Voronoi Diagrams and Delaunay Triangulations

Sándor Kisfaludi-Bak

Computaional Geometry Summer semester 2020



• Voronoi diagrams – definition and properties

• Voronoi diagrams – definition and properties

• Fortune's algorithm (1987)

• Voronoi diagrams – definition and properties

• Fortune's algorithm (1987)

• Delaunay graphs and triangulations

• Voronoi diagrams – definition and properties

• Fortune's algorithm (1987)

• Delaunay graphs and triangulations

• Delaunay triangulation via divide and conquer (Guibas and Stolfi, 1985)

• Voronoi diagrams – definition and properties

• Fortune's algorithm (1987)

• Delaunay graphs and triangulations

- Delaunay triangulation via divide and conquer (Guibas and Stolfi, 1985)
- Lifting to a paraboloid; computation via convex hull Next lecture!

Motivation – nearest neighbor

Given: $P \subset \mathbb{R}^2$.

Motivation – nearest neighbor Given: $P \subset \mathbb{R}^2$. \boldsymbol{Q}

What is the nearest point in P to a given query point $q \in \mathbb{R}^2$?



What is the nearest point in P to a given query point $q \in \mathbb{R}^2$?

- Where in P should I get my ice cream if I'm at q?
- Accident at q. Which hospital in P should send helicopter?

The Voronoi diagram of $P \subset \mathbb{R}^d$ is the partition of \mathbb{R}^d according to the closest point of P.

The Voronoi diagram of $P \subset \mathbb{R}^d$ is the partition of \mathbb{R}^d according to the closest point of P.

If |P| = n, then partition into n cells s.t. cell of $p \in P$ consist of $q \in \mathbb{R}^d$ where

dist(q, p) < dist(q, p') for all $p' \in P \setminus \{p\}$

The Voronoi diagram of $P \subset \mathbb{R}^d$ is the partition of \mathbb{R}^d according to the closest point of P.

If |P| = n, then partition into n cells s.t. cell of $p \in P$ consist of $q \in \mathbb{R}^d$ where

dist(q, p) < dist(q, p') for all $p' \in P \setminus \{p\}$







The Voronoi diagram of $P \subset \mathbb{R}^d$ is the partition of \mathbb{R}^d according to the closest point of P.

If |P| = n, then partition into n cells s.t. cell of $p \in P$ consist of $q \in \mathbb{R}^d$ where

dist(q, p) < dist(q, p') for all $p' \in P \setminus \{p\}$



perpendicular bisector





The Voronoi diagram of $P \subset \mathbb{R}^d$ is the partition of \mathbb{R}^d according to the closest point of P.

If |P| = n, then partition into n cells s.t. cell of $p \in P$ consist of $q \in \mathbb{R}^d$ where

dist(q, p) < dist(q, p') for all $p' \in P \setminus \{p\}$



perpendicular bisector





The Voronoi diagram of $P \subset \mathbb{R}^d$ is the partition of \mathbb{R}^d according to the closest point of P.

If |P| = n, then partition into n cells s.t. cell of $p \in P$ consist of $q \in \mathbb{R}^d$ where

dist(q, p) < dist(q, p') for all $p' \in P \setminus \{p\}$



perpendicular bisector





bisectors, center of circumcircle

The Voronoi diagram of $P \subset \mathbb{R}^d$ is the partition of \mathbb{R}^d according to the closest point of P.

If |P| = n, then partition into n cells s.t. cell of $p \in P$ consist of $q \in \mathbb{R}^d$ where

dist(q, p) < dist(q, p') for all $p' \in P \setminus \{p\}$



perpendicular bisector





bisectors, center of circumcircle

Historical notes

Voronoi diagram = Dirichlet tessellation

Goes back to Descartes

Historical notes

Voronoi diagram = Dirichlet tessellation 1907 1850

Goes back to Descartes 1644

Complexity and properties in \mathbb{R}^2

Each Cell(p) is intersection of half-planes. Each cell is convex (bounded or unbounded) polygon.

