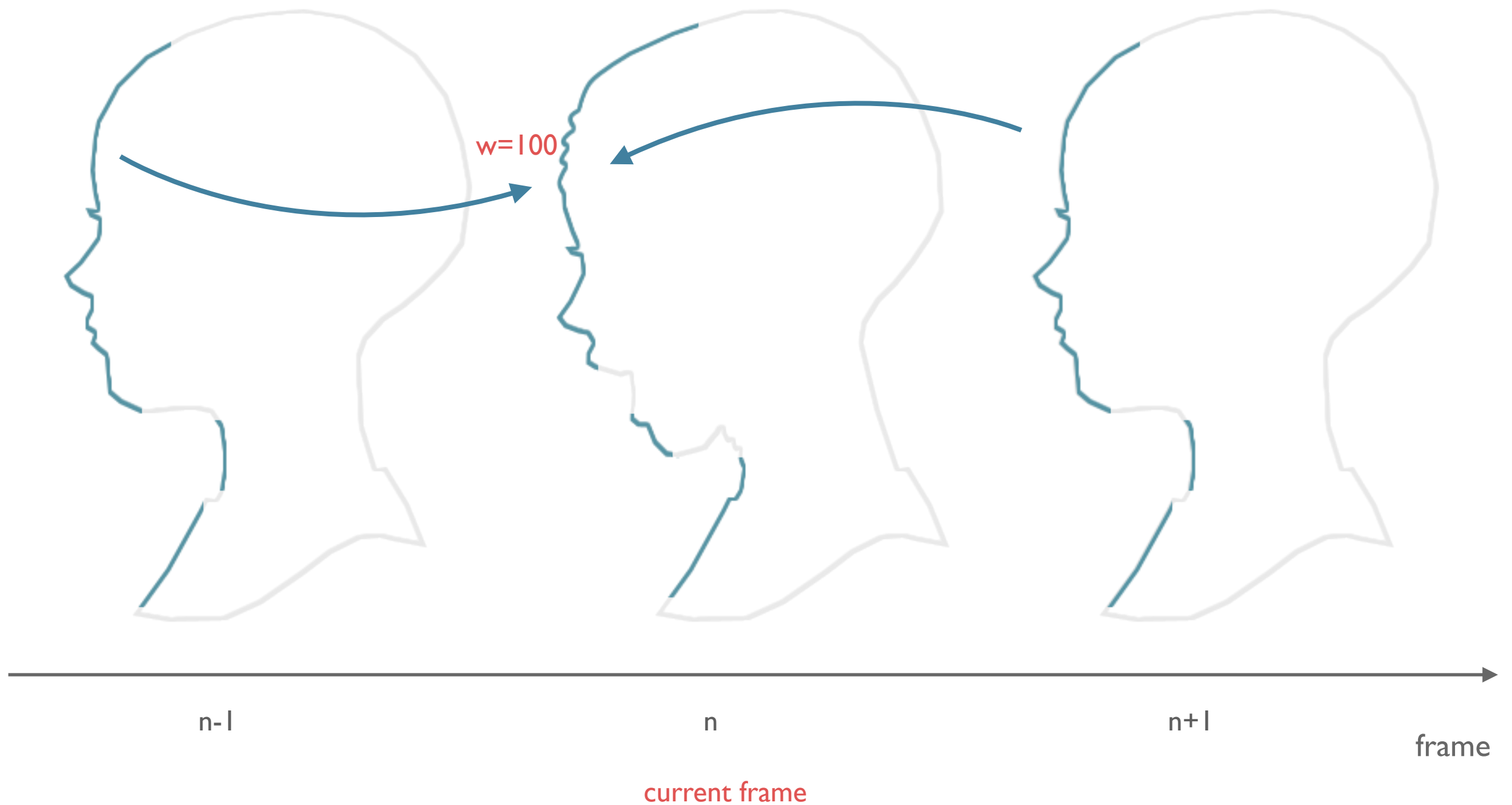
Temporal Filtering



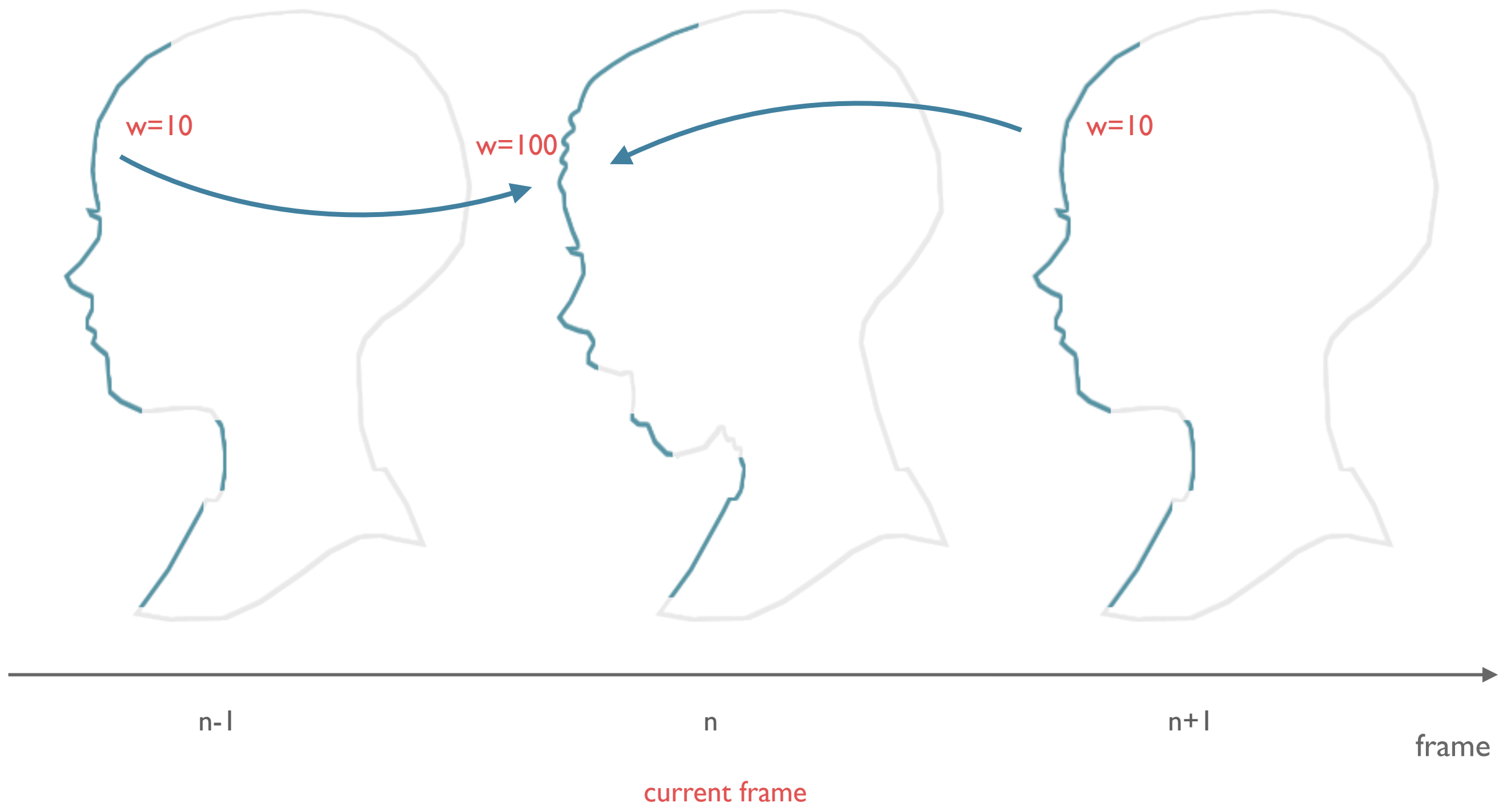
Temporal Filtering



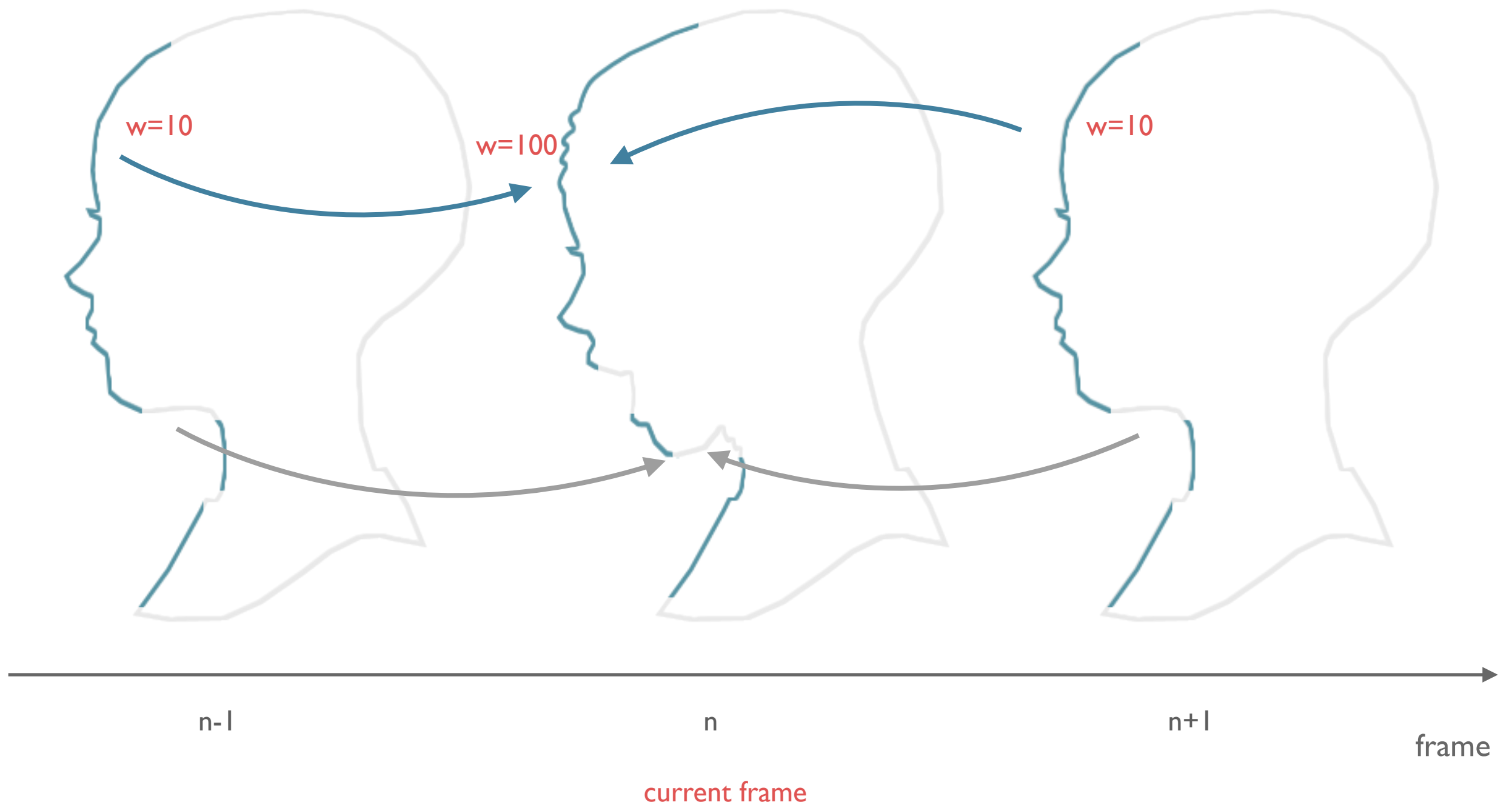
Temporal Filtering



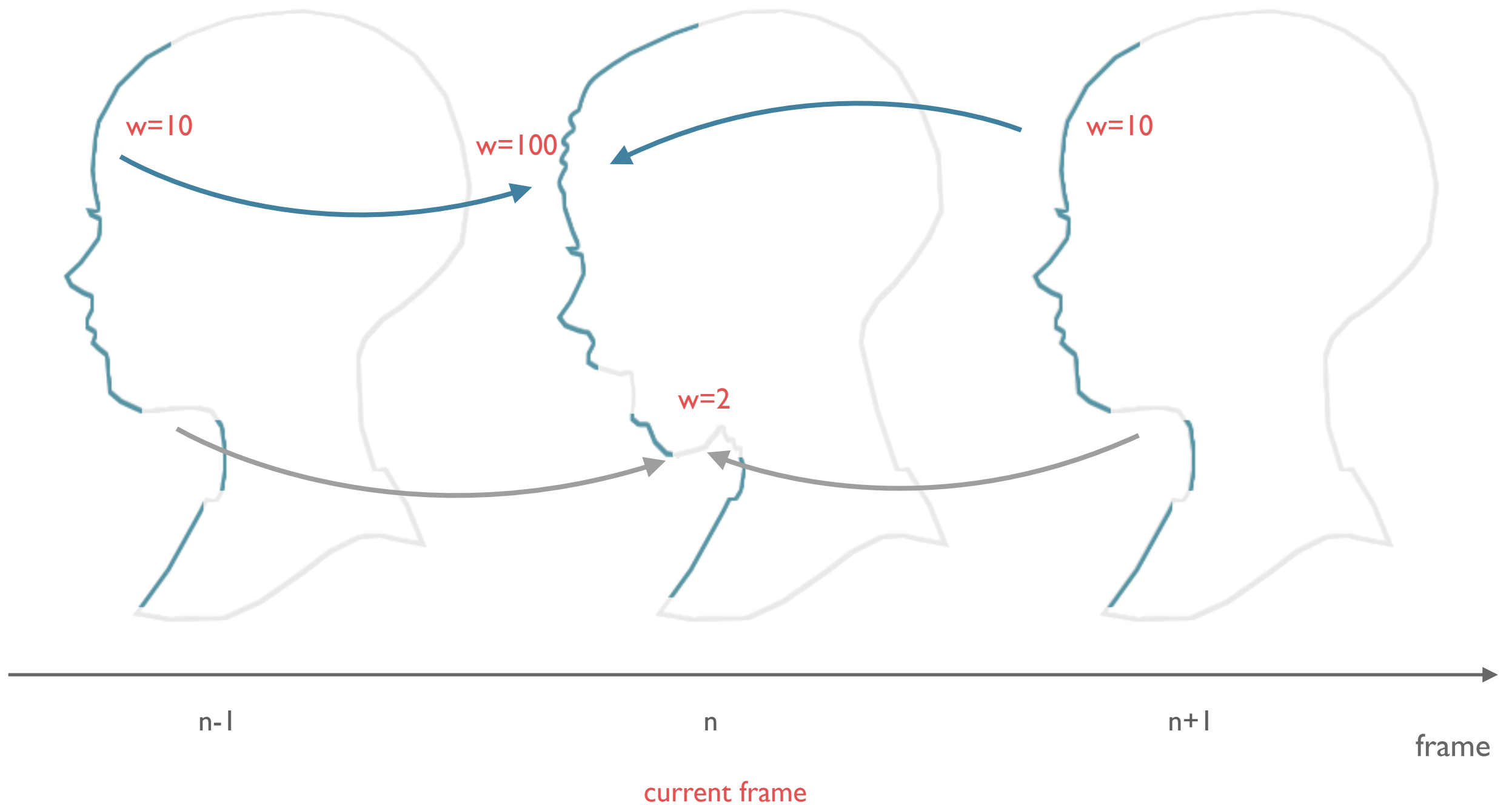
Temporal Filtering



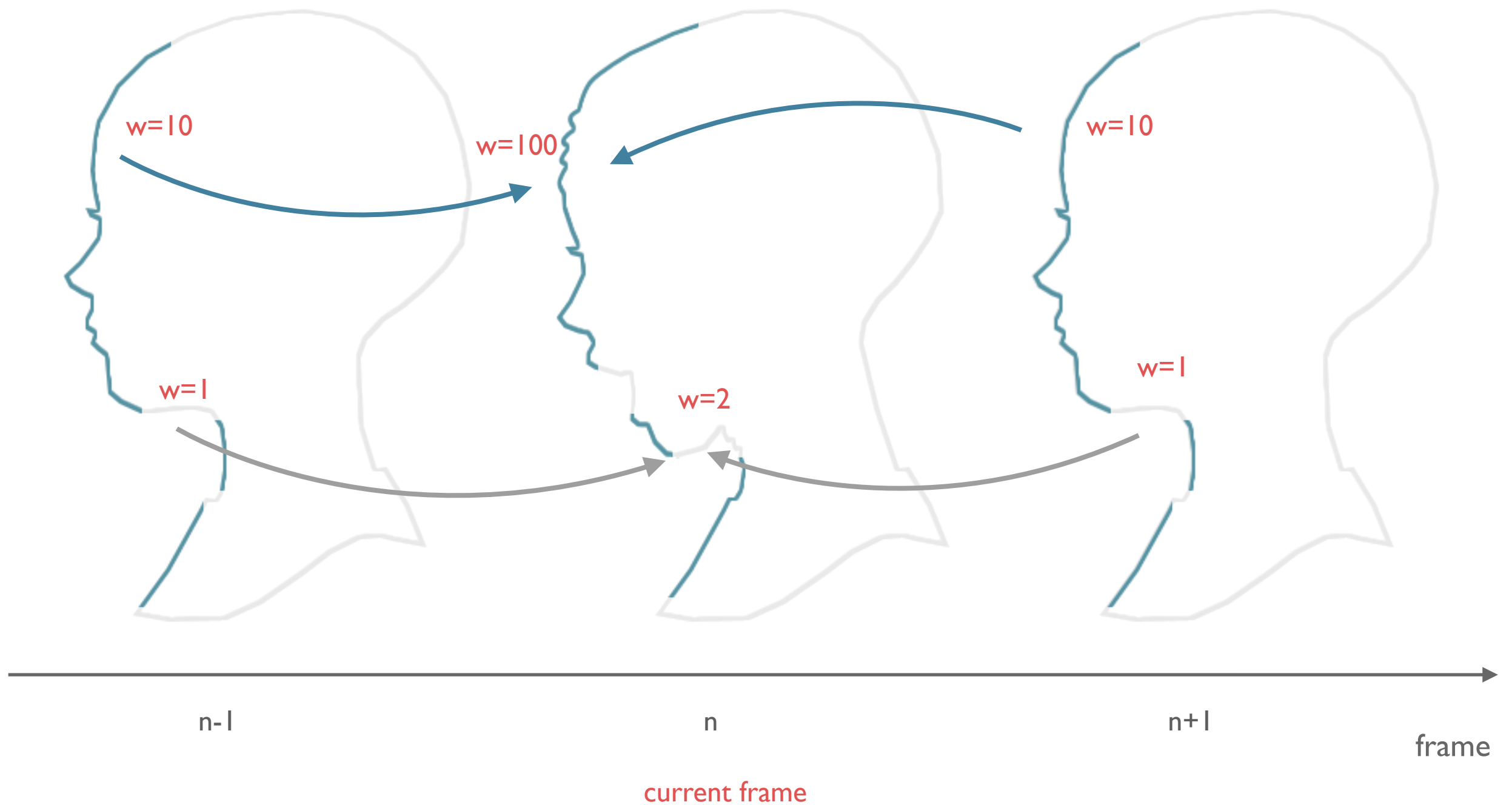
Temporal Filtering



Temporal Filtering



