

Scalable Multitask Representation Learning for Scene Classification

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Contributions

• state of the art on SUN397 benchmark^[1]

- **49.5%** (SIFT & LCS ⇒ Fisher Vector ⇒ MTL)
- consistent improvement over standard one-vs-all single task learning (STL)
- w/ and w/o color cues
- **5..50** training examples per class
- top-*K* accuracy for **all** *K*
- scalability to Fisher Vector features
 - 260 000 dimensions, dense

Scene Classification

- previous state of the art^[2] (47.2%)
- Fisher Vector on SIFT & LCS (color feature)
- independent one-vs-all SVMs
- SUN397 challenges
 - groups of related (ambiguous) classes
 - ≤50 training examples per class combined with high dimensional FV features \Rightarrow overfitting

specialization

• existing relations between classes could be exploited



industrial area



- discrimination between visually similar classes is hard (also for humans)
- forcing a one-vs-all classifier to separate 'nuclear power plants' from 'power plants' may lead to increased overfitting
- instead, our method separates classes in a lower dimensional subspace, which is learned jointly for all scene categories



nuclear power plan

Multitask Representation Learning — MTL-SDCA

• effective regularization (lower dimensional subspace)

$$\min_{U} \frac{1}{T} \sum_{t=1}^{T} \left[\min_{w_t} \frac{1}{n} \sum_{i=1}^{n} \max\left\{0, 1 - y_{ti} \langle w_t, Ux_i \rangle\right\} + \frac{\lambda}{2} \|w_t\|^2 \right] + \frac{\mu}{2} \|U\|_F^2$$

multitask learning

Algorithm

1. start with an image representation x_i (e.g., Fisher Vector, but could be any)

2. train one-vs-all SVMs on x_i (first layer, initialization for MTL)

standard approach up to this point

- 3. stack learned predictors into U_0
- 4. iterate (multitask learning)
- train SVMs on Ux_i
- update U

← crucial step

prediction cost is effectively the same as STL since additional product is low dim.

5. final prediction:

• $\arg\max\langle w_t^{\star}, U^{\star}x\rangle$ t = 1, ..., T

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• joint learning of mapping U (multitask learning - MTL)

one-vs-all SVM

Implementation Details (code on GitHub!)

- adapt SDCA solver^[3] (Stochastic Dual Coordinate Ascent)
- no primal variables, all in dual
- learning U via SDCA-variant
- both subproblems via SDCA (hence MTL-SDCA)
- use precomputed kernels (dual optimization: $n=20K \ll d=260K$)
- closed-form updates, also for U

$$\alpha_{ti}^{(s)} = \begin{cases} \max\left(0, \min\left(C, \alpha_{ti}^{(s-1)} + h\right)\right) & \text{if } y_{ti} = +1, \\ \max\left(-C, \min\left(0, \alpha_{ti}^{(s-1)} - h\right)\right) & \text{if } y_{ti} = -1, \end{cases}$$
$$h = \frac{1 - y_{ti} K_i^{\top} A M_t}{K_{ii} M_{tt}}, \ C = \frac{1}{\mu n T}, \ K = X^{\top} X, \ M = U_0^{\top} U_0$$

Runtime Comparison

	MTL	STL	Overhead
SDCA training	25min	2min	x11
+kernels + U_0	33min	8min	x4
+image representation	6.7h	6.2h	x1.07

*further details can be found in the supplementary material

Experiments



sanity check on

MNIST/USPS

(improvement over STL,

on par w/ another MTL)

• evaluation on SUN397

- FV fine-tuning +1.2%
- top-*K* accuracy (top-5/15: +3.7%/+5%)



Left: SUN397 state of the art. Middle: STL vs MTL, SIFT only (top-K accuracy). Right: STL vs MTL, SIFT and color.

References

[1] J. Xiao, J. Havs, K. A. Ehinger, A. Oliva, and A. Torralba. SUN database: Large-scale scene recognition from Abbey to Zoo. CVPR'10. [2] J. Sanchez, F. Perronnin, T. Mensink, and J. Verbeek. Image classification with the Fisher vector: theory and practice. IJCV'13. [3] S. Shalev-Shwartz and T. Zhang. Stochastic dual coordinate ascent methods for regularized loss minimization. JMLR'13.

https://github.com/mlapin/cvpr14mtl

Conclusion

• effective MTL regularization consistently improves over STL • achieves state of the art results • scales to dense high dimensional image representation (Fisher Vector)