Vor(P): collection of segments and rays on cell boundaries

If P has 3 non-collinear pts $\Rightarrow \operatorname{Vor}(P)$ is connected

Complexity and properties in \mathbb{R}^2

Each Cell(p) is intersection of half-planes. Each cell is convex (bounded or unbounded) polygon.

Vor(P): collection of segments and rays on cell boundaries

If P has 3 non-collinear pts $\Rightarrow Vor(P)$ is connected

Lemma Vor(P) has total complexity O(n).

Complexity and properties in \mathbb{R}^2

Each Cell(p) is intersection of half-planes. Each cell is convex (bounded or unbounded) polygon.

Vor(P): collection of segments and rays on cell boundaries

If P has 3 non-collinear pts $\Rightarrow Vor(P)$ is connected

Lemma Vor(P) has total complexity O(n).

Proof. There are n cells. Euler's formula $i \Rightarrow O(n)$ edges, O(n) vertices.



Circumcircles in Voronoi diagrams

 ${\cal C}(q)$: largest circle around q whose interior has no pts from ${\cal P}$

Lemma

(i) q is a vertex of Vor(P) iff C(q) has at least 3 points of P (ii) q is on edge btw. cell(p) and cell(p') iff $C(q) \cap P = \{p, p'\}$

Circumcircles in Voronoi diagrams

 ${\cal C}(q)$: largest circle around q whose interior has no pts from ${\cal P}$

Lemma

(i) q is a vertex of Vor(P) iff C(q) has at least 3 points of P (ii) q is on edge btw. cell(p) and cell(p') iff $C(q) \cap P = \{p, p'\}$



Fortune's algorithm (1987)







If q is on undiscovered edge btw. Cell(p) and Cell(p')

 $dist(p,q) = dist(p',q) \Rightarrow dist(p,q) \ge dist(q,\ell)$ $q \text{ is below the parabola with focus } p \text{ and axis } \ell$



$$\begin{split} \operatorname{dist}(p,q) &= \operatorname{dist}(p',q) \Rightarrow \operatorname{dist}(p,q) \geq \operatorname{dist}(q,\ell) \\ &\swarrow \\ q \text{ is below the parabola with focus } p \text{ and axis } \ell \end{split}$$



q is below the parabola with focus p and axis ℓ Vor(P) above waverfront is correct

• Invariant

Part of diagram above wavefront is correctly computed

- Invariant
 Part of diagram above wavefront is correctly computed
- Sweep line structure Intersection of diagram with ℓ

- Invariant Part of diagram above wavefront is correctly computed
- Sweep line structure
 Intersection of diagram with ℓ
 Wavefront (vertices and parabolas in order)

- Invariant Part of diagram above wavefront is correctly computed
- Sweep line structure
 Intersection of diagram with ℓ
 Wavefront (vertices and parabolas in order)
- Event queue: new parabola on wavefront remove arc from wavefront

- Invariant
 Part of diagram above wavefront is correctly computed
- Sweep line structure
 Intersection of diagram with ℓ
 Wavefront (vertices and parabolas in order)
- Event queue: new parabola on wavefront $\Leftrightarrow \ell$ passes through $p \in P$ remove arc from wavefront



- Invariant Part of diagram above wavefront is correctly computed
- Sweep line structure
 Intersection of diagram with ℓ
 Wavefront (vertices and parabolas in order)
- Event queue: new parabola on wavefront $\Leftrightarrow \ell$ passes through $p \in P$ remove arc from wavefront $\Leftrightarrow \ell$ touches circle pp'p''



Wavefront complexity and queue maintenance

Observation. The wavefront consists of at most 2n - 1 parabolic arcs.

Proof: n new arcs added, each splits an existing arc into at most 2 arcs
Wavefront complexity and queue maintenance

Observation. The wavefront consists of at most 2n - 1 parabolic arcs.

Proof: n new arcs added, each splits an existing arc into at most 2 arcs

Event queue: contains unswept points and some circles pp'p'' currently intersected by ℓ

iff parabolas of $p,p^\prime,p^{\prime\prime}$ are consecutive on wavefront

Wavefront complexity and queue maintenance

Observation. The wavefront consists of at most 2n - 1 parabolic arcs.

Proof: n new arcs added, each splits an existing arc into at most 2 arcs

Event queue: contains unswept points and some circles pp'p'' currently intersected by ℓ

iff parabolas of $p,p^\prime,p^{\prime\prime}$ are consecutive on wavefront

updated with each change to wavefront.

• Invariant

Part of diagram above wavefront is correctly computed EQ contains:

- unswept points

- parabola disappearance events for consecutive arc triplets of wavefront with intersecting circumcircle

• Invariant

Part of diagram above wavefront is correctly computed EQ contains:

- unswept points
- parabola disappearance events for consecutive arc triplets of wavefront with intersecting circumcircle
- Sweep line structure Wavefront as self-balancing BST on wavefront vertices, represented by focus pairs (p, p'), ordered left to right

• Invariant

Part of diagram above wavefront is correctly computed EQ contains:

- unswept points
- parabola disappearance events for consecutive arc triplets of wavefront with intersecting circumcircle
- Sweep line structure Wavefront as self-balancing BST on wavefront vertices, represented by focus pairs (p, p'), ordered left to right
- Event queue:

new parabola on wavefront (new point swept) remove existing arc from wavefront **Stored as priority queue**

Invariant

Part of diagram above wavefront is correctly computed EQ contains:

- unswept points
- parabola disappearance events for consecutive arc triplets of wavefront with intersecting circumcircle
- Sweep line structure Wavefront as self-balancing BST on wavefront vertices, represented by focus pairs (p, p'), ordered left to right
- Event queue:

new parabola on wavefront (new point swept) remove existing arc from wavefront **Stored as priority queue**

O(n) events with $O(\log n)$ time per event $\Rightarrow O(n \log n)$

Theorem The Voronoi diagram of n points in \mathbb{R}^2 can be computed in $O(n \log n)$ time and O(n) space.

Theorem The Voronoi diagram of n points in \mathbb{R}^2 can be computed in $O(n \log n)$ time and O(n) space.

 \Rightarrow NEAREST NEIGHBOR solved in O(n) space and $O(\log n)$ query time with a point location data strucutre on the Voronoi diagram.

Theorem The Voronoi diagram of n points in \mathbb{R}^2 can be computed in $O(n \log n)$ time and O(n) space.

 \Rightarrow NEAREST NEIGHBOR solved in O(n) space and $O(\log n)$ query time with a point location data strucutre on the Voronoi diagram.



Theorem The Voronoi diagram of n points in \mathbb{R}^2 can be computed in $O(n \log n)$ time and O(n) space.

 \Rightarrow NEAREST NEIGHBOR solved in O(n) space and $O(\log n)$ query time with a point location data strucutre on the Voronoi diagram.



General Voronoi diagrams

Voronoi diagram in different metrics:

- Manhattan (L_1), L_p
- Hyperbolic
- Edge weighted planar graph
- abstract (for some definition of "bisector")

General Voronoi diagrams

Voronoi diagram in different metrics:

- Manhattan (L_1) , L_p
- Hyperbolic
- Edge weighted planar graph
- abstract (for some definition of "bisector")

Other generalizations:

- of segments
- additively/multiplicatively weighted
- power diagram
- Farthest point
- Order-k

Delaunay triangulations

Triangulation of P:

subdivision of $\operatorname{conv}(P)$ into triangles (simplices) whose vertex set is P

Triangulation of P:

subdivision of $\operatorname{conv}(P)$ into triangles (simplices) whose vertex set is P

 $P \subset \mathbb{R}^2 \Rightarrow$ triangulation has total complexity O(n)

Triangulation of P:

subdivision of $\operatorname{conv}(P)$ into triangles (simplices) whose vertex set is P

 $P \subset \mathbb{R}^2 \Rightarrow$ triangulation has total complexity O(n)

"Good" triangulation?

