

## Lecture 8:Testing Sparse images -Monotonicity

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# Definitions

#### Images:

- An image will be represented by a 0/1-valued  $n \times n$  matrix M.
  - Dense if it contains  $\Omega(n^2)$  1-entries/pixels.

#### Access models:

- Dense image model: (analog to dense graph model)
  - Query access to entries
- Sparse image model: (analog to sparse graph model)
  - Query access to entries
  - Sample access to 1-entries

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#### Distance:

- Dense image model:  $\delta(M, M') = \frac{d_H(M, M')}{n^2}$
- Sparse image model:  $\delta(M, M') = \frac{d_H(M, M')}{w(M)}$ where w(M) is the number of 1-pixels in M

### Example properties

- Connectivity: Graph of *M* is connected
- Line imprint: ∃ a line segment such that M(i, j) = 1 iff the line intersects the pixel.
- Convexity: Similar for a convex shape
- Monotonicity:  $\forall$   $(i_1, j_1)$  and  $(i_2, j_2)$  1-pixels it holds:  $i_1 < i_2 \Rightarrow j_1 \le j_2$ .





### Assumptions and warmup

- The algorithm is given an estimate of w(M)
  - Can be obtained using  $\tilde{O}(\min\{\sqrt{w(M)}, \frac{n^2}{w(M)}\})$  queries.

#### Theorem (sampling only tester)

There exists a sampling-only property tester for monotonicity the requires an estimate  $\hat{w} = \Theta(w(M))$  and has sample complexity and running time  $O(\sqrt{w(M)/\epsilon})$ 

The algorithm is the following:

- 1. Take  $\Theta(\sqrt{\hat{w}/\epsilon})$  samples of 1-pixels u.a.r
- 2. If some pair violates monotonicity **REJECT**, otherwise **ACCEPT Proof**:



### Assumptions and warmup

Theorem (sampling lower bound)

There exists NO sampling-only property tester for monotonicity using  $o(\sqrt{w(M)})$  samples and no queries.





# Improved algorithm using gueries

#### Algorithm with gueries:

- (1) Take a sample  $S_1$  of  $t_1 = \Theta(g_1 \log n/\epsilon^2)$  1-pixels. If  $S_1$  contains a violating pair, then REJECT; otherwise, continue.
- (2) Take a sample  $S_2$  of  $t_2 = \Theta(1/\epsilon)$  1-pixels. If there is a violating pair in  $S_1 \cup S_2$ , then REJECT. Otherwise, for each of the 1-pixels (a, b) in  $S_2$  perform the following subtest: -For  $\ell = 1$  to  $g_2$ , where  $\ell$  increases by a multiplicative factor of 2 in each iteration, uniformly select  $t_3(\ell) = \Theta(\ell \cdot (n/w(M)) \cdot \log(n)/\epsilon^2)$  entries in the submatrix of dimensions  $\ell \times \ell$  that (a, b) is the bottom-right corner of, and similarly for the  $\ell \times \ell$  submatrix that (a, b) is the top-left corner of, and perform queries on all these pixels. If any is answered by '1', then REJECT.
- (3) If no step caused rejection, then accept.

#### **Remarks:**

- We try to decompose into a set of submatrices with the properties:
  - Captures most 1-pixels in M
  - No cross-violations
- Structural result: Either we detect a violation or the above holds

 Latter case: Use gueries to detect violations within submatrices. lanck institut

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### Improved algorithm using queries

We will show the following theorem for the above algorithm:

#### Theorem (sampling and query tester)

There exists an one-sided error property tester for monotonicity the requires an estimate  $\hat{w} = \Theta(w(M))$  and has sample and query complexity as well as its running time is  $\tilde{O}\left(\frac{n^{2/3}}{w(M)^{1/3}\epsilon^2}\right)$ 



## Improved algorithm using queries

- Let S be a subset of 1-pixels obeying monotonicity.
- The picture below shows the corresponding set of submatrices *M*(*S*).





### Improved algorithm using queries

Lemma With high constant probability over the choice of the sample  $S_1^1$ , either  $S_1^1$  contains a violating pair or there exists a subset of  $S_1^1$  of size at most  $6g_1 (= 6n^{2/3}/w(M)^{1/3})$ , denoted  $\tilde{S}_1^1$  such that at most an  $(\epsilon/16)$ -fraction of the 1-pixels in M belong to heavy submatrices in  $\mathcal{M}(\tilde{S}_1^1)$ .

Proof:

