

# Ch 10 - Goals

- Introducing the synchronous abstraction
- Simulating the synchronous abstraction
- Approximate agreement
- Pulse synchronization with better skew

# Synchronous Abstraction

- At initialization each node may receive an input.
- Execution proceeds in rounds:
  - nodes perform local computations
  - send messages to their neighbors
  - receive the messages from their neighbors
  - optionally: report output value and terminate
- For a network  $G=(V,E)$  and a set  $F$  of faulty nodes, we denote by  $V_g$  the set of correct nodes.
- Synchronous execution of a deterministic algorithm at the correct nodes is totally determined by the input values and messages sent by the faulty nodes to correct nodes.
- A very clean abstraction.

# Our Model

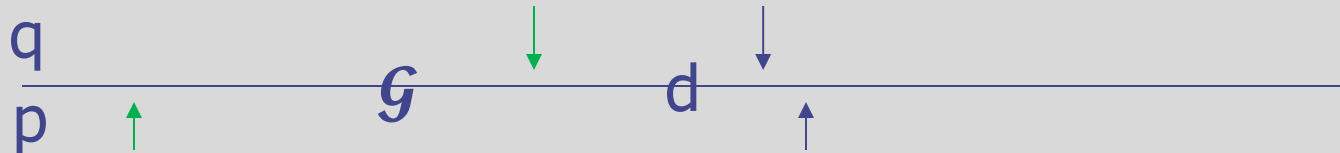
- We have logical clock algorithm that satisfies:
  - Upper bound on Logical Clock skew  $\mathcal{G}$ .
    - $\max_{v,w \in V_g} \{L_v(t) - L_w(t)\} \leq \mathcal{G}$
  - Bound on logical clock drift  $\beta$ .
    - $t - t' \leq H_v(t) - H_v(t') \leq L_v(t) - L_v(t') \leq \beta(t - t')$
  - The end-to-end message delay is  $d$ .
  - Assume that initial logical clock skew is also  $\mathcal{G}$ .
- In our model messages are being exchanged among the correct nodes and the faulty nodes inject their messages.
- The objective is to separate the message exchange into clean rounds, so each correct node will associate messages from correct nodes to separate rounds in a consistent way.

# Breakout Room

- How one can obtain a synchronous abstraction using logical clocks?

# Simulating Synchronous Abstraction

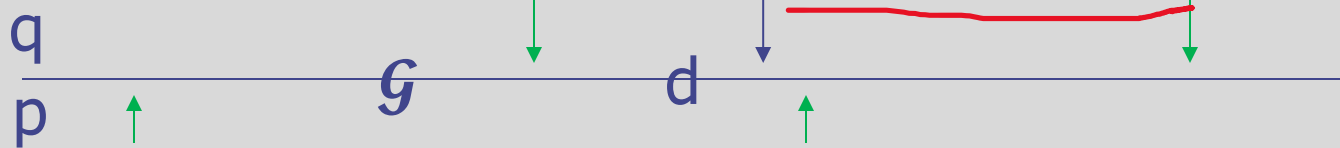
- Logical clocks satisfy:
  - Upper bound on Logical Clock skew  $\mathcal{G}$ .
  - Bound on logical clock drift  $\beta$ .
  - end-to-end message delay  $d$ .
  - Assume that initial logical clock skew is also  $\mathcal{G}$ .
- Send round  $r$  messages at time  $t$  satisfying
  - $L_v(t) = \beta \mathcal{G} + (r-1) \beta (d + \mathcal{G})$



- Observe: all messages from correct nodes of round  $r$  arrive before any correct node needs to send messages for the next round, round  $r+1$ .

# Simulating Synchronous Abstraction

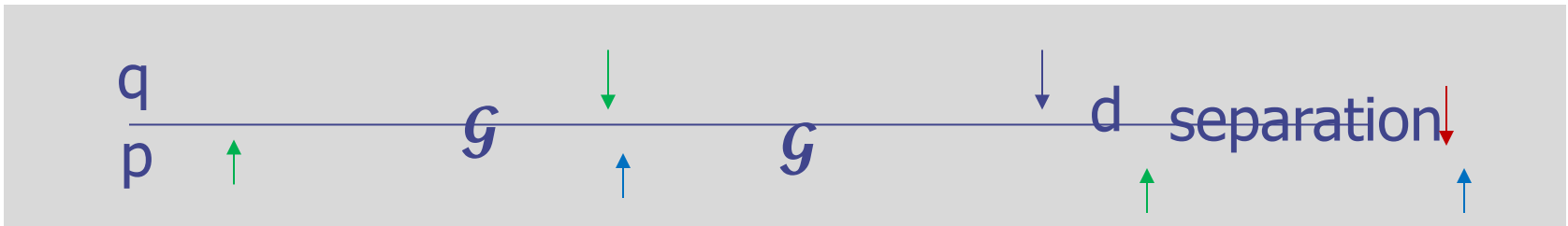
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  - Assume that initial logical clock skew is also  $\mathcal{G}$ .
- Send round  $r$  messages at time  $t$  satisfying
  - $L_v(t) = \beta \mathcal{G} + (r-1) \beta (d + \mathcal{G})$



