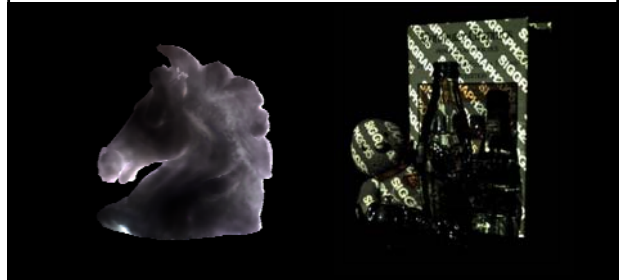


Capturing Reflectance
From Theory to Practice

Near-field Reflectance Fields

Hendrik P.A. Lensch
MPI Informatik

Digitizing Real World Objects

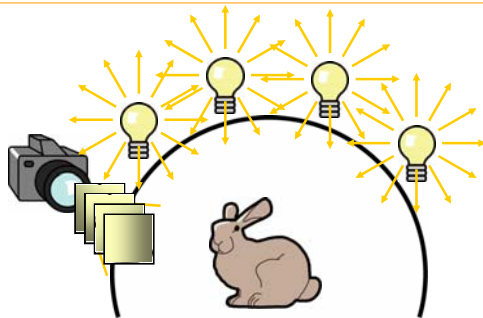


relighting with arbitrary illumination patterns

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Relighting

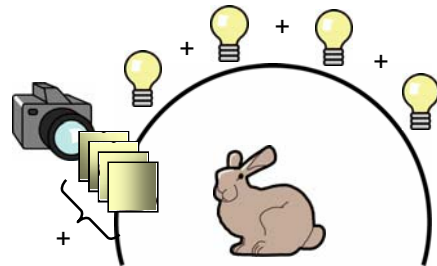


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Relighting

[Debevec2000]

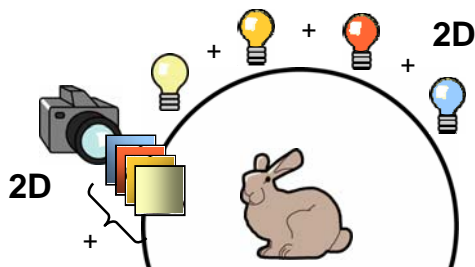


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Far-Field Reflectance Fields

[Debevec2000]



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Far- vs. Near-Field Illumination

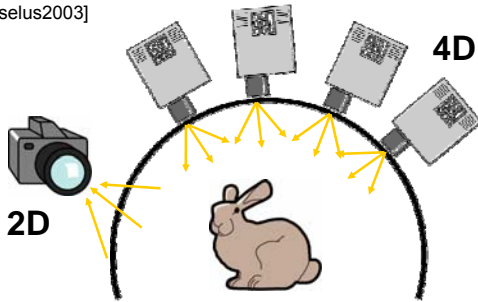


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6D Reflectance Fields

[Masselus2003]

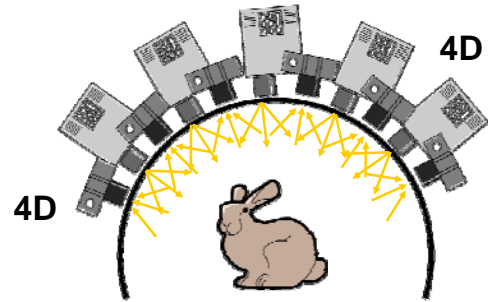


relighting with 4D incident light fields

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8D Reflectance Fields



arbitrary view point + arbitrary illumination

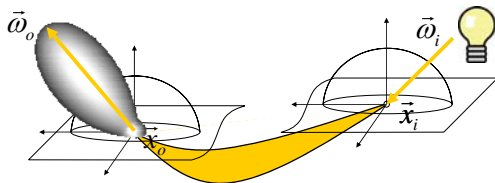
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Definition – Reflectance Field

8D function

$$f_r((\vec{x}_i, \vec{\omega}_i) \rightarrow (\vec{x}_o, \vec{\omega}_o))$$



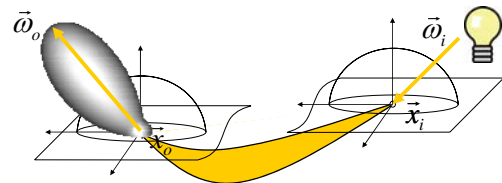
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Definition – Reflectance Field

ratio of reflected radiance to incident flux

$$f_r((\vec{x}_i, \vec{\omega}_i) \rightarrow (\vec{x}_o, \vec{\omega}_o)) = \frac{dL_o(\vec{x}_o, \vec{\omega}_o)}{d\phi_i(\vec{x}_i, \vec{\omega}_i)}$$



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Main Problem

- sampling an **8D function**
 - spending 100 samples/dimension
→ 10^{16} samples
 - hi-res 3D geometry: 10^8 vertices
- coherence in reflectance fields
→ reduced data complexity
- no complete solution yet



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Approaches

- limited reflectance model
- limited reproduction
 - viewer position
 - incident illumination
- adaptive parallel acquisition
- advanced interpolation

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Relighting with 4D Incident Light Fields

- goal: relighting with spatially varying illumination, e.g. spot lights [Masselus2003]

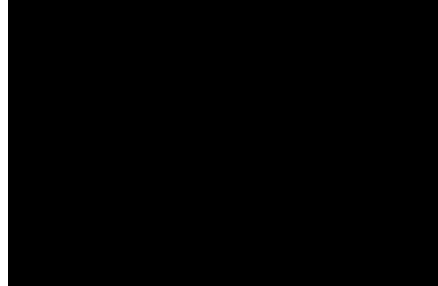


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Acquisition with Large Blocks

- fixed camera perspective
- rotating illumination



Relighting Results



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Translucent Objects



- light transport through the object
- scattering dampens high frequencies

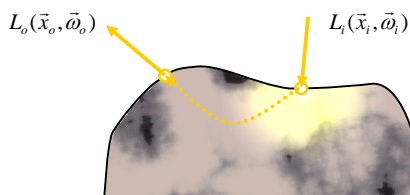
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BSSRDF – 8D

bidirectional scattering-surface reflectance distribution function [Nicolle77]

$$f_r((\vec{x}_i, \vec{\omega}_i) \rightarrow (\vec{x}_o, \vec{\omega}_o))$$



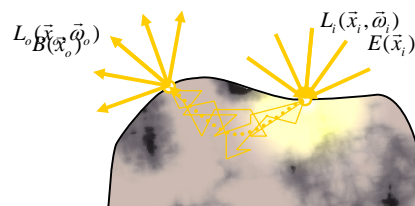
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Diffuse Approximation

neglect directional dependency [Jensen 2001]

- multiple scattering leads to diffuse light transport



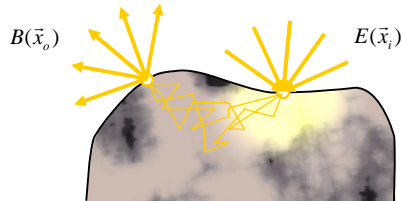
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4D - Diffuse Approximation

⇒ diffuse reflectance function $R_d(\vec{x}_i, \vec{x}_0)$

- four dimensions only
- dense sampling is possible



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Diffuse Reflectance Function R_d

- discretize the surface
 - enumerate all surface points
 - vectors for irradiance E and radiosity B
- matrix R_d

linear point-to-point transport

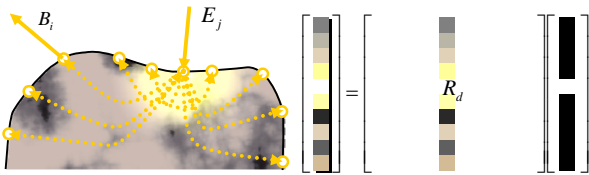
$$\begin{bmatrix} B_i \end{bmatrix} = \begin{bmatrix} R_d \end{bmatrix} \begin{bmatrix} E_j \end{bmatrix}$$

