

## Exercise 11: Counting

### 1

In the *self-stabilising Byzantine firing squad* problem, in each round  $r \in \mathbb{N}$ , each node  $v \in V$  has an external input channel  $\text{GO}(v, r) \in \{0, 1\}$ . If  $\text{GO}(v, r) = 1$ , then we say that  $v$  receives a GO input in round  $r$ . Moreover, the algorithm determines an output  $\text{FIRE}(v, r) \in \{0, 1\}$  at each node  $v \in V_g$  in each round  $r \in \mathbb{N}$ . We say that an execution of an algorithm *stabilizes in round*  $r \in \mathbb{N}$ , if the following three properties hold:

**Agreement:**  $\text{FIRE}(v, r') = \text{FIRE}(w, r')$  for all  $v, w \in V_g$  and  $r \leq r' \in \mathbb{N}$ .

**Safety:** If  $\text{FIRE}(v, r_F) = 1$  for  $v \in V_g$  and  $r \leq r_F \in \mathbb{N}$ , then there is  $r_G < r_F$  s.t.

- a)  $\text{GO}(w, r_G) = 1$  for some  $w \in V_g$  and
- b)  $\text{FIRE}(v, r') = 0$  for all  $r' \in \{r_G + 1, \dots, r_F - 1\}$ .

**Liveness:** If  $\text{GO}(v, r_G) = 1$  for at least  $f + 1$  correct nodes  $v \in V_g$  and  $r \leq r_G \in \mathbb{N}$ , then  $\text{FIRE}(v, r_F) = 1$  for all nodes  $v \in V_g$  and some  $r_G < r_F \in \mathbb{N}$ .

Note that the liveness condition requires  $f + 1$  correct nodes to receive an external GO input, as otherwise it would be impossible to guarantee that a correct node has received a GO input when firing. We say that an execution stabilized by round  $r$  has *response time*  $R$  from round  $r$  on if

1. if  $f + 1$  correct nodes  $v \in V_g$  satisfy  $\text{GO}(v, r_G) = 1$  on some round  $r_G \geq r$ , then all correct nodes  $w \in V_g$  satisfy  $\text{FIRE}(w, r_F) = 1$  on some round  $r_G \leq r_F \leq r_G + R$ , and
2. if there is a round  $r_F \geq r$  such that  $\text{FIRE}(v, r_F) = 1$  for some correct  $v \in V_g$ , then there is a round  $r_G$  with  $r_F > r_G \geq r_F - R$  and some correct node  $w \in V_g$  with  $\text{GO}(w, r_G) = 1$ .

Finally, we say that an algorithm  $F$  is an  $f$ -resilient firing squad algorithm with stabilization time  $S(F)$  and response time  $R(F)$  if in any execution of the system with at most  $f$  faulty nodes there is a round  $r \leq S(F)$  by which the algorithm stabilized and from which on it has response time at most  $R(F)$ .

- a) Given a  $T$ -counting algorithm of stabilization time  $S$  and message size  $M_1$  alongside a consensus algorithm of running time  $T$  and message size  $M_2$ , provide a firing squad algorithm with the following properties:
  1. It stabilizes within  $\max\{S + T, 2T\}$  rounds.
  2. It has response time  $R \leq 2T$ .
  3. It has message size  $M \leq M_1 + M_2 + 1$ .
- b) Conclude that a firing squad algorithm with stabilization and response time  $\mathcal{O}(f)$  and message size  $\mathcal{O}(\log f)$  exists.
- c) Prove that any firing squad algorithm must have response time  $f + 1$ . (Hint: Reduce consensus to firing squad!)

## 2

In this exercise, you show how to obtain a silent (binary) consensus algorithm from an arbitrary consensus algorithm. As usual, we assume that  $f < n/3$ . Here's a description of the new algorithm up to determining its output:

The new protocol  $C'$  can be seen as a “wrapper” protocol that manipulates the inputs and then lets each node decide whether it participates in an instance of the original protocol. In the first round of the new protocol,  $C'$ , each participating node broadcasts its input if it is 1 and otherwise sends nothing. If a node receives fewer than  $n - f$  times the value 1, it sets its input to 0. In the second round, the same pattern is applied.

Subsequently,  $C$  is executed by all nodes that received at least  $f + 1$  messages in the first round. If during the execution of  $C$  a node

1. cannot process the messages received in a given round in accordance with  $C$  (this may happen e.g. when not all of the correct nodes participate in the instance, which is not covered by the model assumptions of  $C$ ),
2. would have to send more bits than it would have according to the known bound  $M(C)$ , or
3. would violate the running time bound of  $C$ ,

then the node (locally) aborts the execution of  $C$ .

- a) Prove that the protocol is silent.
- b) Define suitable rules for determining the output of the new protocol  $C'$  based on the first two rounds of the wrapper, whether the execution of  $C$  was aborted, and, if it wasn't, on its output. Show agreement and validity of  $C'$  with these rules.

## 3\*

- a) Contemplate your experience with the lecture.
- b) Come up with clever ideas on what we could do better next time.
- c) Join us for ice cream and spill the beans!