- The **problem** is that  $q$  still collects round  $r$  messages when  $p$  sends its round  $r+1$  message.

# Simulating Synchronous Abstraction

- Begin round  $r$  messages at time  $t$  satisfying
  - $L_v(t) = \beta \mathcal{G} + (r-1) \beta (d + 2\mathcal{G})$
- send round  $r$  messages at time
  - $L_v(t) = \beta \mathcal{G} + (r-1) \beta (d + 2\mathcal{G}) + \beta \mathcal{G}$



- $p$  sends after  $q$  starts listening for the right round  $r$

# Approximate Agreement

- Each node  $v \in V_g$  is given and input  $r_v \in \mathcal{R}$ . Given  $\varepsilon > 0$ . Generate output value  $o_v \in \mathcal{R}$ , such that
  - agreement:  $\max_{v,w \in V_g} \{ |o_v - o_w| \} \leq \varepsilon$
  - validity: for each  $v \in V_g$  is  $\min_{w \in V_g} \{ r_w \} \leq o_v \leq \max_{w \in V_g} \{ r_w \}$
  - termination: each node  $v \in V_g$  outputs its value,  $o_v$ , and terminate within finite number of rounds.
- Thus, nodes need to exchange their input values and try (iteratively) to compute output values that satisfy the above requirement.
- Faulty nodes may send arbitrary values to try to prevent the convergence of output values.



# Approximate Agreement Algorithm

The algorithm proceeds in rounds.

The input to each round is the output of the previous round.

The initial input is the input of the first round.

## The Basic Iteration:

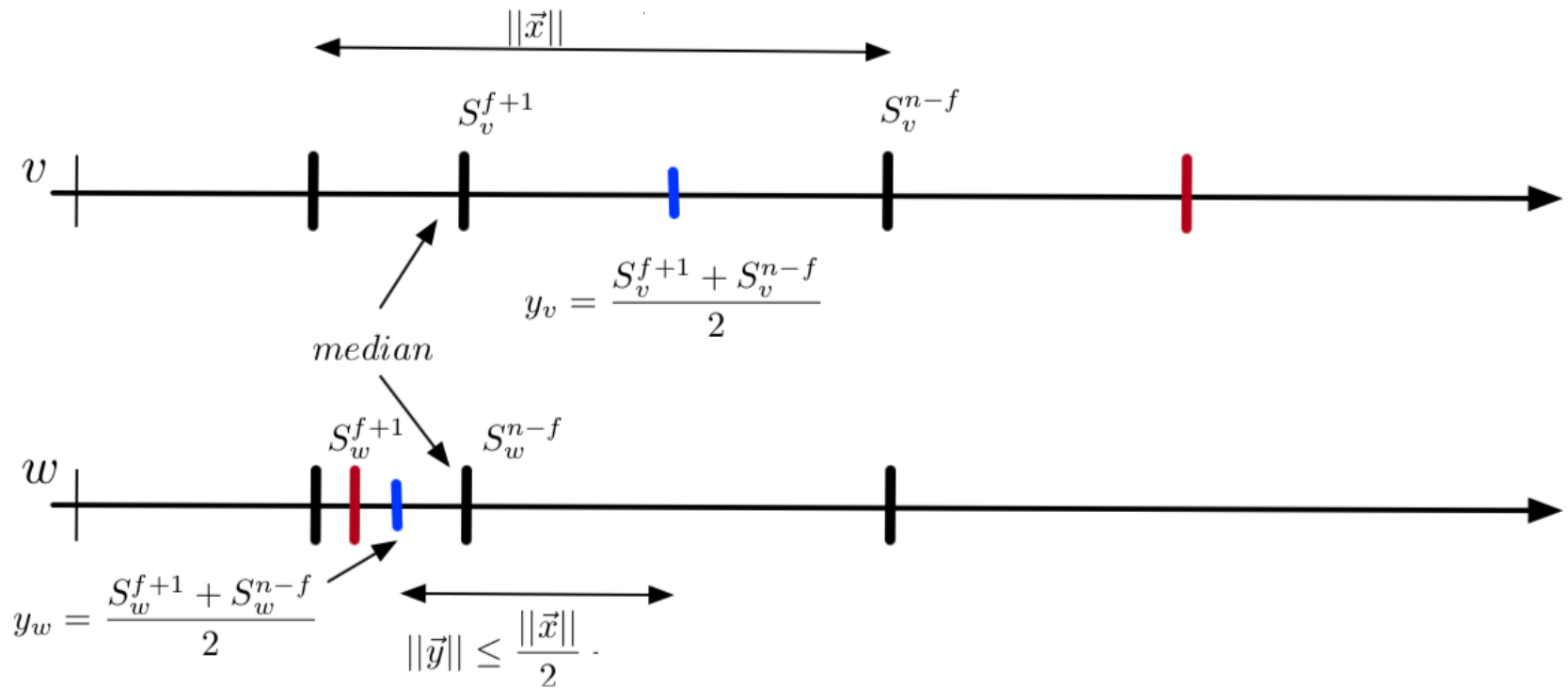
1. send  $r_v$  to all.
2. receive  $r_{w,v}$ , the value sent by  $w$  in this round.  
// replace any "missing" value by  $r_v$
3.  $S_v := \{r_{w,v}\};$  //ordered set
4.  $o_v := (S_v^{(f+1)} + S_v^{(n-f)})/2;$  // the  $(f+1)$ st and  $(n-f)$ -th values in  $S$
5. Return  $o_v$