• Terrain reconstruction: Avoid long skinny triangles

Triangulation of P:

subdivision of $\operatorname{conv}(P)$ into triangles (simplices) whose vertex set is P

 $P \subset \mathbb{R}^2 \Rightarrow$ triangulation has total complexity O(n)

"Good" triangulation? • Terrain reconstruction: Avoid long skinny triangles

Triangulation of P:

subdivision of $\operatorname{conv}(P)$ into triangles (simplices) whose vertex set is P

 $P \subset \mathbb{R}^2 \Rightarrow$ triangulation has total complexity O(n)

"Good" triangulation? • Terrain reconstruction: Avoid long skinny triangles

 Distance along triangualtion edges approximates Euclidean distance

Definition A Delaunay triangulation of P is a triangulation where the circumcircle of any triangle has no points of P in its interior.

Definition A Delaunay triangulation of P is a triangulation where the circumcircle of any triangle has no points of P in its interior.



bad triangles $\alpha + \beta > \pi$

Definition A Delaunay triangulation of P is a triangulation where the circumcircle of any triangle has no points of P in its interior.



Definition A Delaunay triangulation of P is a triangulation where the circumcircle of any triangle has no points of P in its interior.



DT is a triangulation whose angles (when ordered in increasing sequence) are lexicographically maximized.

Example



Example



The dual of Voronoi

Voronoi vertex v at circumcenter of pp'p''

circumcircle of pp'p'' has no point of P in its interior



The dual of Voronoi

Voronoi vertex v at circumcenter of pp'p''

pp'p'' is a triangle in the Delaunay triangulation



circumcircle of pp'p'' has no point of P in its interior



Example: Voronoi and Delaunay



Voronoi edges

dual (Delaunay) edges they define the Delaunay Graph

Example: Voronoi and Delaunay



Voronoi edges

dual (Delaunay) edges they define the Delaunay Graph

 ≥ 4 points on same circle \Rightarrow Vor. vertex of degree ≥ 4 \bigcirc Face F of size ≥ 4 in Delaunay graph (any triangulation of F has good triangles)



Example: Voronoi and Delaunay



Voronoi edges

dual (Delaunay) edges they define the Delaunay Graph

DG is plane graph
DT is unique and DT=DG iff no 4 points on one circle

 ≥ 4 points on same circle \Rightarrow Vor. vertex of degree ≥ 4 \bigcirc Face F of size ≥ 4 in Delaunay graph (any triangulation of F has good triangles)



Incremental Delaunay with flips





T is a Delaunay-tr. \Leftrightarrow No bad triangles \Leftrightarrow No bad edges to flip

bad triangles $\alpha + \beta > \pi$

Incremental Delaunay with flips



Simple incremental algorithm:

- add points one at a time in random order
- maintain $DT(i) = DT(p_1 \dots, p_i)$
- maintain special point location data structure on DT(i)

Incremental Delaunay with flips



Simple incremental algorithm:

- add points one at a time in random order
- maintain $DT(i) = DT(p_1 \dots, p_i)$
- maintain special point location data structure on DT(i)

Use flips to update triangulation

Flip algorithm

After adding p_i :

- 1. Find triangle $\Delta(pp'p'') \in DT(i-1)$ where $p_i \in \Delta(pp'p'')$
- 2. Connect p_i to p, p', p'' (to get triangulation)
- 3. Flip until no more bad edges, updating point location throughout

Flip algorithm

After adding p_i :

- 1. Find triangle $\Delta(pp'p'') \in DT(i-1)$ where $p_i \in \Delta(pp'p'')$
- 2. Connect p_i to p, p', p'' (to get triangulation)
- 3. Flip until no more bad edges, updating point location throughout

 \blacktriangleright Could be $\Omega(n)$ flips!