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Basic Idea

- direct measurement of R_d
 - illuminate individual surface points
 - capture impulse response function

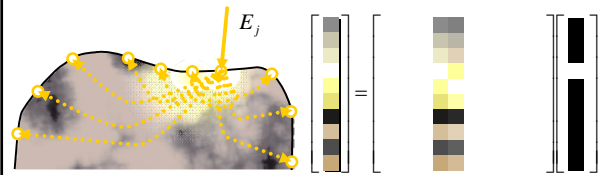


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Basic Idea

- direct measurement of R_d
 - illuminate individual surface points
 - capture impulse response function

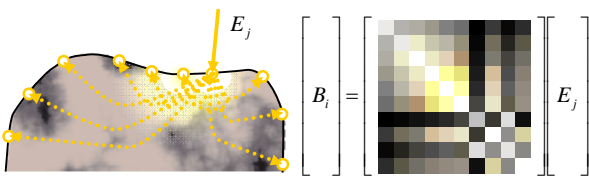


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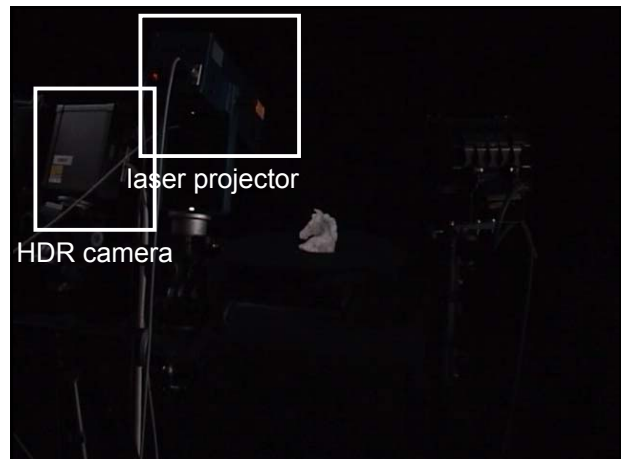
Basic Idea

- direct measurement of R_d
 - illuminate individual surface points
 - capture impulse response function



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Matrix Representation

- 500.000 – 1.000.000 input images
⇒ $\sim 100.000^2$ entries
- fill up holes (inpainting)
- hierarchical representation
- hardware assisted rendering
 - analysis
 - real-time rendering

[Lensch, Goesele, Bekaert, Magnor, Lang, Seidel – PG2003]

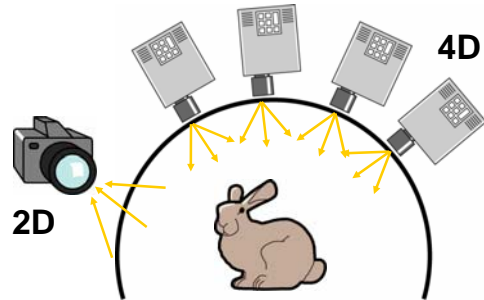
Video

1.000.000 images, 22 hours → model - 800MB



[Goesele, Lensch, Lang, Fuchs, Seidel - SIGGRAPH 2004]

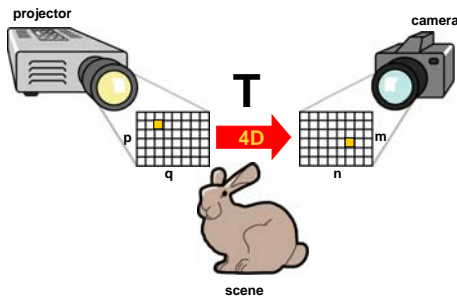
Fixed Perspective + Arbitrary Illumination



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Pixel-to-Pixel Transport

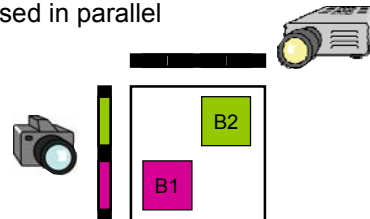


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Adaptive Parallel Acquisition