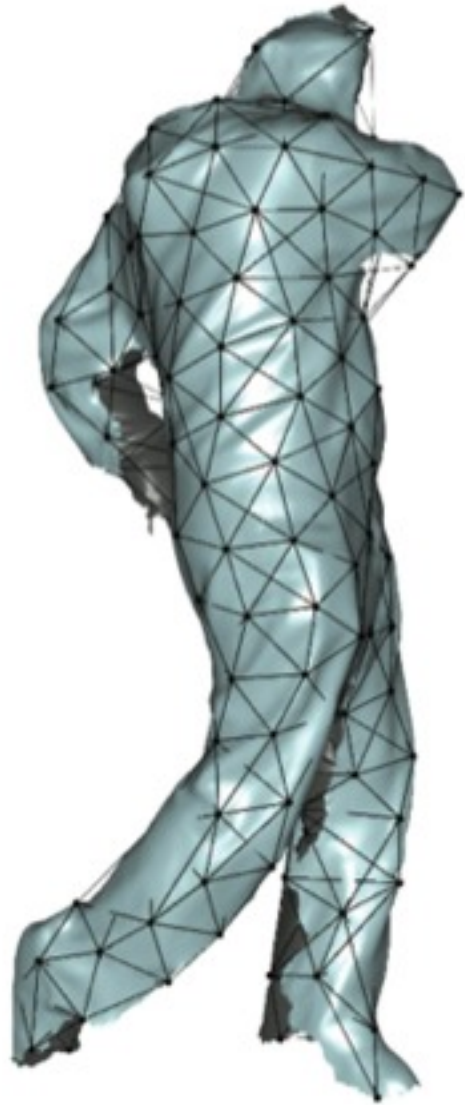
Temporal Filtering



Short Range Correspondences

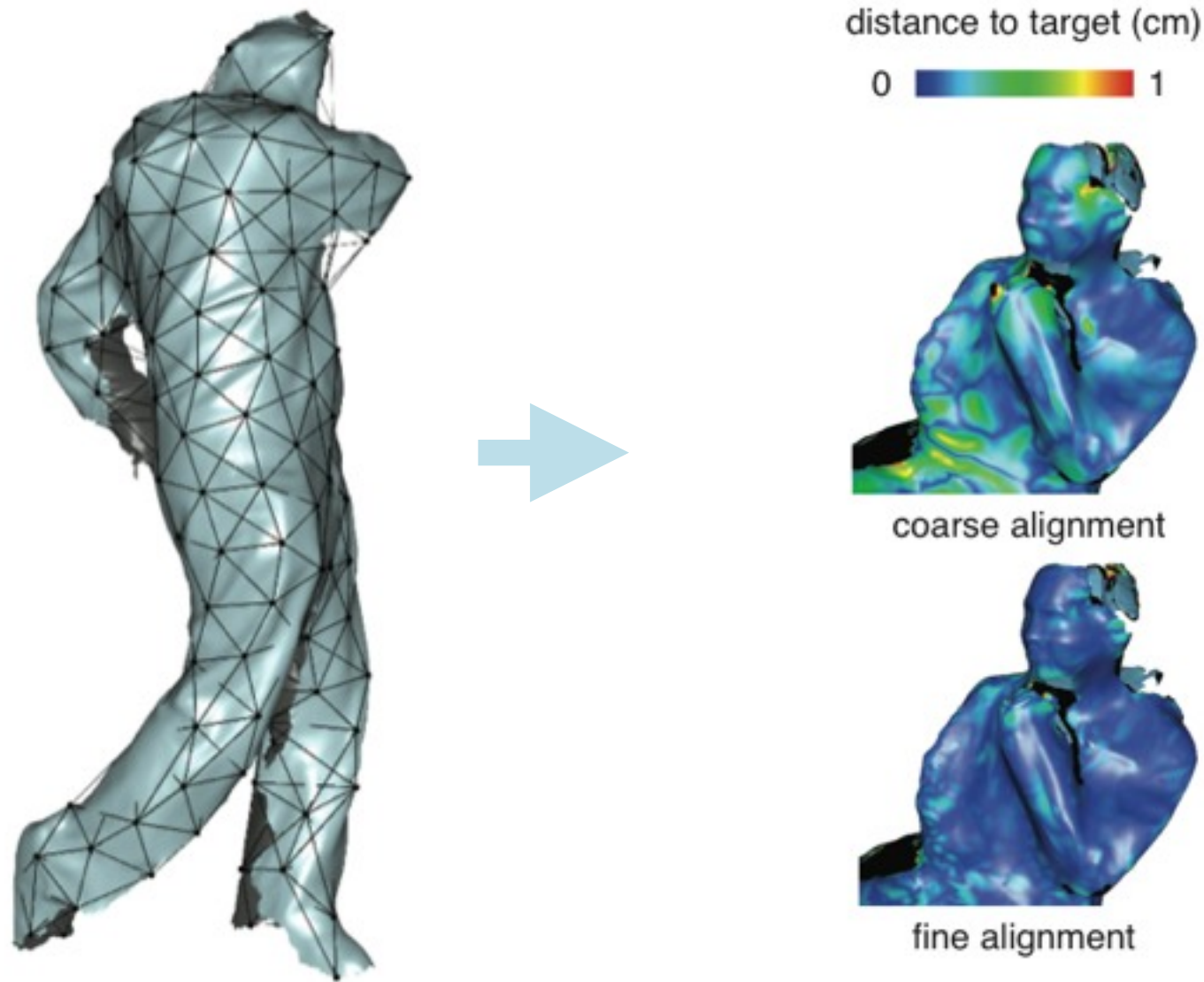


Short Range Correspondences