Flip algorithm

After adding p_i :

- 1. Find triangle $\Delta(pp'p'') \in DT(i-1)$ where $p_i \in \Delta(pp'p'')$
- 2. Connect p_i to p, p', p'' (to get triangulation)
- 3. Flip until no more bad edges,updating point location throughout

 \smile Could be $\Omega(n)$ flips!

Theorem The randomized incremental construction has expected running time $O(n \log n)$ and needs O(n) space in expectation.

Delaunay triangulation via divdie and conquer (Guibas and Stolfi, 1985)




Some triangles became bad...





Start with common lower tangent. O(n)





Bubble-up merge



Start with common lower tangent. O(n)



Start with common lower tangent. O(n)



Start with common lower tangent. O(n)





















Start with common lower tangent. O(n)





Start with common lower tangent. O(n)

Push a bubble through the base edge until new vertex is hit

Properties:

- 1. All bubbles are empty
- 2. edge deletions are justified (they intersect some valid edge)
- 3. gives triangulation with only valid triangles \Rightarrow gives a DT

Finding the next bubble



New vertex is DT-neighbor of v or w. (Find candidates v', w' choose best)

Finding the next bubble



New vertex is DT-neighbor of v or w. (Find candidates v', w' choose best)

 v_1, v_2, \ldots : neighbors of v in CCW order after w

Finding the next bubble



New vertex is DT-neighbor of v or w. (Find candidates v', w' choose best)

 v_1, v_2, \ldots : neighbors of v in CCW order after w

Claim There is an i such that

 $\cdots \supset slice(vv_{i-1}w) \supset slice(vv_iw) \subset slice(vv_{i+1}w) \subset \ldots$

Claim There is an i such that

 $\cdots \supset slice(vv_{i-1}w) \supset slice(vv_iw) \subset slice(vv_{i+1}w) \subset \ldots$

 $t_i :=$ other intersection of ℓ and $circle(vv_iv_{i+1})$



Claim There is an *i* such that $\cdots \supset slice(vv_{i-1}w) \supset slice(vv_iw) \subset slice(vv_{i+1}w) \subset \cdots$ $t_i := \text{other intersection of } \ell \text{ and } circle(vv_iv_{i+1})$ $\Delta(vv_{i-1}v_i), \Delta(vv_iv_{i+1}) \text{ are empty triangles in DT(left)}$ $\Rightarrow t_1, t_2, \cdots$ moves left on ℓ







Next hit in DTleft: v_i where t_i is first to the left of w

Any edge vv_i passed is not DT edge (not empty disk) \Rightarrow delete such edges

Any edge vv_i passed is not DT edge (not empty disk) \Rightarrow delete such edges

- find common tangents
- starting at bottom tangent = vw:
 - find $v_i =$ next hit on left by stepping through N(v) in CCW order, deleting passed edges
 - find $w_j =$ next hit on right by stepping through N(w) in CW order, deleting passed edges
 - check which of v_i , w_j works
 - set vw as new edge

until vw is other tangent

Any edge vv_i passed is not DT edge (not empty disk) \Rightarrow delete such edges

• find common tangents

O(n)

- starting at bottom tangent = vw:
 - find $v_i =$ next hit on left by stepping through N(v) in CCW order, deleting passed edges
 - find $w_j =$ next hit on right by stepping through N(w) in CW order, deleting passed edges
 - check which of v_i , w_j works
 - set vw as new edge

until vw is other tangent

O(1) steps per deleted edge, O(n) deleted edges

Any edge vv_i passed is not DT edge (not empty disk) \Rightarrow delete such edges

• find common tangents

O(n)

- starting at bottom tangent = vw:
 - find $v_i =$ next hit on left by stepping through N(v) in CCW order, deleting passed edges
 - find $w_j =$ next hit on right by stepping through N(w) in CW order, deleting passed edges
 - check which of v_i , w_j works
 - set vw as new edge

until vw is other tangent

O(1) steps per deleted edge, O(n) deleted edges

Bubble merge runs in O(n)