- assumption: sparse matrix
- radiometrically independent blocks can be sensed in parallel

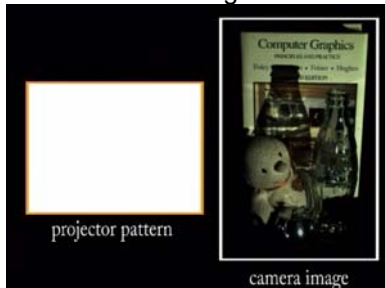


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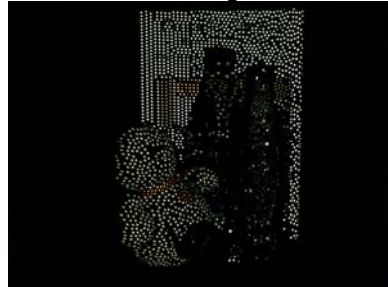
Adaptive Parallel Acquisition

parallelized acquisition of regions which do not overlap in the camera image



Adaptive Parallel Acquisition

parallelized acquisition of regions which do not overlap in the camera image



Relighting with Arbitrary Patterns

1.200 images, 2 hours → model - 220MB



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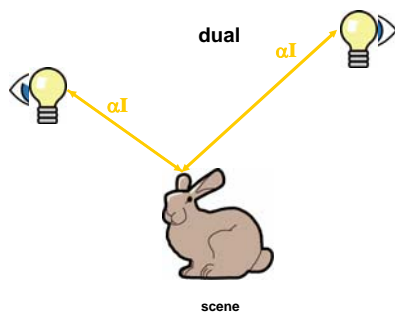
Captured Global Light Transport



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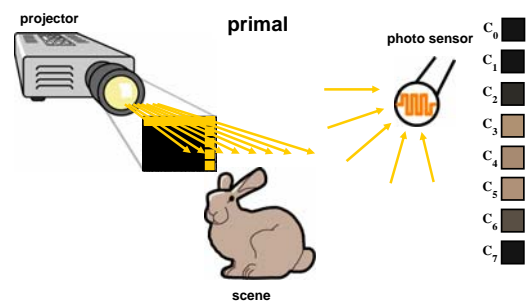
Helmholtz Reziprocität



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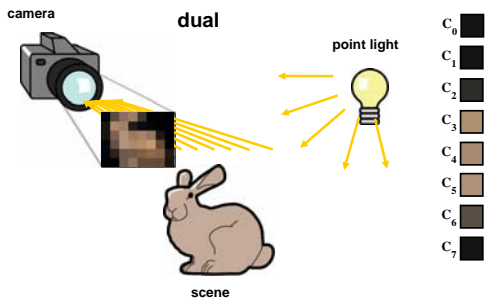
Image Acquisition without a Camera



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Image Acquisition without a Camera



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Dual Photography

photograph from camera



dual image from projector



[Sen, Chen, Garg, Marschner, Horowitz, Levoy, Lensch - SIGGRAPH 2005]

Examples



primal



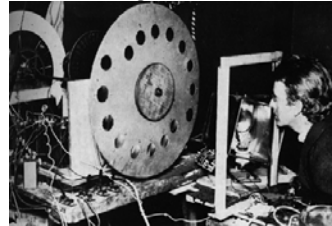
dual

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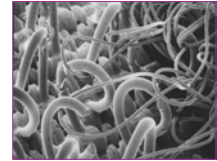
Hendrik Lensch

Related Techniques

- “Flying-spot” TV camera [Baird 1926]
- scanning electron microscope



[Baird 1926]

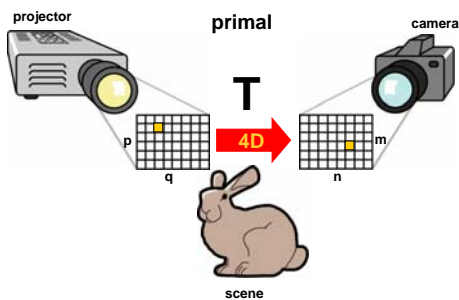


35x magnification
[museum of Science, Boston]

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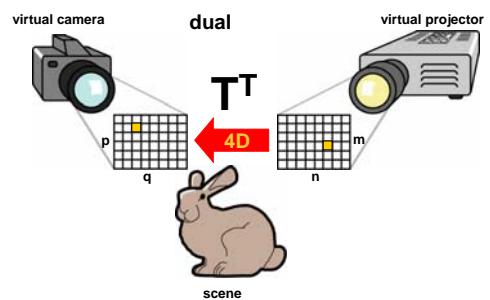
Relighting with Dual Photography



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Relighting with Dual Photography

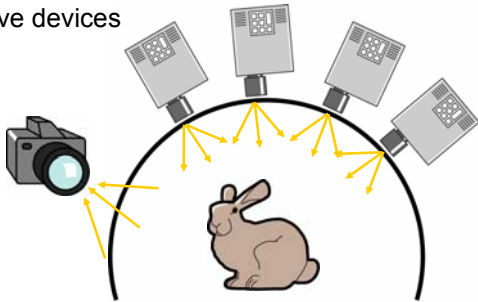


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Acquisition of 6D Reflectance Fields

active devices

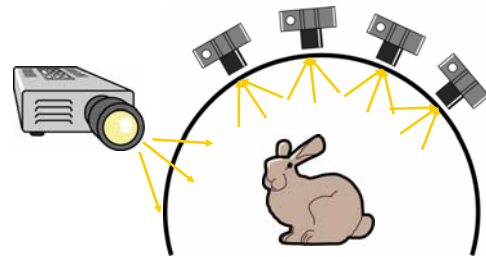


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Dual Acquisition Process

parallel acquisition by passive devices

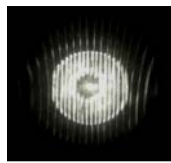


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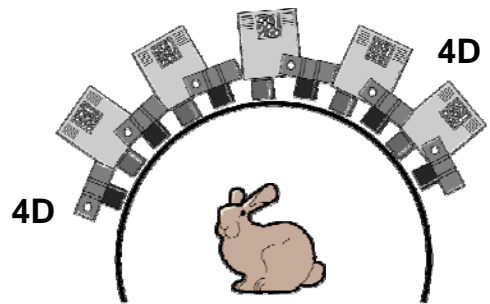
Smooth Interpolation

100.000 images, 26 hours → model - 4.5GB



[Chen, Lensch - VMV2005]

8D Reflectance Fields



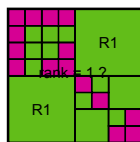
arbitrary view point + arbitrary illumination

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H -Matrices

[Hackbusch2000]



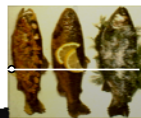
efficient representation of dense but **data-sparse** matrices

- subdivision hierarchy
- local low-rank approximation
- efficient evaluation

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Direct vs. Indirect Reflections



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Direct vs. Indirect Reflections

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Direct vs. Indirect Reflections

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2D Slices through a Reflectance Field

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Symmetric Acquisition

- symmetric 8th order tensor
- rank-1 approximation from two images only
- parallel acquisition of dense matrices

[Garg, Talvala, Levoy, Lensch – EGSR06]

Symmetric Exploration

B3 – row sums B3 – column sums
 B2 – rows+columns B1 – rows+columns

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Symmetric Exploration

B3 – row sums B3 – column sums
 B2 – rows+columns B1 – rows+columns

rank-1 approximation? $B3 \approx \begin{bmatrix} | \\ | \end{bmatrix} \cdot \begin{bmatrix} | \\ | \end{bmatrix}$

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Hierarchical Rank-1 Decomposition

$$\begin{bmatrix} B1 & R1 \\ R1 & B2 \end{bmatrix} = \begin{bmatrix} & B3 \\ B3^T & \end{bmatrix} + \begin{bmatrix} B1 & \\ & B2 \end{bmatrix} = \dots$$

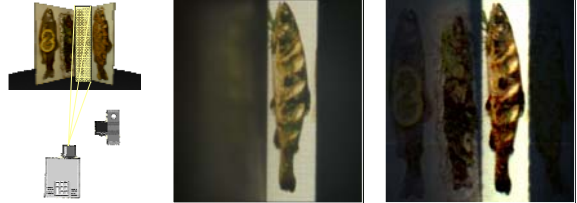
already determined
radiometrically independent

B1 and B2 are investigated in parallel.
parallel acquisition even for dense matrices

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Dual vs. Symmetric Photography



- increased SNR because regions are determined at large block sizes

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An 8D Reflectance Field

3.300 images, 6 hours → model – 1.4 GB

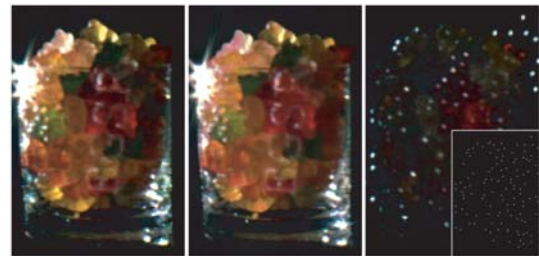


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Virtual Photography

- reflectance fields of arbitrarily complex scenes



novel illumination

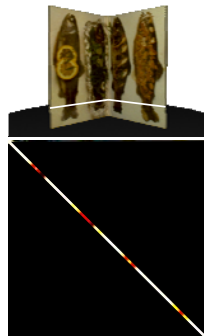
original

acquisition pattern

[Garg, Talvala, Levoy, Lensch – EGSR 2006]

Application of Near-field Reflectance Fields

- getting rid of global effects

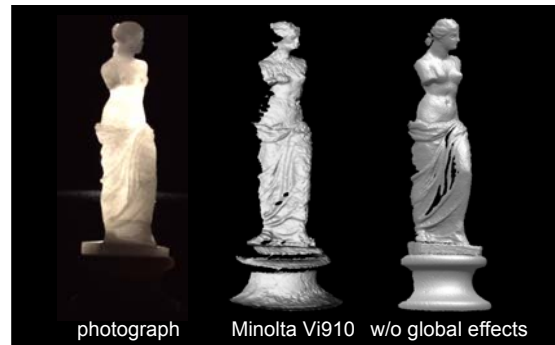


compare [Nayar2006]

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Application to 3D Scanning



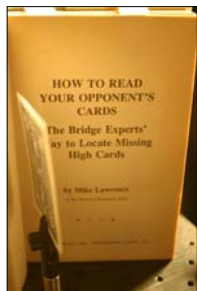
photograph

Minolta Vi910

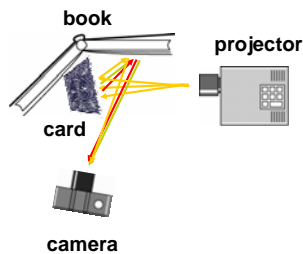
w/o global effects

[Chen, Fuchs, Lensch, Seidel – CVPR 2007]

Card Experiment



primal



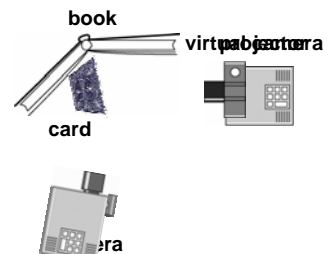
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Card Experiment



primal



virtual projector

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Card Experiment



primal



dual

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Near-Field Reflectance Fields

- Sequential Sampling
- Dual Photography
- Symmetric Photography based on \mathbf{H} -matrices
- first methods for acquiring the global light transport in arbitrary scenes

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Challenges

- densely sampled 8D reflectance fields
- upsampling / interpolation
- dynamic near-field reflectance fields
- interactive relighting
- global illumination with reflectance fields
- theory on the complexity of reflectance fields

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Thanks

- BMBF (FKC01IMC01)
- DFG – Emmy Noether Program



<http://mpi-inf.mpg.de/~lensch>

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