coarse-scale alignment
+ graph prediction
+ surf/optical flow

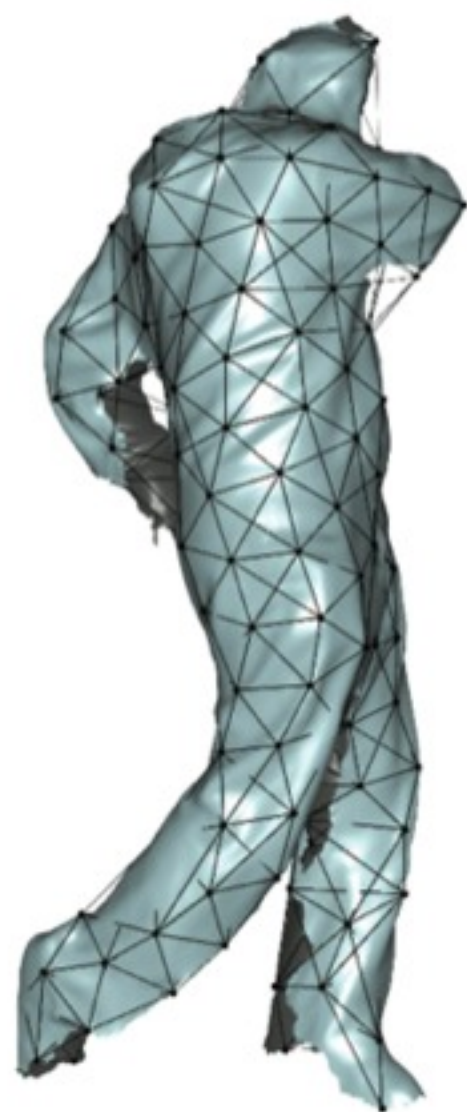
Short Range Correspondences



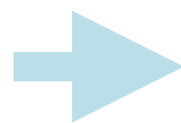
