

Send your solutions in pdf format to:

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## Problem 1. (8 points)

Computing a  $\theta$ -graph in the plane reduces to finding for each point p in input set S its partner  $k_u(p)$  for some direction u. (Recall that  $k_u(p)$  is the point  $q \in S \setminus \{p\}$  with  $\angle(\vec{pq}, u) \le \phi = \theta/2$  and whose projection of onto the ray  $R_u(p)$  is closest to p.)

Give an algorithm that given S and u produces for each  $p \in S$  its partner  $k_u(p)$  provided it exists. Your algorithm should run in  $O(n \log n)$  time.

*Hint:* You may find it easier to compute the inverse of the function  $k_u(\cdot)$ .

# Problem 2. (8+1 points)

For a set S of n points in  $\mathbb{R}^d$  define X(S) to be the sum of all interpoint distances, i.e.,  $X(S) = \sum_{\{p,q\} \subset S} \delta(p,q)$ . Design an efficient algorithm for approximating X(S), i.e., given S and parameter  $\varepsilon$  the algorithm should output a number Y with  $X(S) \leq Y \leq (1 + \varepsilon)X(S)$ .

Show that you can compute the exact sum of all **squared** distances in less time.

### Problem 3. (5+1 points)

Let T be the Delaunay triangulation of some point set S in the plane. Let D be some disk and let  $T_D$  be the subgraph of T that is induced by the vertex set  $S \cap D$ . ("Induced" here means that  $T_D$  contains exactly those edges of T that have both endpoints in  $S \cap D$ .) Prove that  $T_D$  is a connected graph.

Is the same statement true if instead of the Delaunay triangulation you are dealing with the graph formed by the vertices and edges of a Voronoi diagram?

#### Problem 4. (6 points)

In a point set  $P \subseteq \mathbb{R}^2$  the nearest neighbor of  $p \in P$  is the point  $p' \in P \setminus \{p\}$  for which  $\operatorname{dist}(p, p')$  is minimized. Given P, compute the nearest neighbor for each  $p \in P$  in  $O(n \log n)$  time.

#### Problem 5. (8 points)

In the  $L_1$  metric (a.k.a. Manhattan or taxicab metric), the distance from (x, y) to (x', y') is |x - x'| + |y - y'|. Show that the  $L_1$  Voronoi diagram of a set of n points (as a subdivision of  $\mathbb{R}^2$  into polygons) has complexity O(n).

#### Problem 6. (10 points)

Given a subdivision of  $\mathbb{R}^2$  into convex shapes of total complexity n (with a doubly connected edge list), decide in O(n) time if it is the Voronoi diagram of some point set P, and if so, output P.