

The simple LIA branch and bound calculus is very similar to DPLL, Section 2.8. A LIABB problem state is a pair $(M; N)$ where M a sequence of partly annotated simple bounds $x_i \leq d$, $d \in \mathbb{Z}$, and N is a set of inequations, $\text{vars}(N) = \{x_1, \dots, x_n\}$. Let a be the maximal absolute value of a coefficient in N , $c = n(|N|a)^{2|N|+1}$, then the following LIABB states can be distinguished:

- $(B; N)$ is the start state for N , where $B = -c \leq x_1, x_1 \leq c, \dots, -c \leq x_n, x_n \leq c$.
- $(M; N)$ is a final state, if there is a unique β , $\text{LIA}(\beta) \models M \wedge N$
- $(M; N)$ is a final state, if there is no β , $\text{LIA}(\beta) \not\models N$

Propagate $(M; N) \Rightarrow_{\text{LIABB}} (M, x \circ d; N)$

provided there is a valuation β , $\text{LRA}(\beta) \models M \wedge N$,
 $\text{LIA} \models \forall x_1, \dots, x_n. [(M \wedge N) \rightarrow x \circ d]$, $d \in \mathbb{Z}$, and $x \circ d$ is
 undefined in M

Decide $(M; N) \Rightarrow_{\text{LIABB}} (M, x \circ e^d; N)$

provided $x \circ e$ is undefined in M , $\text{LRA}(\beta) \models M \wedge N$, $\beta(x) = d$ and
 either $(\circ = \leq$ and $e = \lfloor d \rfloor)$ or $(\circ = \geq$ and $e = \lceil d \rceil)$

Backtrack $(M_1, x \circ_1 e_1^d, M_2; N) \Rightarrow_{\text{LIABB}} (M_1, x \circ_2 e_2; N)$

provided there is no valuation β ,
 $\text{LRA}(\beta) \models (M_1 \wedge x \circ_1 e_1 \wedge M_2 \wedge N)$ and there is no $y \circ' e'^{d'}$ in M_2
 and if $\circ_1 = \leq$, then $\circ_2 = \geq$ and $e_2 = \lceil d \rceil$; if $\circ_1 = \geq$, then $\circ_2 = \leq$ and
 $e_2 = \lfloor d \rfloor$