coarse-scale alignment
+ graph prediction
+ surf/optical flow

fine-scale registration

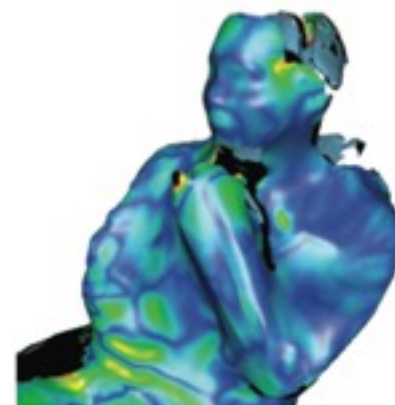
Short Range Correspondences



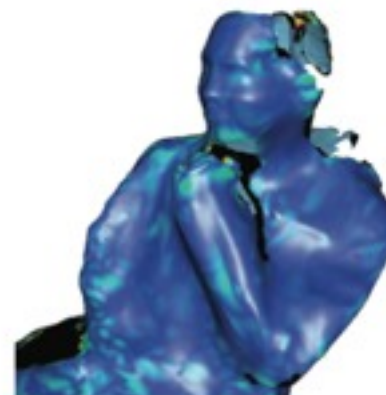
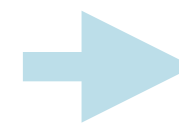
coarse-scale alignment
+ graph prediction
+ surf/optical flow



distance to target (cm)