# Notations

- We denote by  $r_{\text{gg}}$  the ascending vector of the inputs of all correct nodes. For simplicity let's assume that  $|V_{\text{g}}| = n - f$ . We assume that  $n = 3f + 1$ .
- For any ascending vector, say  $x$ ,  $x^{(i)}$  denotes the  $i$ -th entry in the vector.
- $\llbracket x \rrbracket$ , the diameter of  $x$ , is the difference between the maximal and minimal values in  $x$ .

We will show some basic properties of the algorithm and that each iteration of the algorithm reduces the diameter by half.

# 4 nodes – 1 faulty



## Lemma 10.4

For each  $v \in V_g$  is  $r_g^{(1)} \leq o_v \leq r_g^{(n-f)}$

Proof: notice that in every iteration we remove the bottom  $f$  values and there are at most  $f$  faults.

Therefore, for each  $v \in V_g$

$$S_v^{(f+1)} \geq \min_{w \in V_g} \{r_{wv}\} \geq r_g^{(1)}$$
$$S_v^{(n-f)} \leq \max_{w \in V_g} \{r_{wv}\} \leq r_g^{(n-f)}$$

The value computed in the iterations satisfies

$$r_g^{(1)} \leq S_v^{(f+1)} \leq o_v := (S_v^{(f+1)} + S_v^{(n-f)})/2 \leq S_v^{(n-f)} \leq r_g^{(n-f)}$$

# Lemma 10.5

In each iteration,  $\llbracket o \rrbracket \leq \llbracket r_g \rrbracket / 2$

Proof: since  $3f+1=n$ ,  $n-f=2f+1$ , for every  $v \in V_g$

$$r_g^{(1)} \leq S_v^{(f+1)} \leq r_g^{(f+1)} \leq S_v^{(2f+1)} \leq S_v^{(n-f)} \leq r_g^{(n-f)}$$

Therefore, by Lemma 10.4,

$$o_v - o_w = (S_v^{(2f+1)} - S_w^{(2f+1)} + S_v^{(n-f)} - S_w^{(n-f)}) / 2$$

By the above

$$o_v - o_w \leq (r_g^{(f+1)} - r_g^{(1)} + r_g^{(n-f)} - r_g^{(f+1)}) / 2$$

and we get

$$o_v - o_w \leq (r_g^{(n-f)} - r_g^{(1)}) / 2 = \llbracket r_g \rrbracket / 2$$

# Theorem 10.6

Let  $R \geq r_g^{(n-f)} - r_g^{(1)}$ . After  $\log(R/\epsilon)$  iterations the algorithm obtains the approximate agreement properties.

Proof: In each iteration,  $\|o\| \leq \|r_g\|/2$ , and for every two correct nodes,  $o_v - o_w \leq (r_g^{(n-f)} - r_g^{(1)})/2$ .

The rest is immediate.