coarse alignment

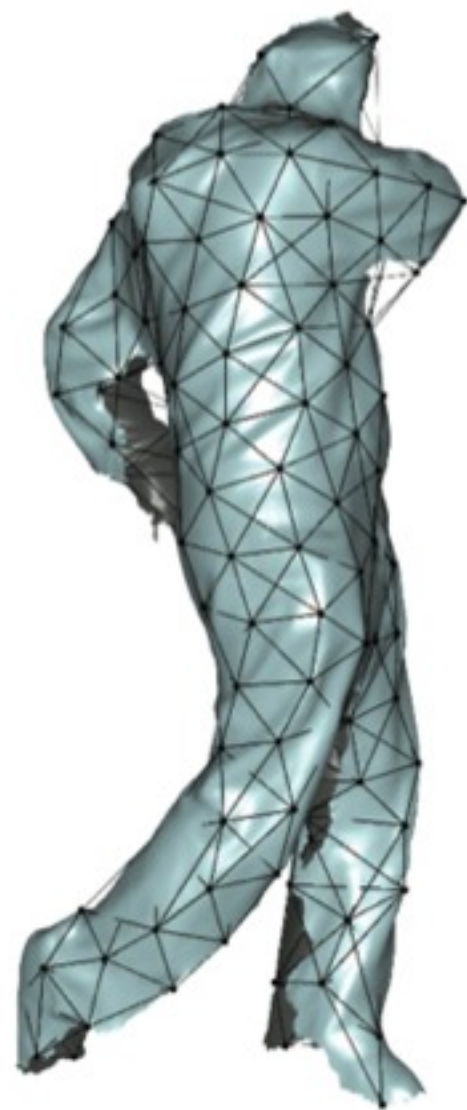


fine alignment

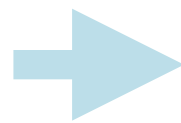
fine-scale registration



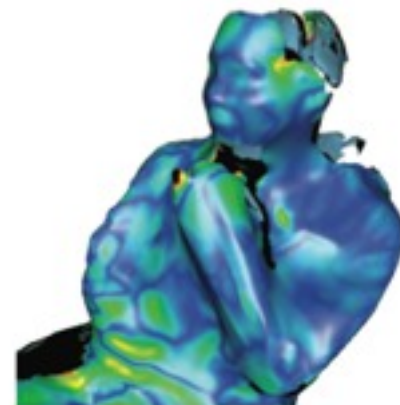
Short Range Correspondences



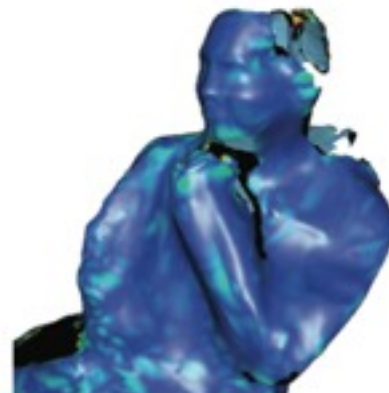
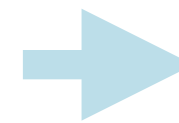
coarse-scale alignment
+ graph prediction
+ surf/optical flow



distance to target (cm)



coarse alignment



fine alignment

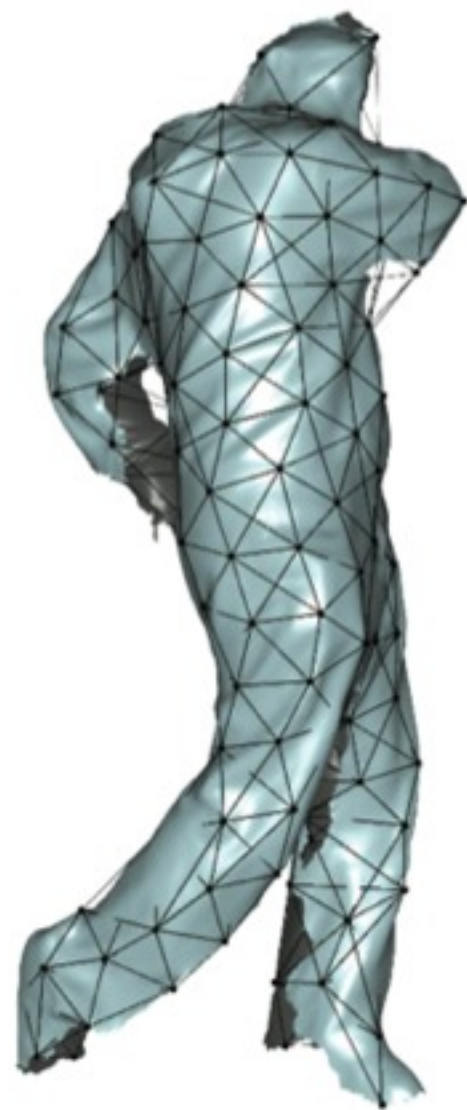
fine-scale registration

Coarse
Registration

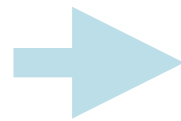



Fine
Registration

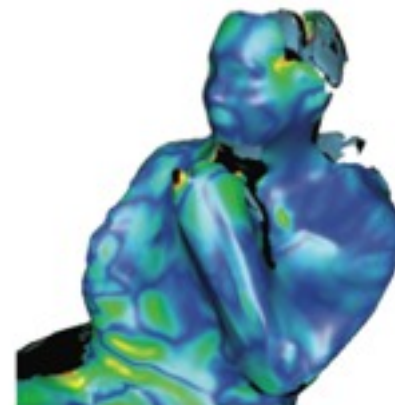
Short Range Correspondences



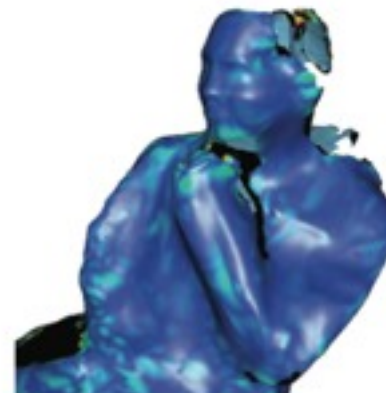
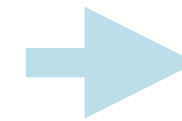
coarse-scale alignment
+ graph prediction
+ surf/optical flow



distance to target (cm)
0  1



coarse alignment

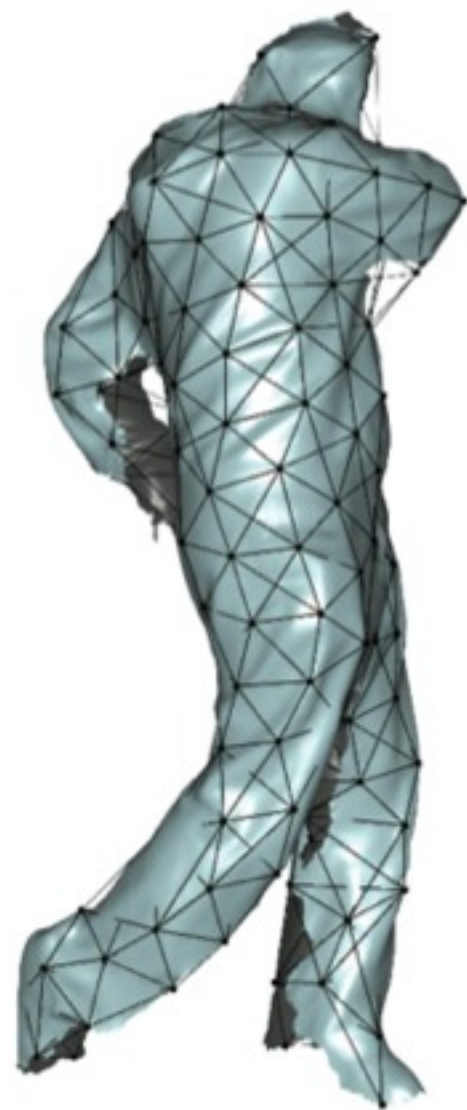


fine alignment

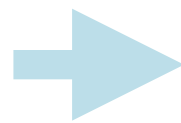
fine-scale registration



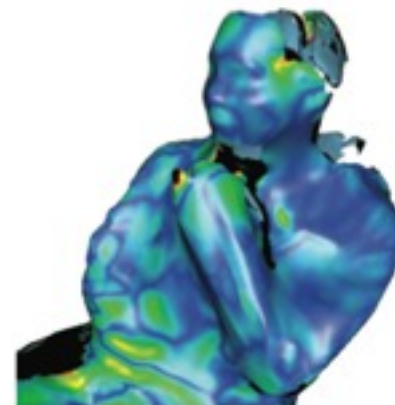
Short Range Correspondences



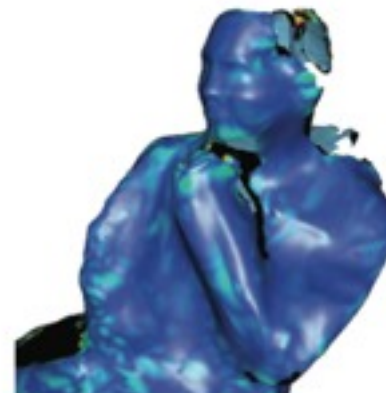
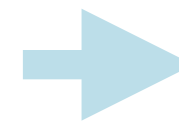
coarse-scale alignment
+ graph prediction
+ surf/optical flow



distance to target (cm)



coarse alignment



fine alignment

fine-scale registration



Free-Viewpoint Video

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Free-Viewpoint Video

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